

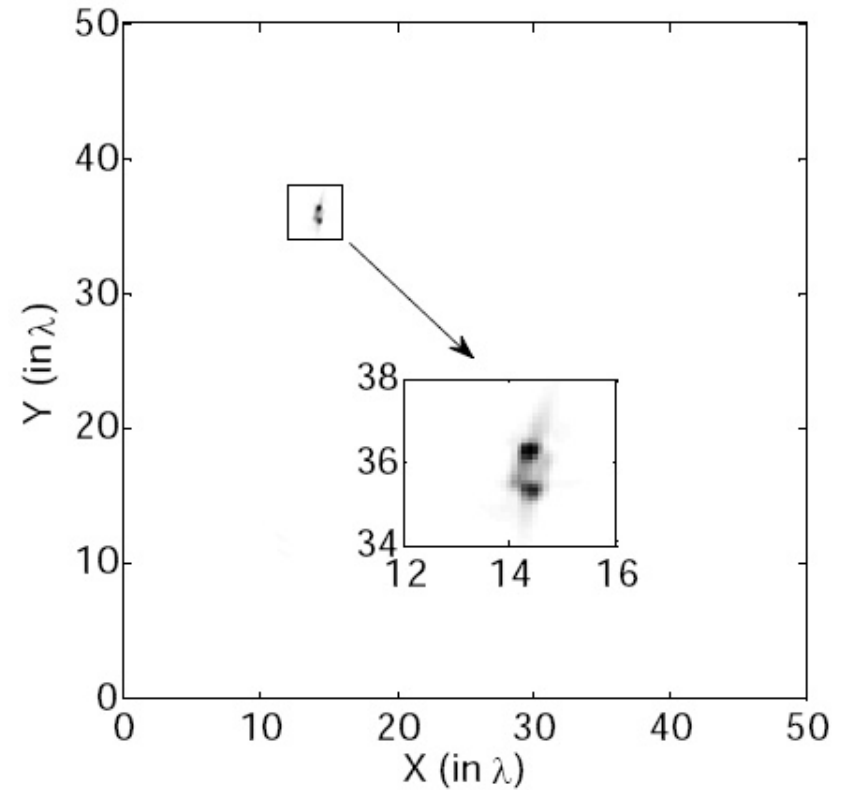
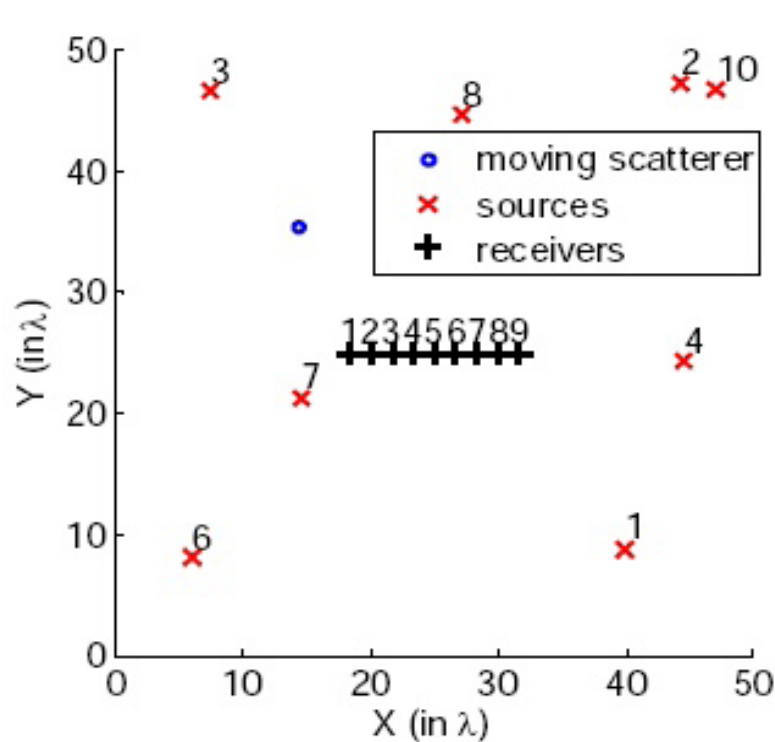
Locating weak changes in the multiple scattering regime



Thomas PLANES , Eric LAROSE, Vincent ROSSETTO, Ludovic MARGERIN.

Classical imaging (pulse-echo)

Homogeneous medium \Leftrightarrow Single scattering regime

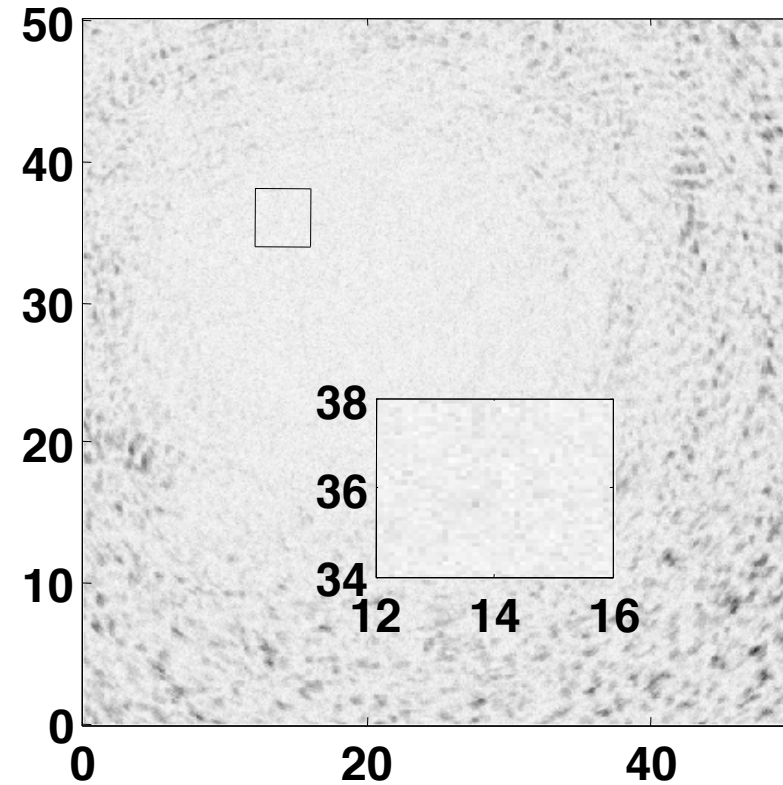
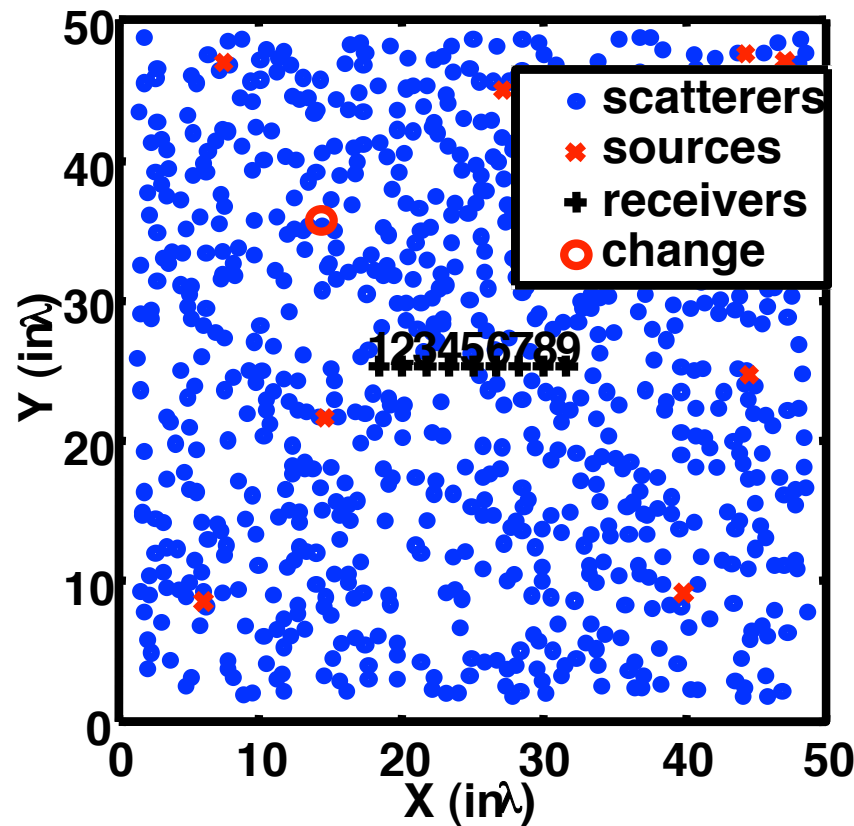


$$I(x, y) = \sum_{S,R} [\phi_0(S, R, \delta) - \phi_1(S, R, \delta)]^2 \quad \delta : \text{Time of flight } S - \text{pixel}(x, y) - R$$

Classical imaging (pulse-echo)

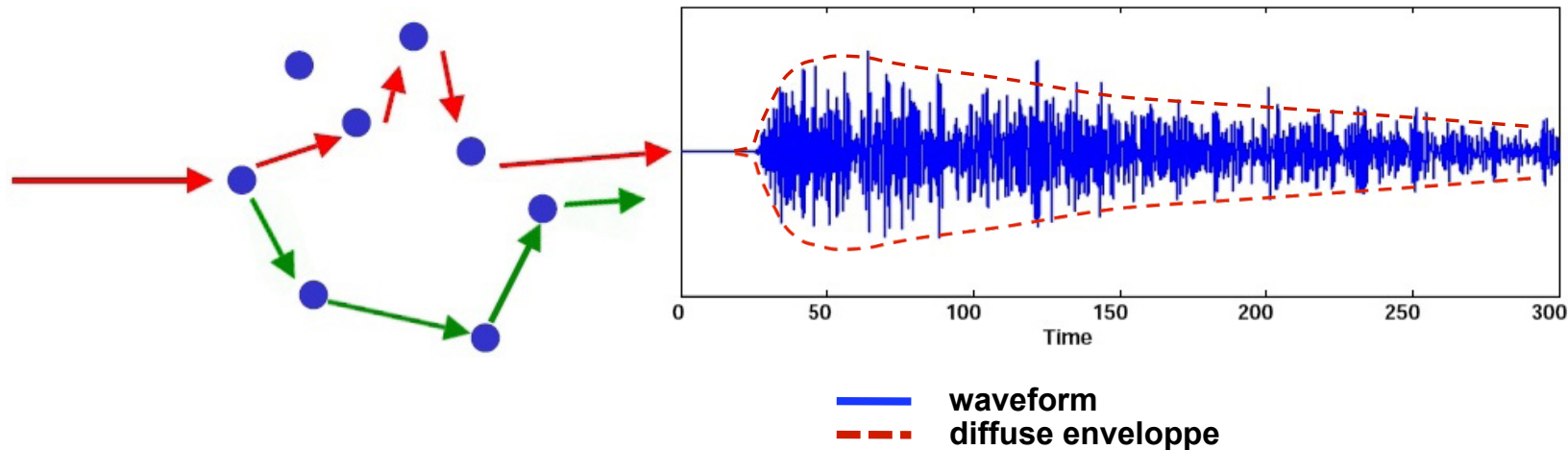
Highly heterogeneous medium \Leftrightarrow Multiple scattering regime

$$\lambda \ll l^* \ll l_{abs}, L_{medium}$$



$$I(x, y) = \sum_{S,R} [\phi_0(S, R, \delta) - \phi_1(S, R, \delta)]^2 \quad \delta : \text{Time of flight } S - \text{pixel}(x, y) - R$$

