

Cargese (23 April 2013)

Exploring Earth's deep interior with ambient noise and earthquake signals

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Massachusetts Institute of Technology

Acknowledgments:

Scott Burdick (MIT), Huang Hui (MIT), Xuefeng Shang (MIT), Yao Huajian (now at USTC), Maarten de Hoop (Purdue University), Liu Qiyuan (Institute of Geology, China Earthquake Administration)

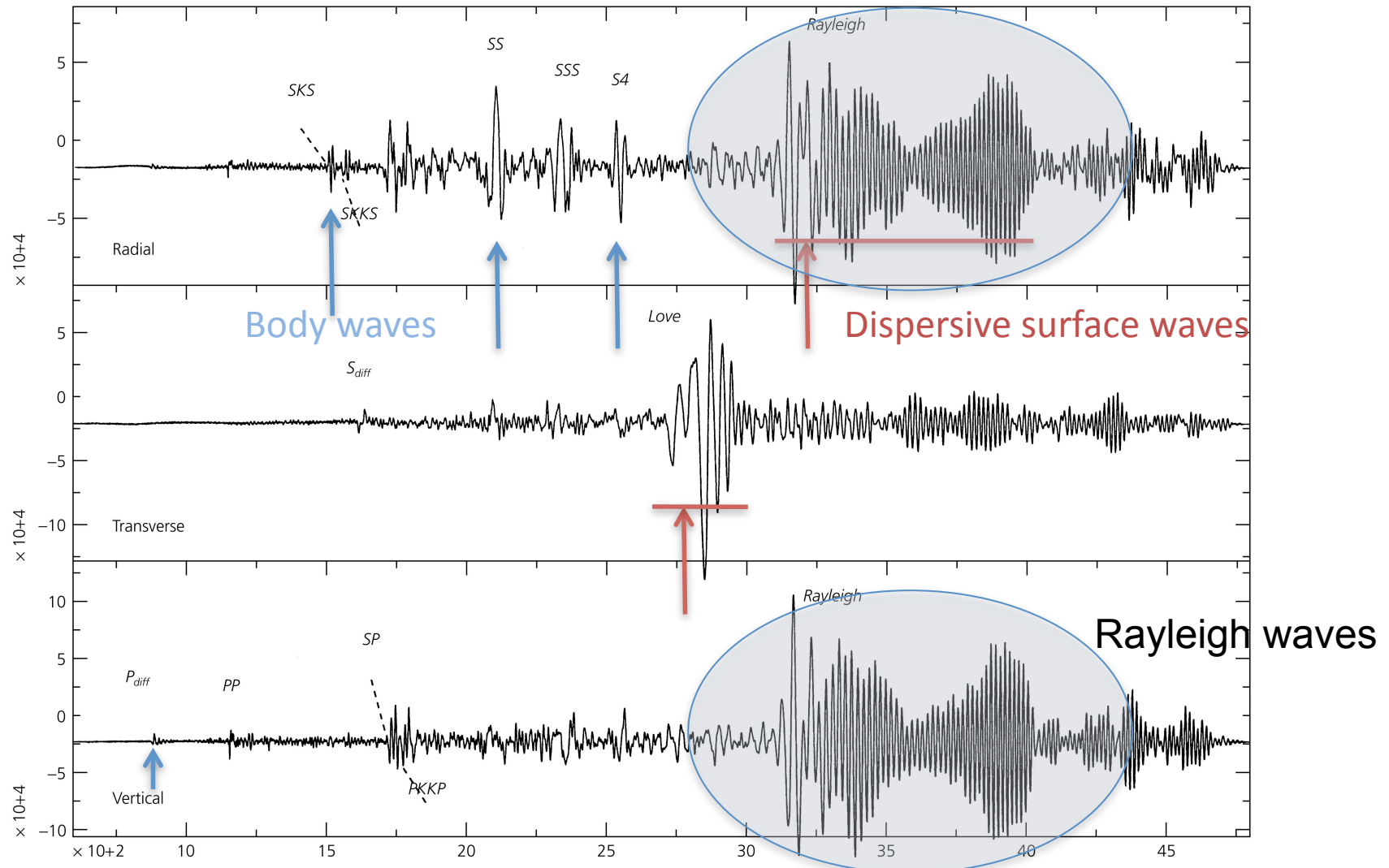
Overview of lecture:

1. Introduction/background
2. Ambient noise and surface wave tomography
3. Reverse time migration of converted waves
4. Interferometry of teleseismic (coda) waves

Frequency	Mhz-kHz	10000-100Hz	100-10Hz	10Hz-1Hz	1-0.01Hz
Domain	Laboratory acoustics	Underwater acoustics	Shallow seismic imaging	Seismic imaging	Seismology-large scale
Applications	NDT Monitoring	Tomography Source detection	Structure of shallow layers Geotechnical applications, land slides Monitoring	Natural resources Natural hazards Monitoring	Structure of the Earth, Earthquake risk zonation, Monitoring
Wave type	elastic waves, also sound in water	Acoustic waves	Elastic waves	Elastic waves	Elastic waves
Propagation	Reverberant, and Multiple-Scattering	Weak scattering	Strong attenuation	Weak (crust) to strong (volcanoes) scattering	Weak scattering

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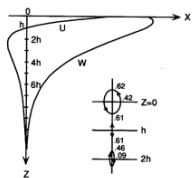
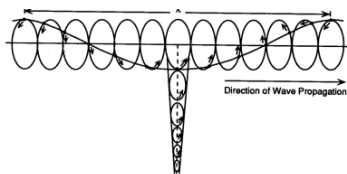
Figure 2.7-1: Seismograms recorded at a distance of 110°, showing surface waves.