Locating with the coda

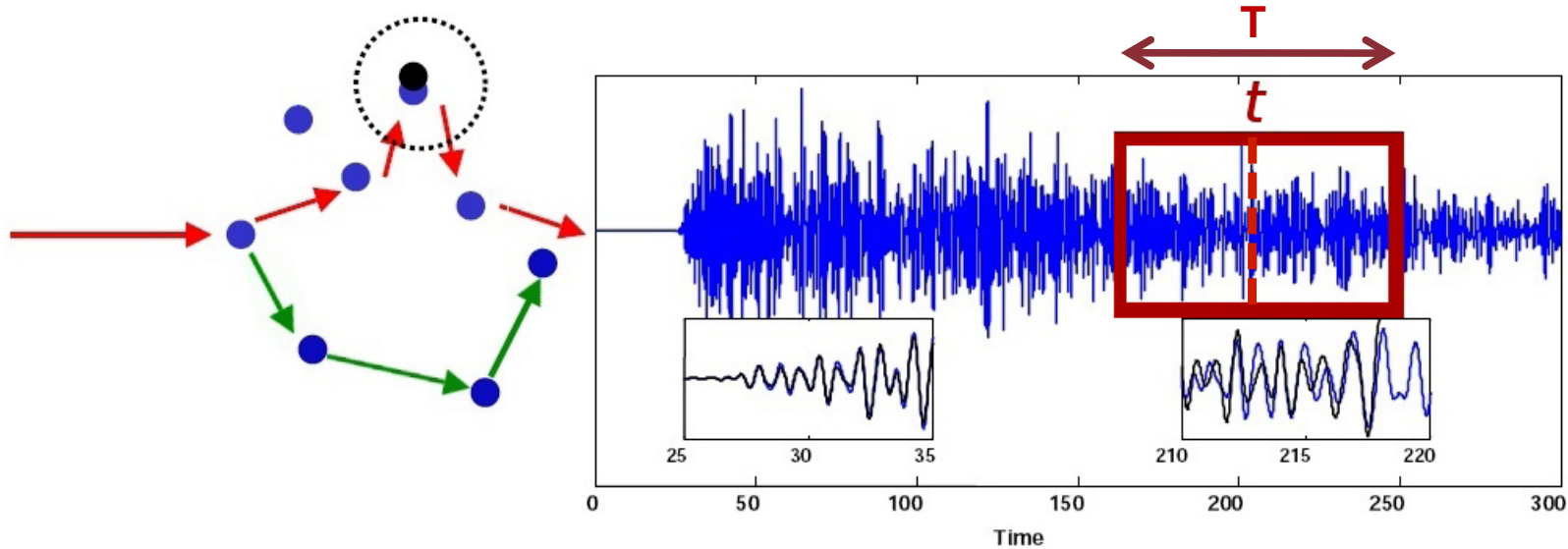


- Complex signal (one arrival time \Leftrightarrow several trajectories)
- Diffuse intensity

➔ Statistical approach

- Intensity correlation [Feng & Sornette 1991]
- Time-lapse travel time change [Pacheco & Snieder 2005]
- D(A)WS...[Pine et al. 1988, Cowan et al. 2002]

Signature of a change in the coda

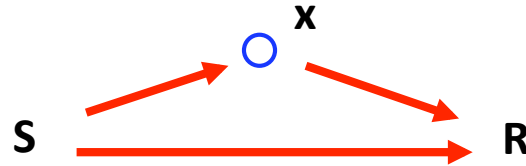


Very sensitive to weak changes

$$\text{Decorrelation : } DC(t) = 1 - \frac{\langle \phi_0(t) \cdot \phi_1(t) \rangle_T}{\sqrt{\langle \phi_0(t)^2 \rangle_T \langle \phi_1(t)^2 \rangle_T}}$$

$$\text{Stretching factor : } \epsilon(t) = \epsilon \text{ that maximises } \langle \phi_0(t) \cdot \phi_1(t(1 - \epsilon)) \rangle_T$$

Decorrelation induced by an extra scatterer : Theoretical model



Role of an extra scatterer : Nieuwenhuizen & Van Rossum [1993]

Theoretical decorrelation

$$DC^{th}(S, R, r, t) = \frac{c\sigma}{2} \frac{\int_0^t I(S, r, u)I(r, R, t - u)du}{I(S, R, t)}$$

Rossetto et al. [JAP 2011]

I : Intensity propagator (Diffusion solution, Radiative Transfer)

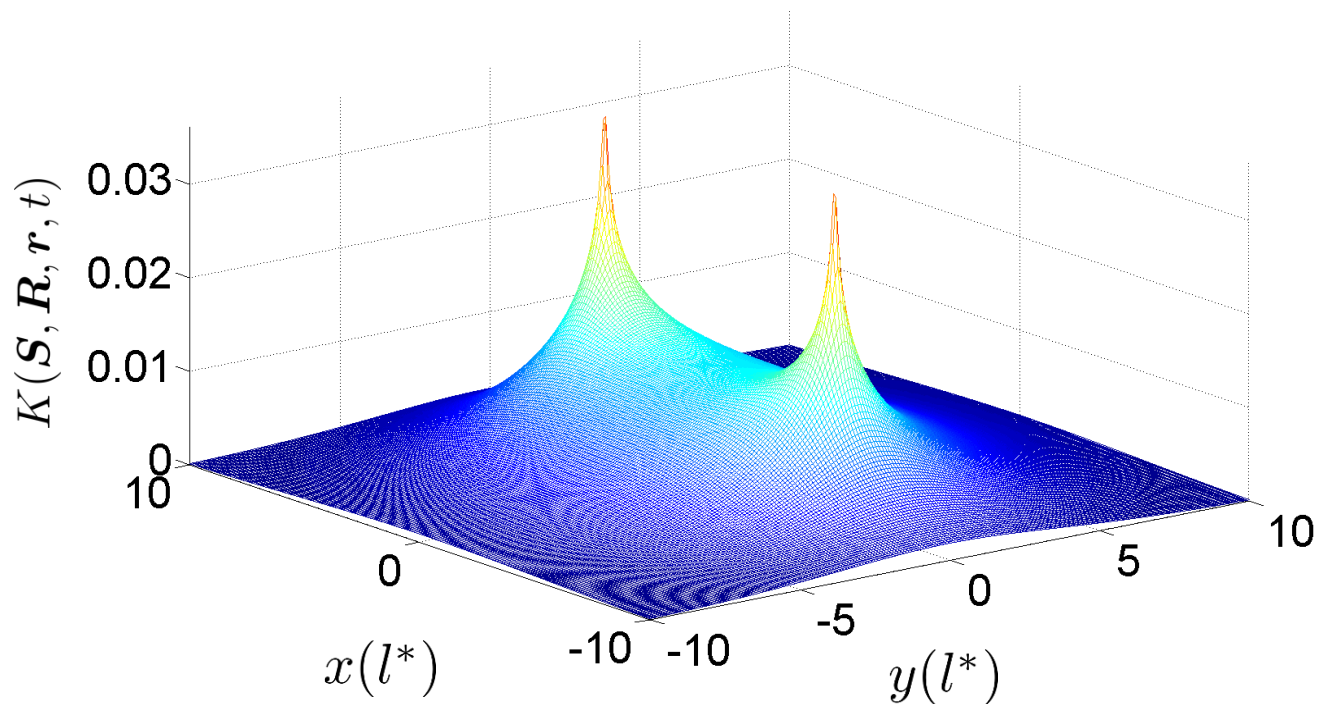
σ : Scattering cross section of the new defect

Sensitivity kernel

decorrelation

$$DC^{th}(S, R, r, t) = \frac{c\sigma}{2} K(S, R, r, t)$$

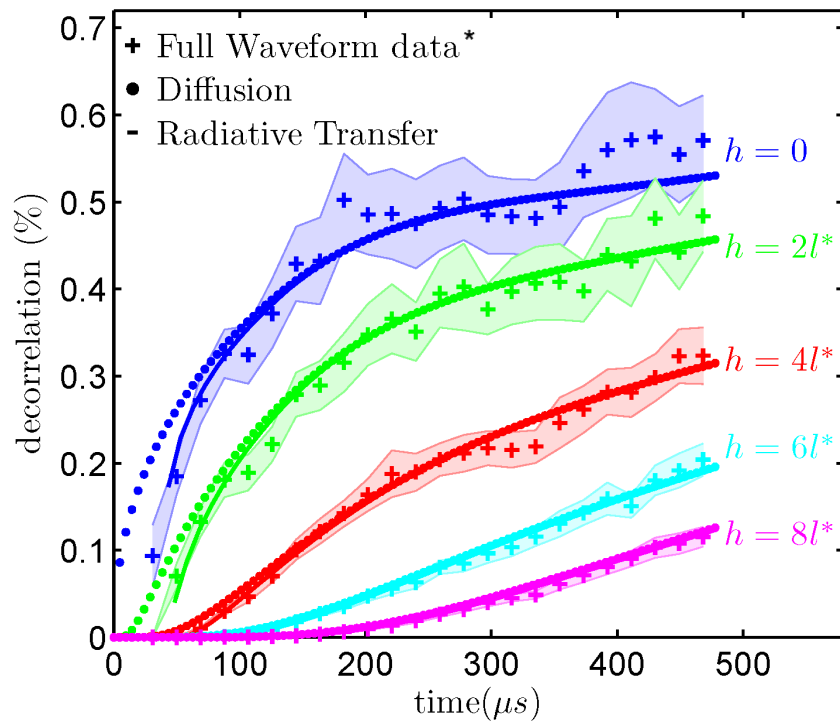
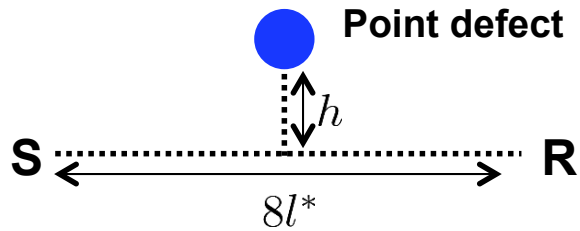
$$K(S, R, r, t) = \frac{\int_0^t I(S, r, u) I(r, R, t - u) du}{I(S, R, t)}$$



$I(S, R, t) =$ Diffusion solution

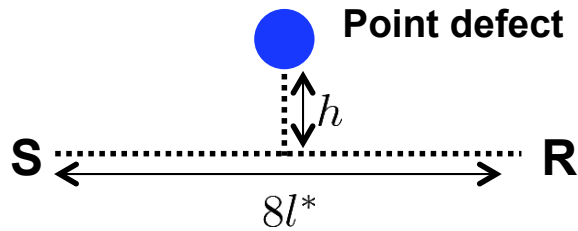
Forward problem validation

Far field

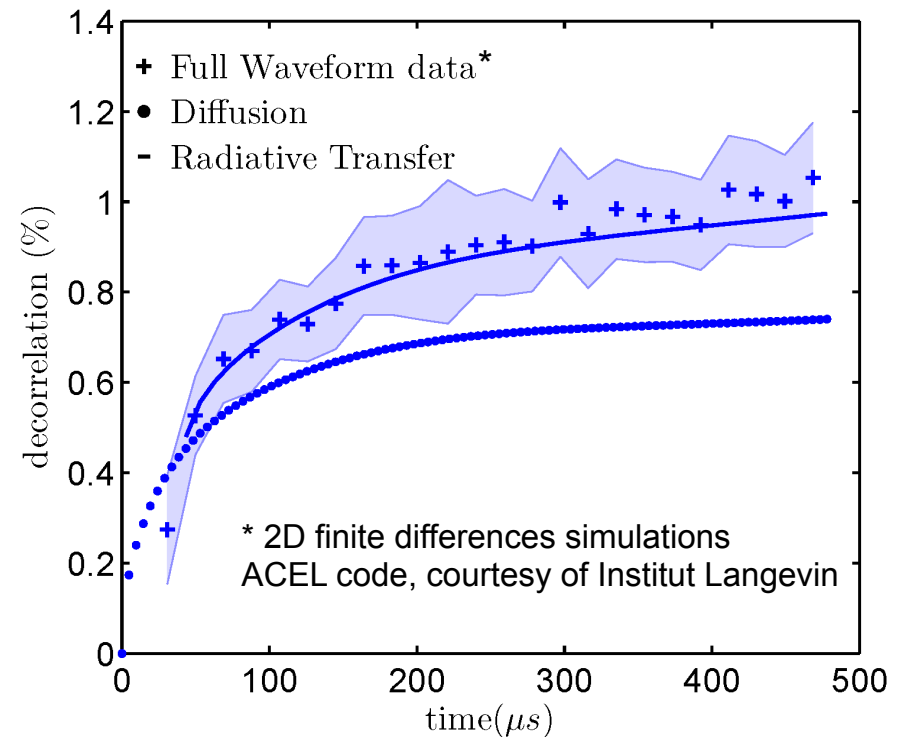
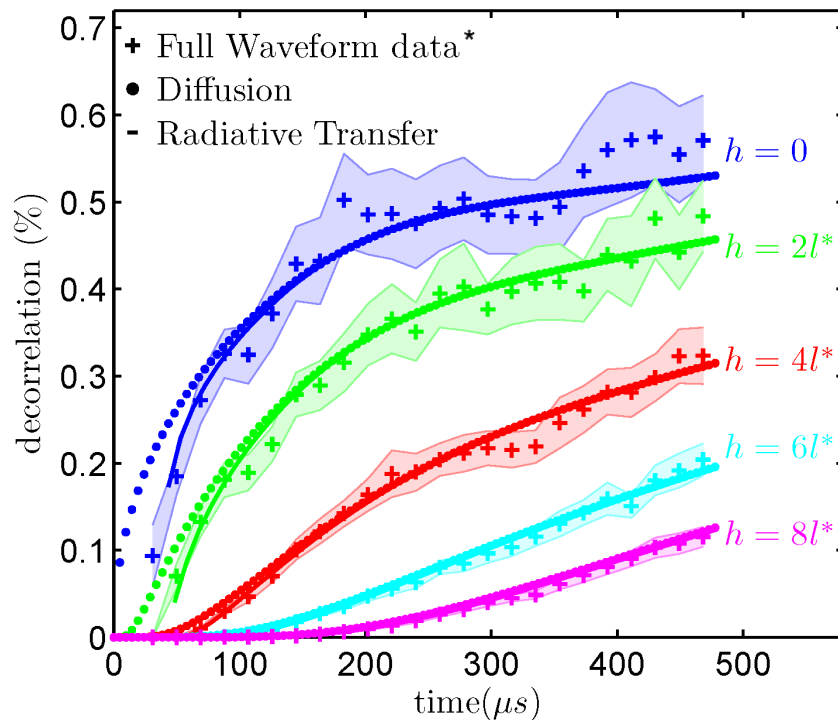
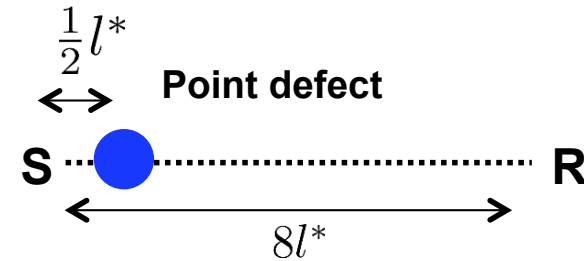


Forward problem validation

Far field

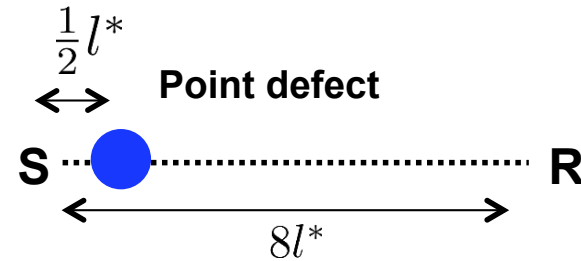


Near field



Forward problem validation

Near field



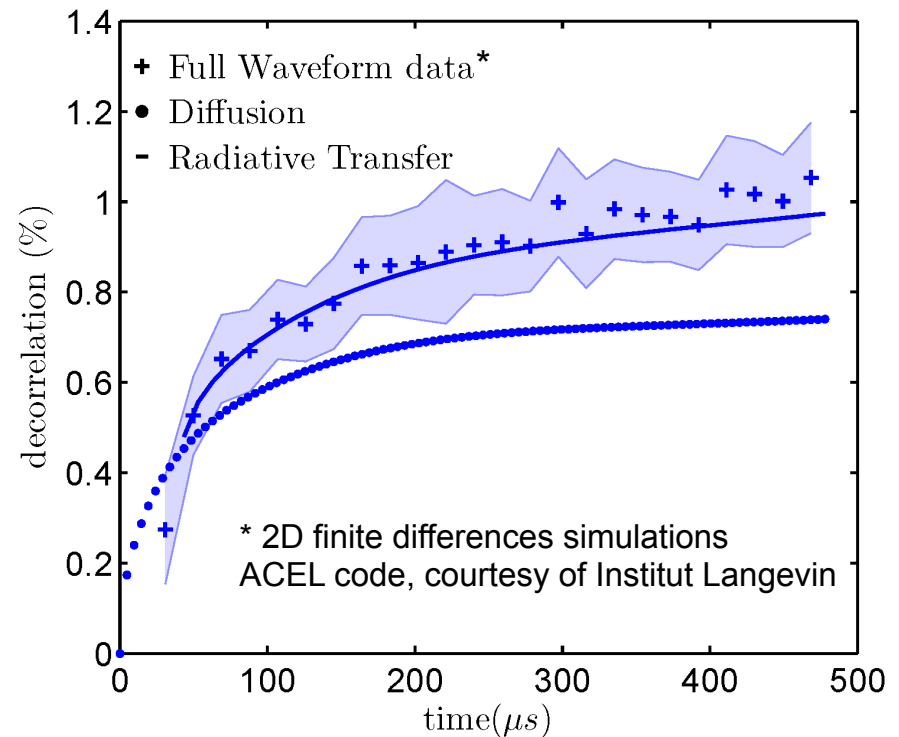
2D Radiative Transfer Solution
[Paasschens PRE 1997] :

$$I(\mathbf{r}, t) = \underbrace{\frac{e^{-ct/l}}{2\pi r} \delta(ct - r)}_{\text{cohérent}}$$

cohérent

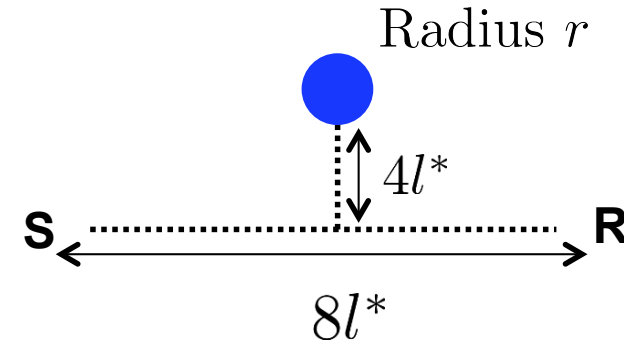
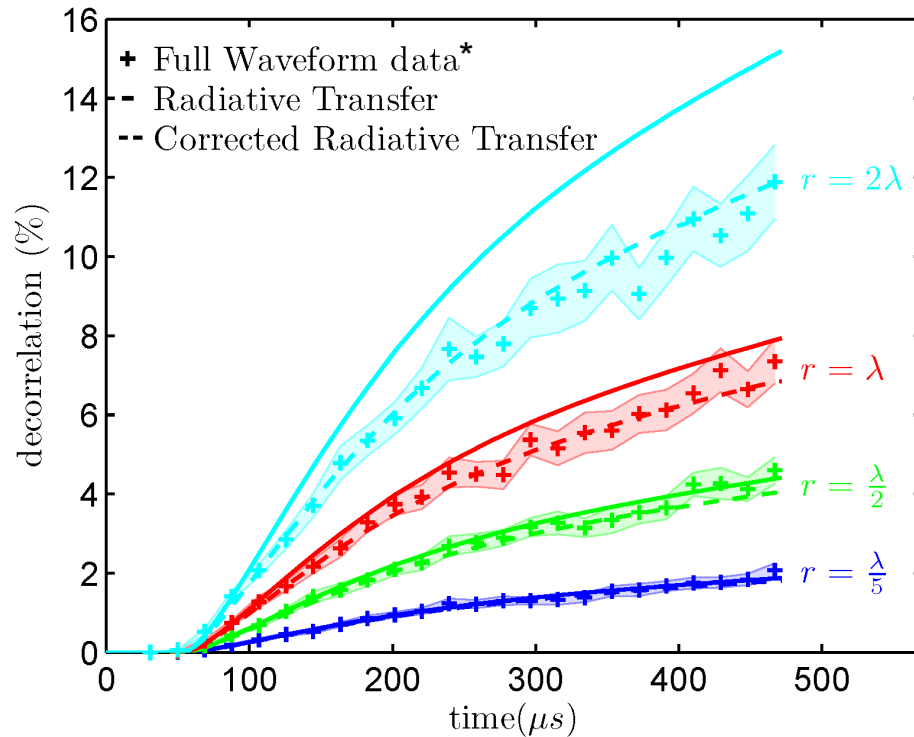
$$+ \underbrace{\frac{1}{2\pi l ct} \left(1 - \frac{r^2}{c^2 t^2}\right)^{-\frac{1}{2}} e^{[l^{-1}(\sqrt{c^2 t^2 - r^2} - ct)]} \Theta(ct - r)}_{\text{incohérent}}$$

incohérent



Forward problem validation

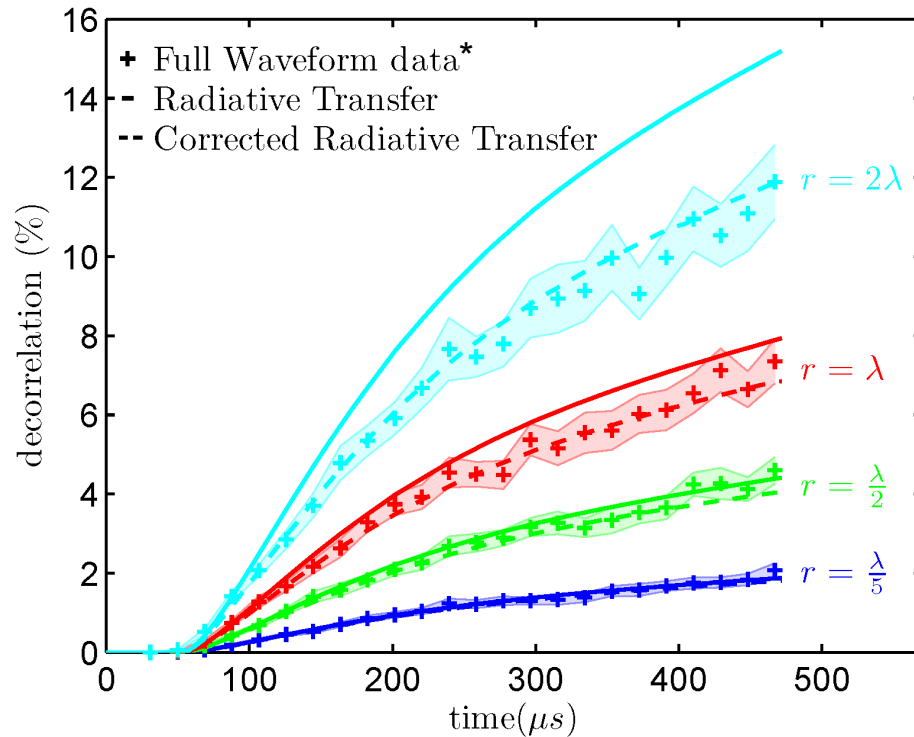
Size of the defect



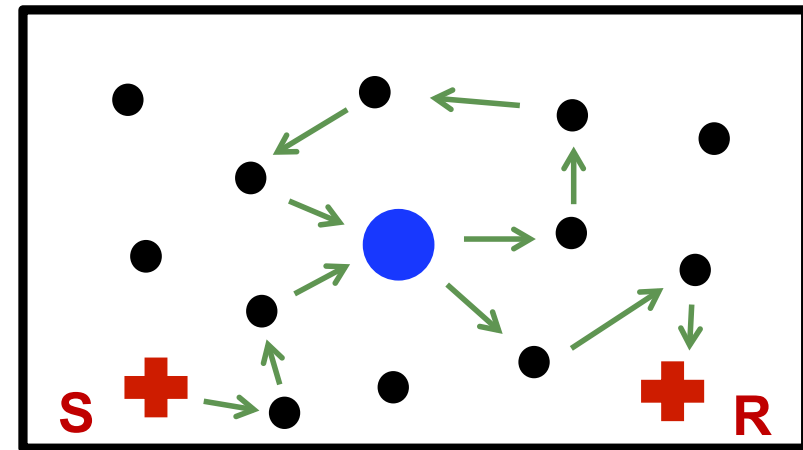
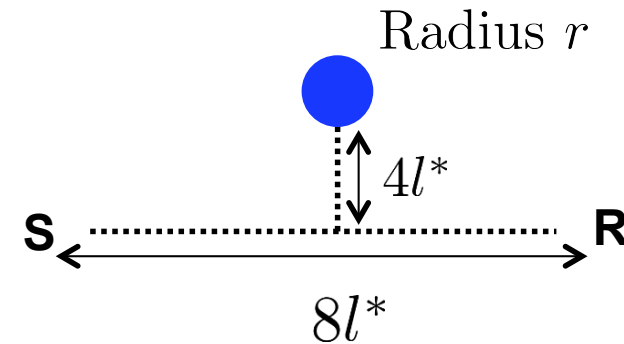
* 2D finite differences simulations
 ACEL code, courtesy of Institut Langevin

Forward problem validation

Size of the defect



* 2D finite differences simulations
 ACEL code, courtesy of Institut Langevin



Loops contribution

Inversion process

First approach : locating one local change

Experiment:

$$\phi_0^{ij}(S_i, R_j, t) \quad \phi_1^{ij}(S_i, R_j, t)$$

➔ $DC_{ij}^{exp}(S_i, R_j, t)$

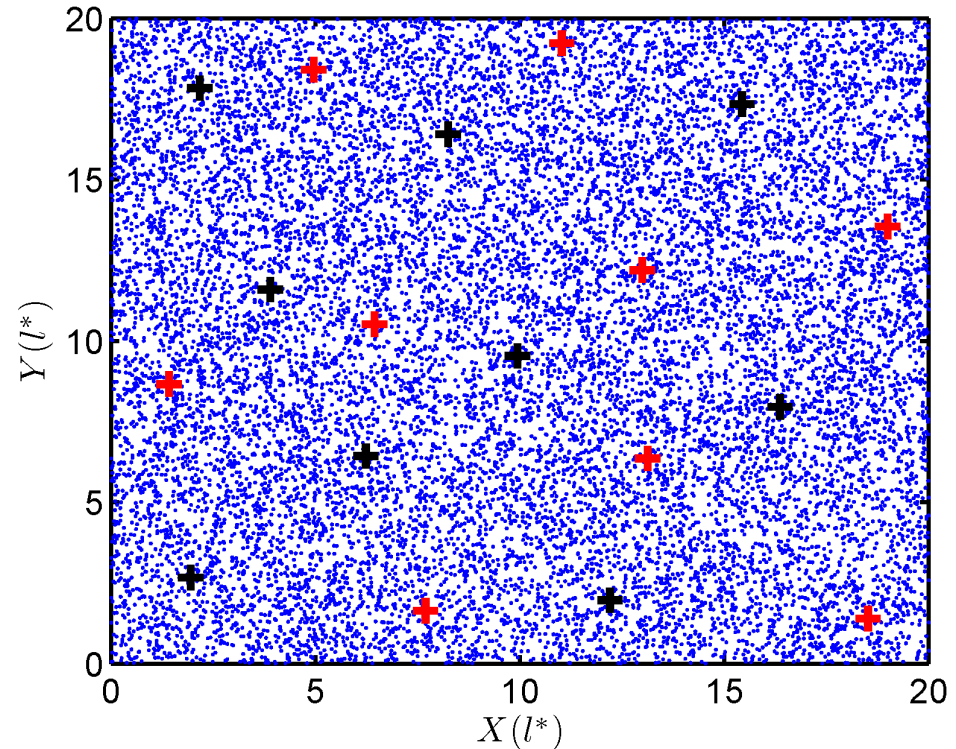
Experimental decorrelations

Numerical model :

For each pixel r :

➔ $DC_{ij}^{th}(S_i, R_j, r, t)$

Theoretical decorrelation






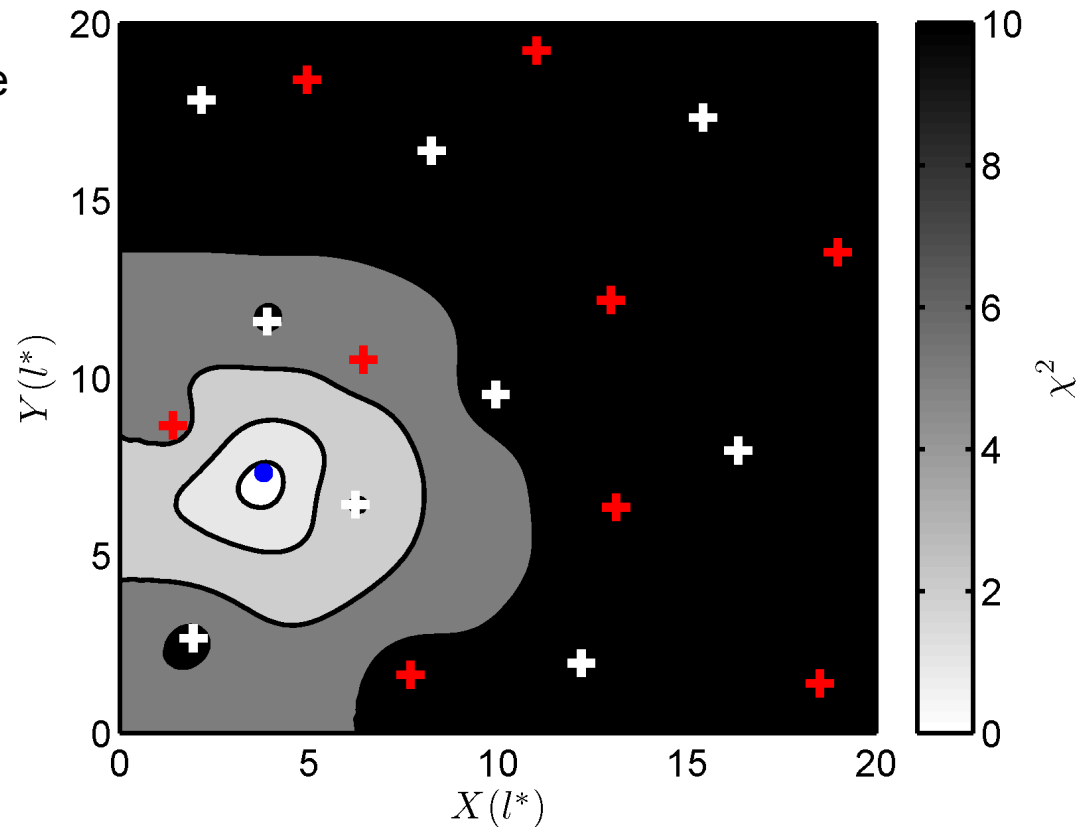
(r, σ) that minimizes the misfit ?

Inversion process

First approach : locating one local change

- 2D Acoustic Finite-Difference Simulation
- Reflective Boundaries

-  Sources
-  Receivers
-  New defect :
Point Defect






$$\text{Misfit function map : } \chi^2(\mathbf{r}) = \frac{1}{N\epsilon^2} \sum_{ij} (DC_{ij}^{exp} - DC_{ij}^{th})^2$$

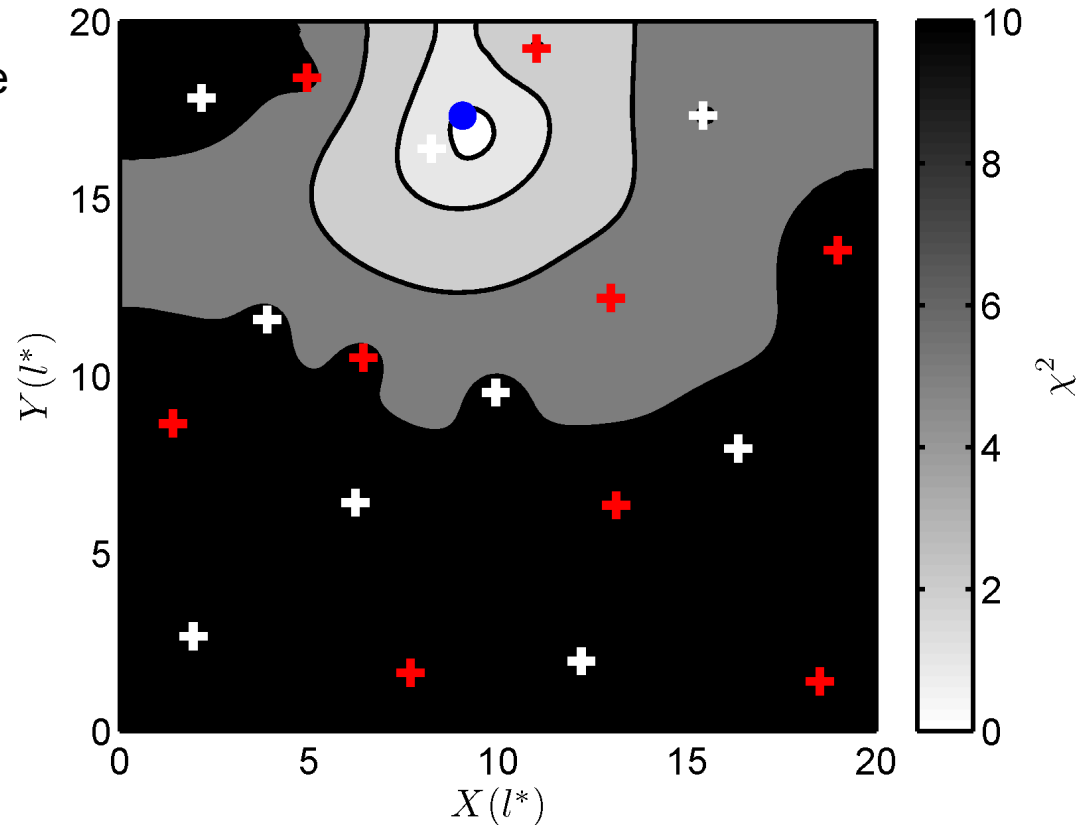
Inversion process

First approach : locating one local change

- 2D Acoustic Finite-Difference Simulation
- Reflective Boundaries

-  Sources
-  Receivers
-  New defect :

$$\text{Radius} = \frac{\lambda}{4}$$






$$\text{Misfit function map : } \chi^2(\mathbf{r}) = \frac{1}{N\epsilon^2} \sum_{ij} (DC_{ij}^{exp} - DC_{ij}^{th})^2$$

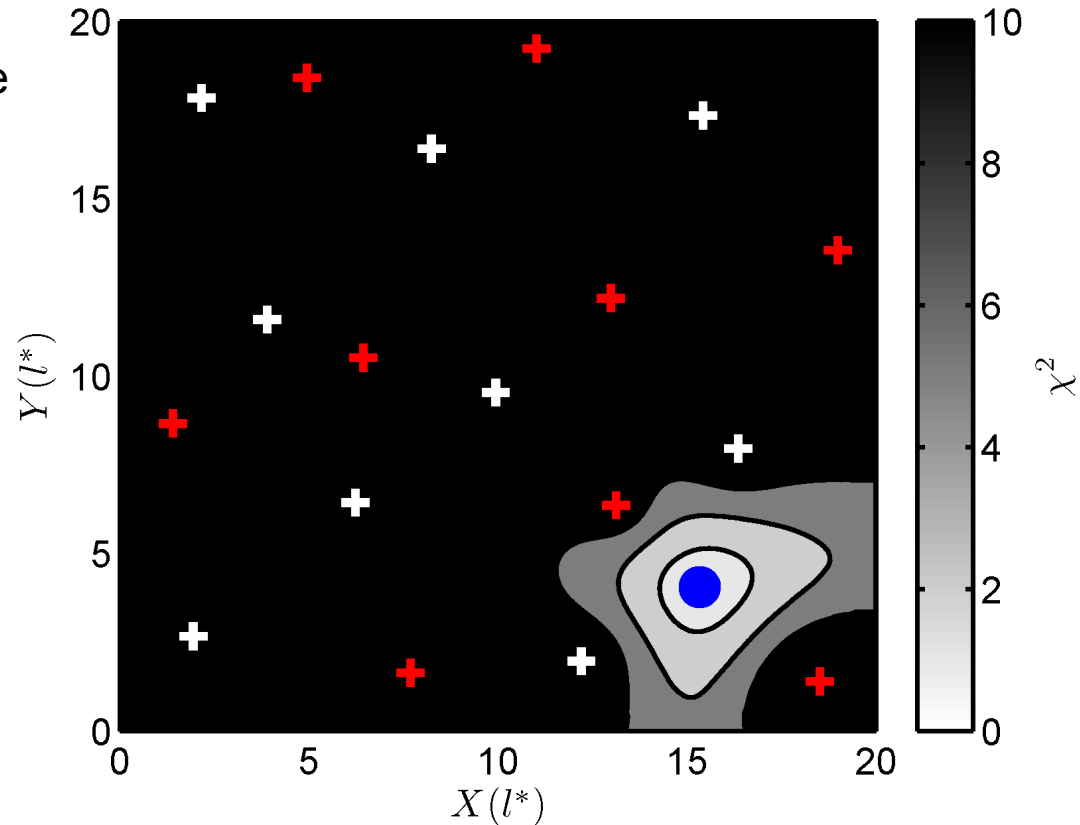
Inversion process

First approach : locating one local change

- 2D Acoustic Finite-Difference Simulation
- Reflective Boundaries

-  Sources
-  Receivers
-  New defect :

$$\text{Radius} = \frac{\lambda}{2}$$






$$\text{Misfit function map : } \chi^2(\mathbf{r}) = \frac{1}{N\epsilon^2} \sum_{ij} (DC_{ij}^{exp} - DC_{ij}^{th})^2$$

Inversion process

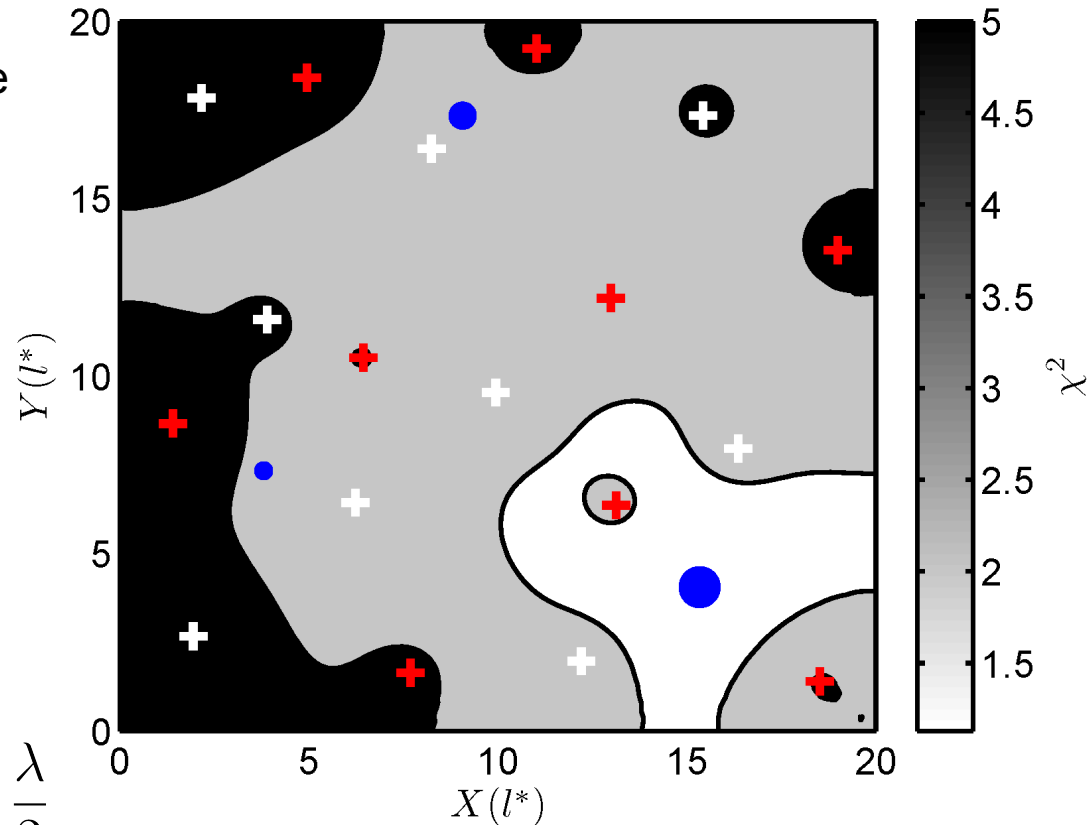
First approach : locating one local change

- 2D Acoustic Finite-Difference Simulation
- Reflective Boundaries

-  Sources
-  Receivers
-  New defect :

Point Defect,

$$\text{Radius} = \frac{\lambda}{4}, \text{Radius} = \frac{\lambda}{2}$$



$$\text{Misfit function map : } \chi^2(\mathbf{r}) = \frac{1}{N\epsilon^2} \sum_{ij} (DC_{ij}^{exp} - DC_{ij}^{th})^2$$

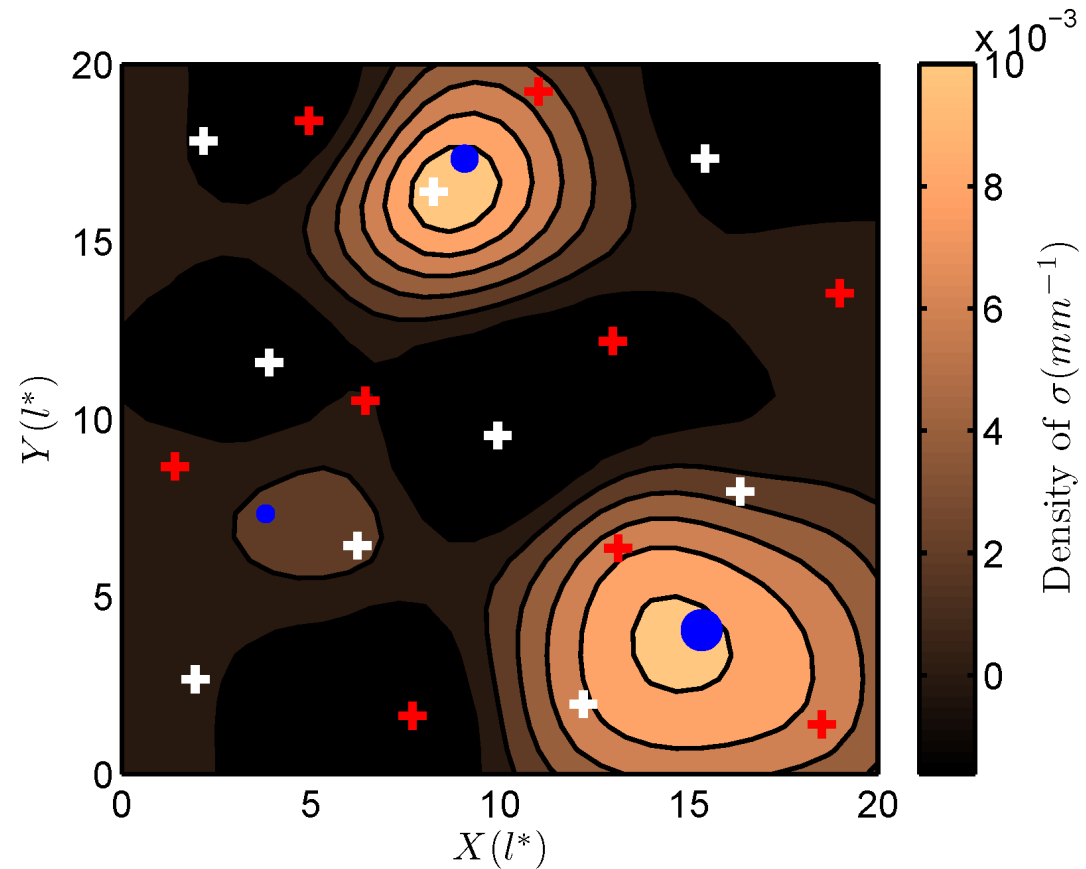
Inversion process

Locating several changes

Linear forward problem :

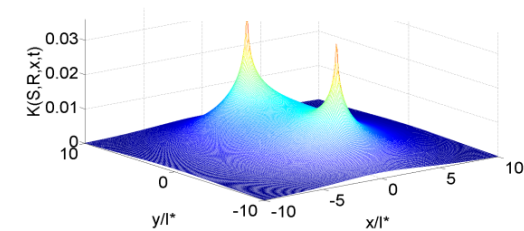
$$DC = \frac{c}{2} K \sigma$$

Least square inversion
[Tarantola 2005] :



Applications :

- Same sensitivity kernel, different measures (extra scatterer, velocity change)
- Non destructive testing in civil engineering
- Monitoring in geophysics (active faults, volcanoes)



Outlook :

- Imaging of extended or multiple defects
- Characterizing the change (fluid ?, absorbing ?, geometry ?)

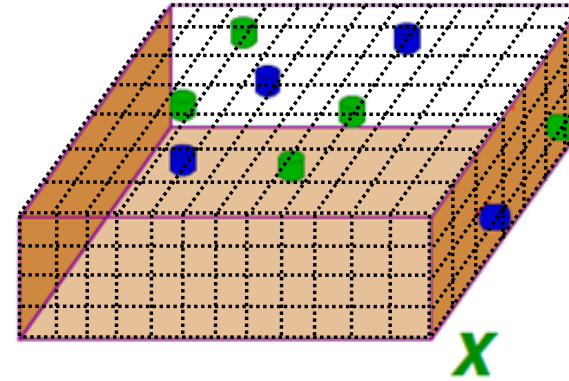
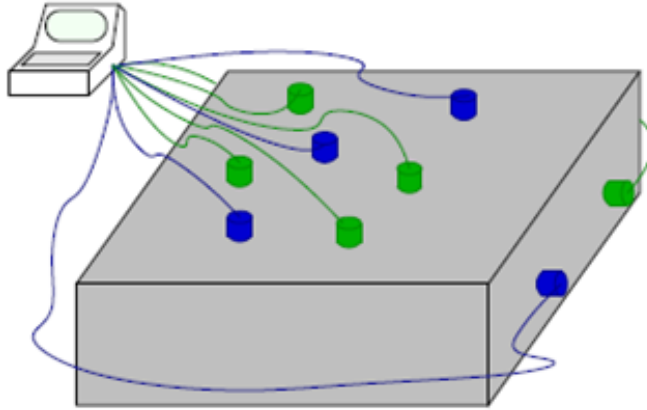


Publications :

- Larose et al., Appl. Phys. Lett. 96, 204101 (2010)
- Rossetto et. al., J. Appl. Phys. 109, 034903 (2011)
- Patent No. FR09-50612

Inversion process

First approach : locating one local change



Experiment :

$$\varphi_0^{ij}(S_i, R_j, t) \quad \varphi_1^{ij}(S_i, R_j, t)$$

➔ $Q_{ij}^{\text{exp}}(S_i, R_j, t)$

Experimental decorrelations

Numerical model :

For each voxel x :

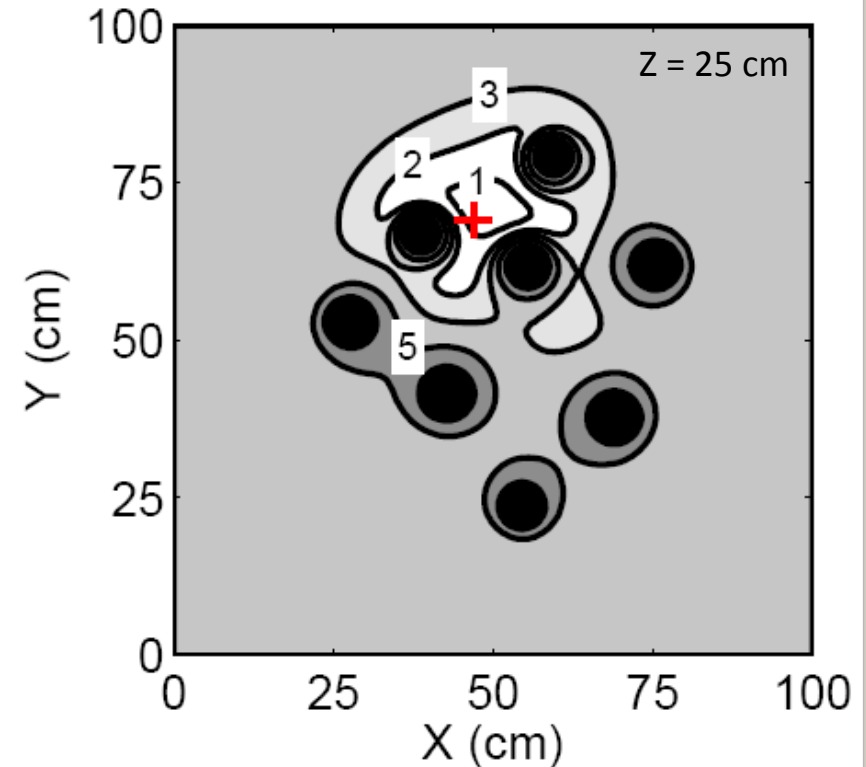
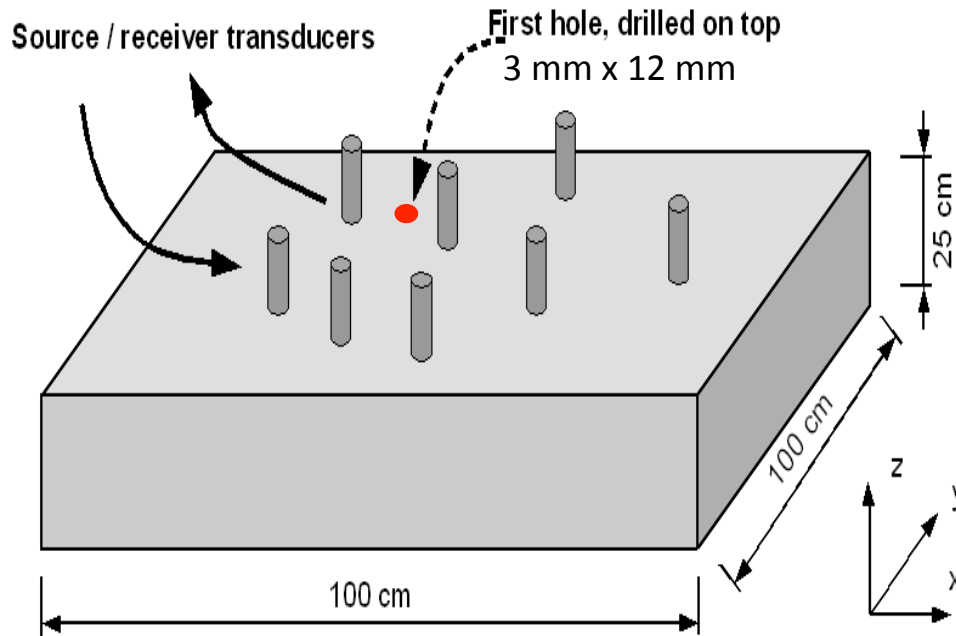
➔ $Q_{ij}^{\text{th}}(S_i, R_j, x, t)$

Theoretical decorrelation

(x, σ) that minimizes the misfit ?

Experimental results on concrete

Larose et al. [Appl. Phys. Lett. 2010]



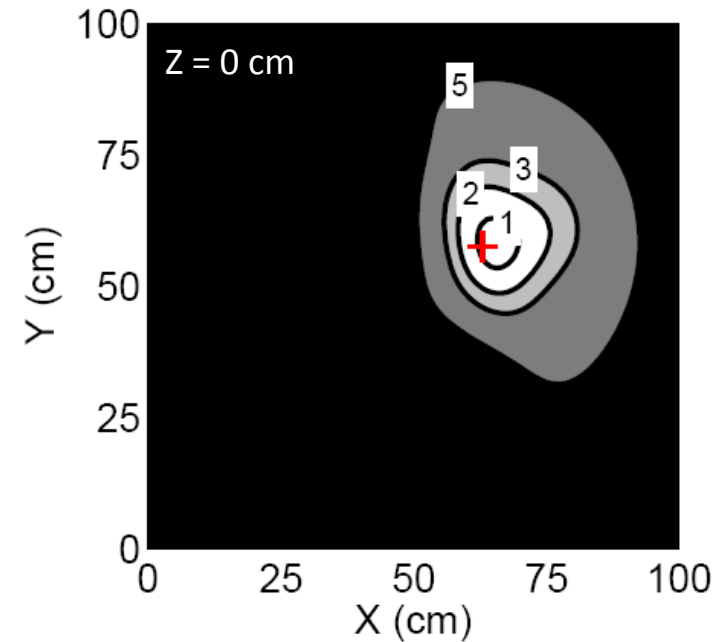
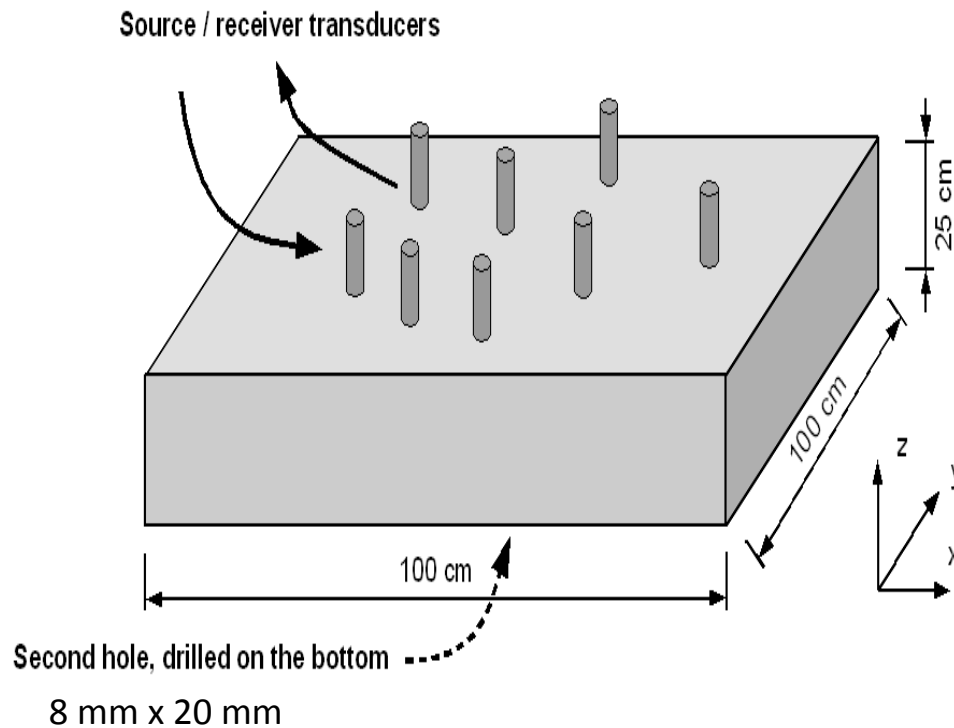
$$\chi^2(x) = \frac{1}{N} \sum_{i,j} \left(Q_{ij}^{\text{exp}}(t) - Q_{ij}^{\text{th}}(x,t) \right)^2 / \varepsilon^2$$

N : number of transducer pairs

ε : measurement error

Experimental results on concrete

Larose et al. [APL 2010]

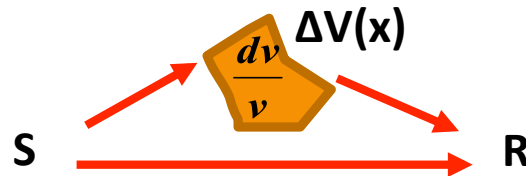


$$\chi^2(x) = \frac{1}{N} \sum_{i,j} \left(Q_{ij}^{\text{exp}}(t) - Q_{ij}^{\text{th}}(x,t) \right)^2 / \varepsilon^2$$

N : number of transducer pairs

ε : measurement error

Theoretical model predicting the stretching factor induced by a local velocity change



Time-lapse travel time change : Pacheco and Snieder [JASA 2005]

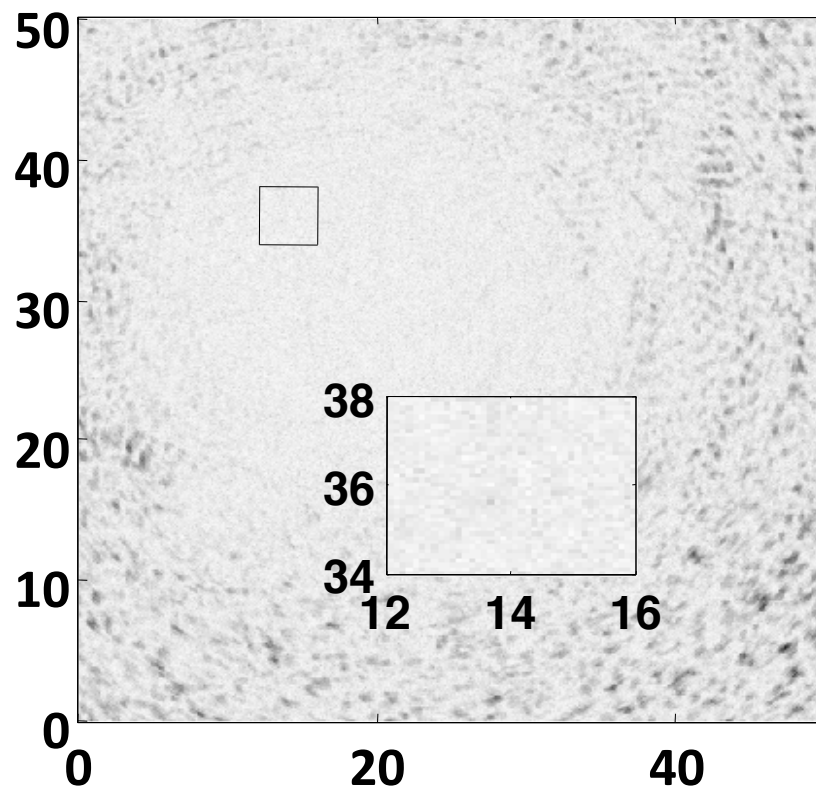
Theoretical stretching factor

$$\varepsilon^{\text{th}}(S, R, x, t) = \frac{dv}{v} \frac{\Delta V}{t} \frac{\int_0^t g(S, x, u) g(x, R, t - u) du}{g(S, R, t)}$$

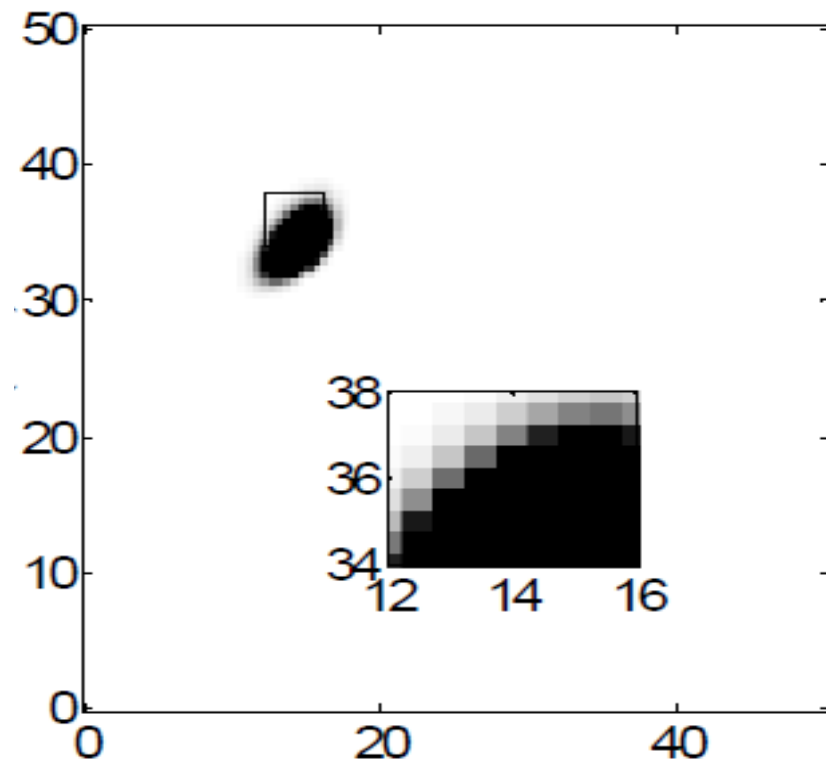
- $g(S, R, t)$ = intensity propagator (diffusion solution, radiative transfer)
- $\frac{dv}{v}$: local relative velocity change
- ΔV : elementary volume centered on x

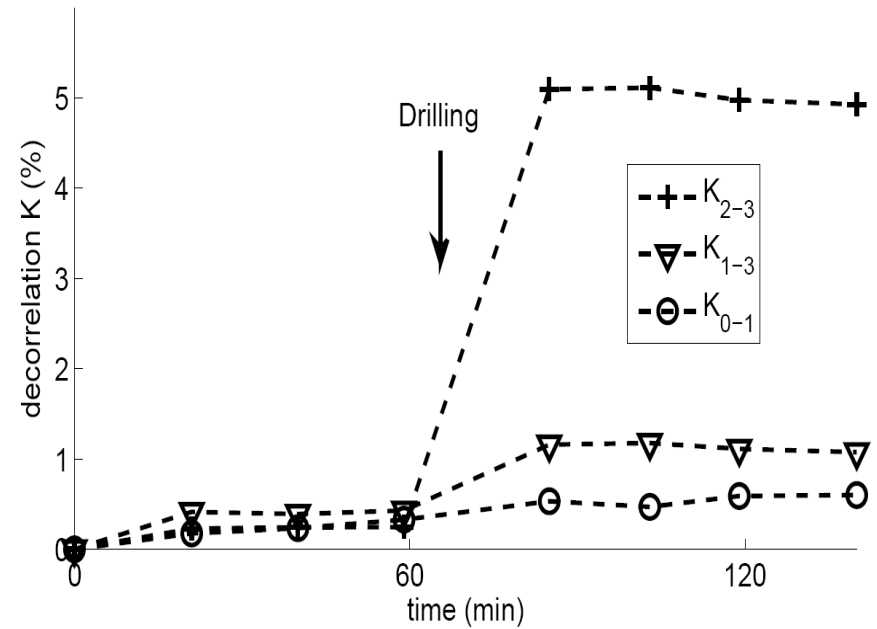
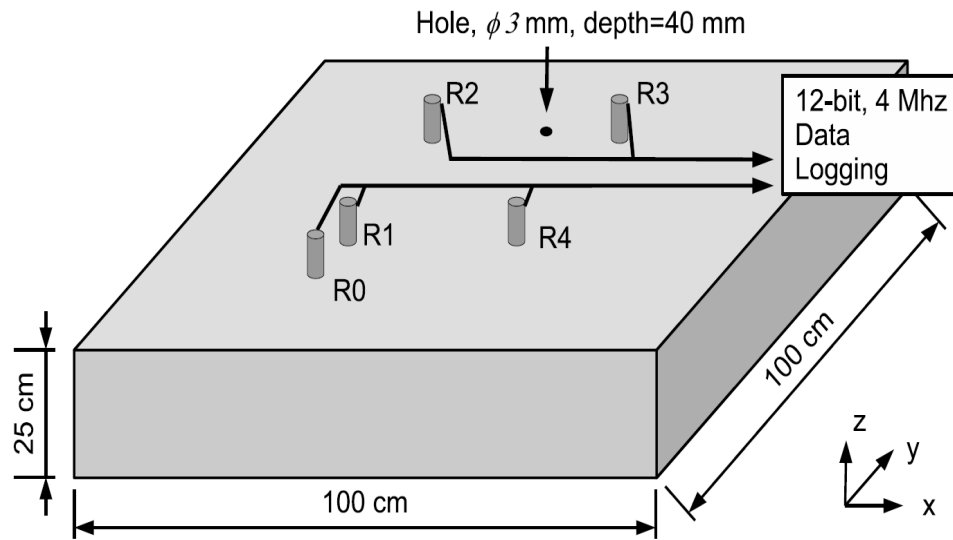
Results from numerical example

Standard imaging

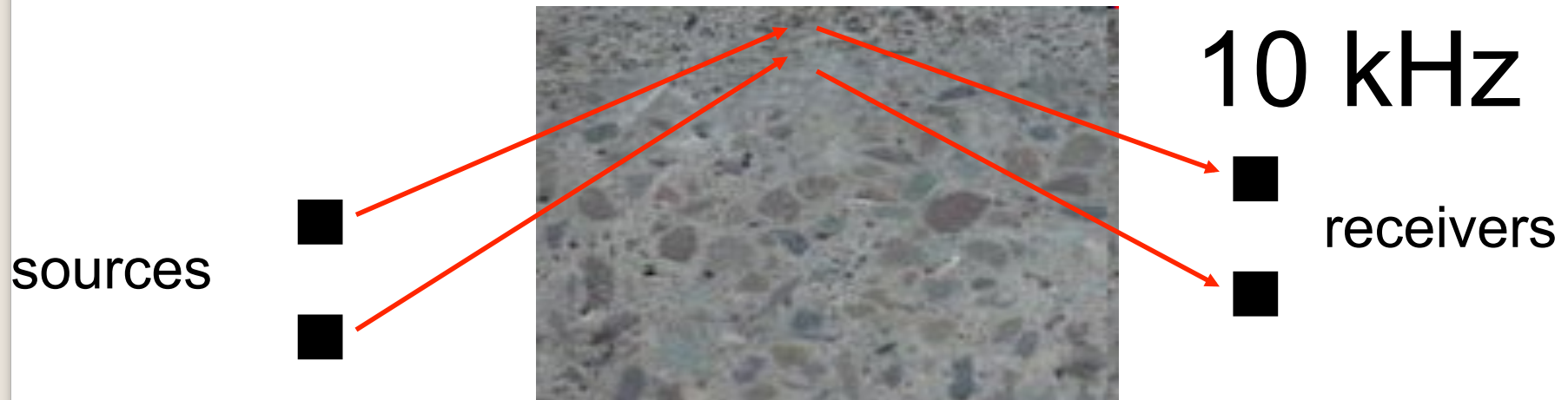


LOCADIFF

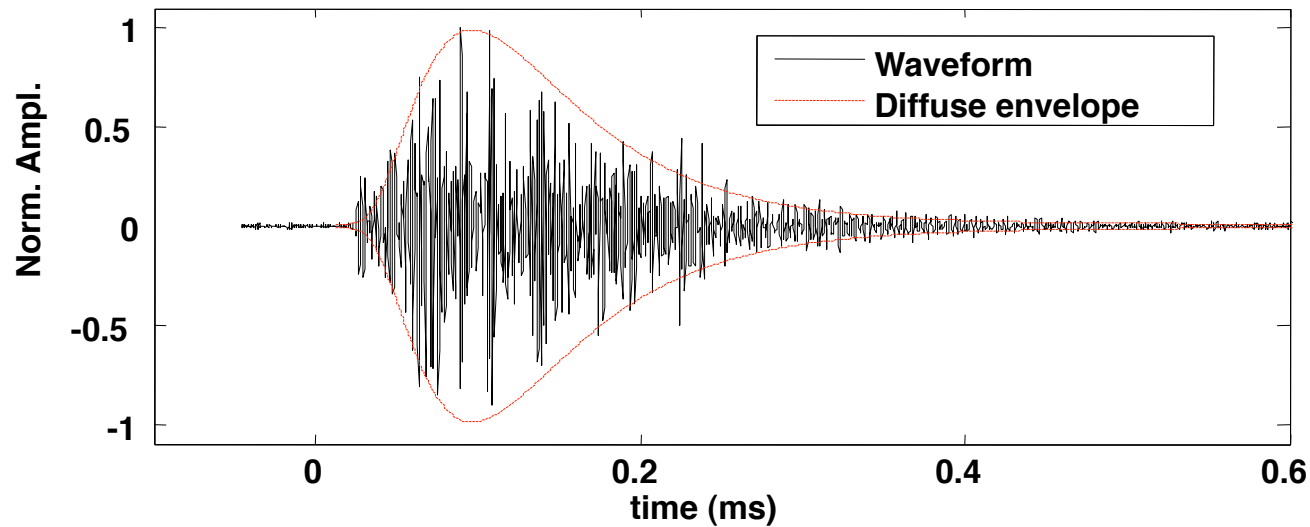




$$\chi^2(\mathbf{x}) = \sum_{i,j} (K_{ij}^d(t) - K_{ij}^n(\mathbf{x}, t))^2 / \epsilon^2$$



$c=2500\text{m}\cdot\text{s}^{-1}$, $\lambda=1\text{ cm}$, $\ell^*=3\text{ cm}$, $\ell_{\text{abs}}=50\text{ cm}$



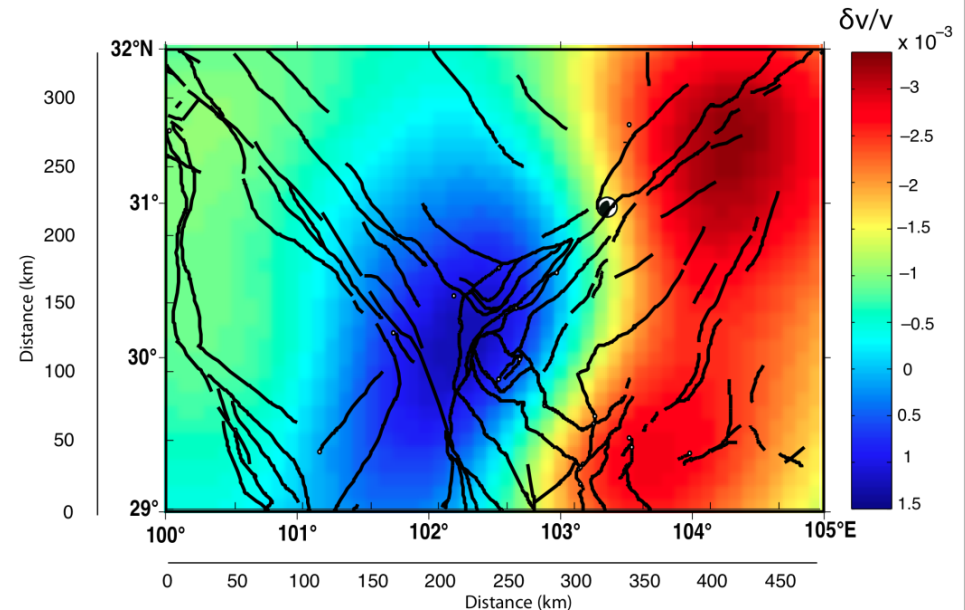
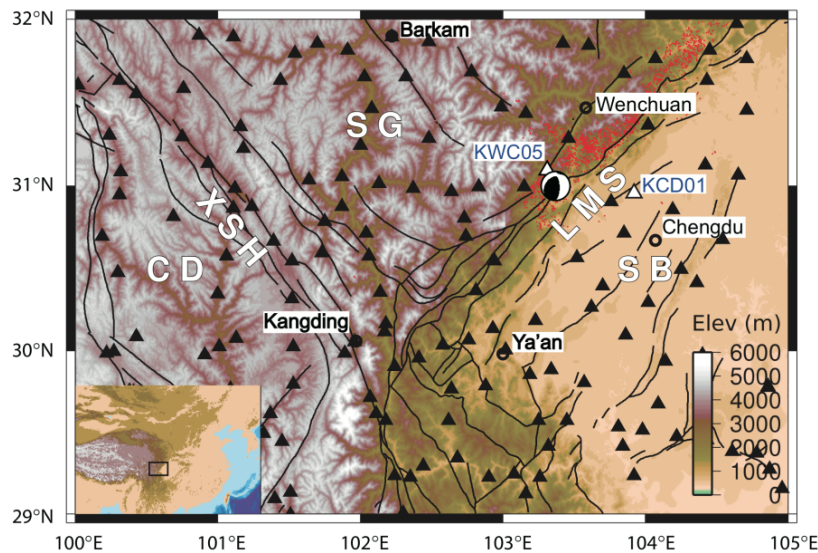
$c=2500\text{m}\cdot\text{s}^{-1}$, $\lambda=1\text{ cm}$, $\ell^*=3\text{ cm}$, $\ell_{\text{abs}}=50\text{ cm}$

Passive seismic data inversion

Berenice Froment (Phd), Michel Campillo

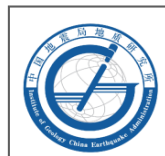
Wenchuan earthquake (May 12, 2008)

Longmen Shan fault zone, Sichuan province, China



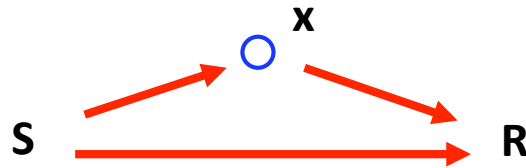
Data:

- . 156 broadband stations
- . 2 years of noise (2007-2008)
- . run by the Institute of Geology of the China Earthquake Administration



Relative velocity change map

Theoretical model predicting the decorrelation induced by an extra scatterer



Rôle of an extra scatterer :
Nieuwenhuizen & Van Rossum [1993]

Theoretical decorrelation

$$Q^{\text{th}}(x, t) = \frac{c\sigma \int_0^t g(S, x, u)g(x, R, t - u)du}{2 g(S, R, t)}$$

- $g(S, R, t)$ = Intensity propagator
- σ : scattering cross section

Rossetto et al. [JAP 2011]

Sensitivity kernel

$$Q^{\text{th}}(x, t) = \frac{c\sigma}{2} K(x, t)$$