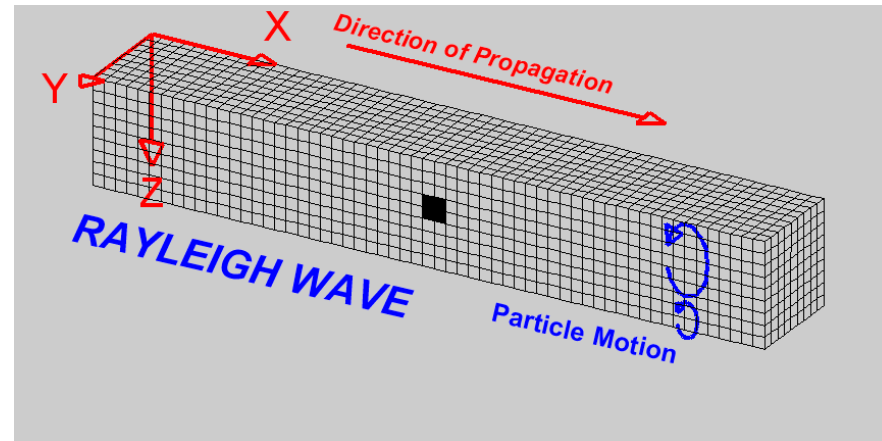
From Stein and Wyession

‘Surface and guided waves’: waves trapped in the shallow layers or a wave guide (such as Love waves in the Earth, acoustic waves in the oceanic SOFAR,)

Also in elasticity the Rayleigh wave at the surface of a half-space

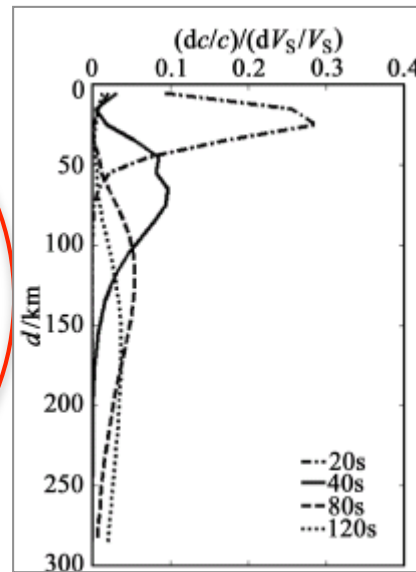
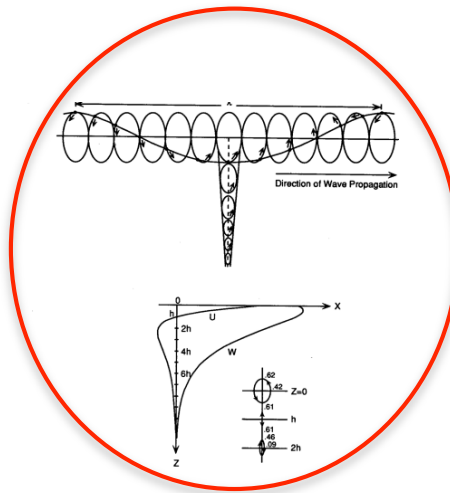


Eigenfunction

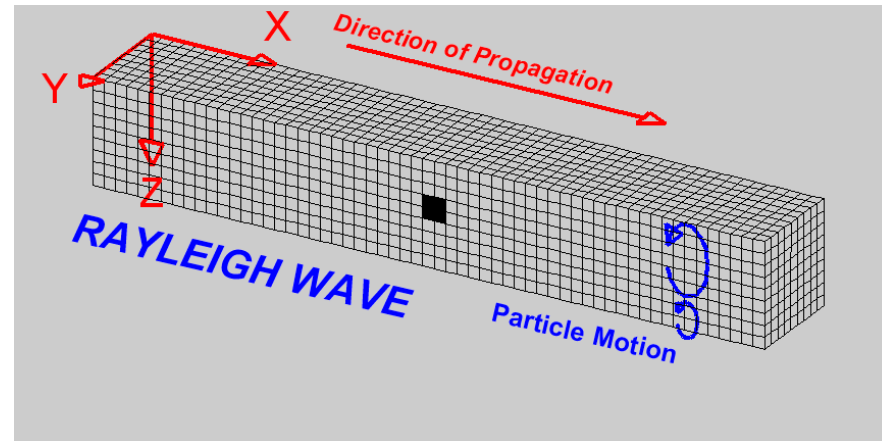


‘Surface and guided waves’: waves trapped in the shallow layers or a wave guide (such as Love waves in the Earth, acoustic waves in the oceanic SOFAR,)

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frequency proxy for depth



Courtesy: Campillo (Cargese, 2011)

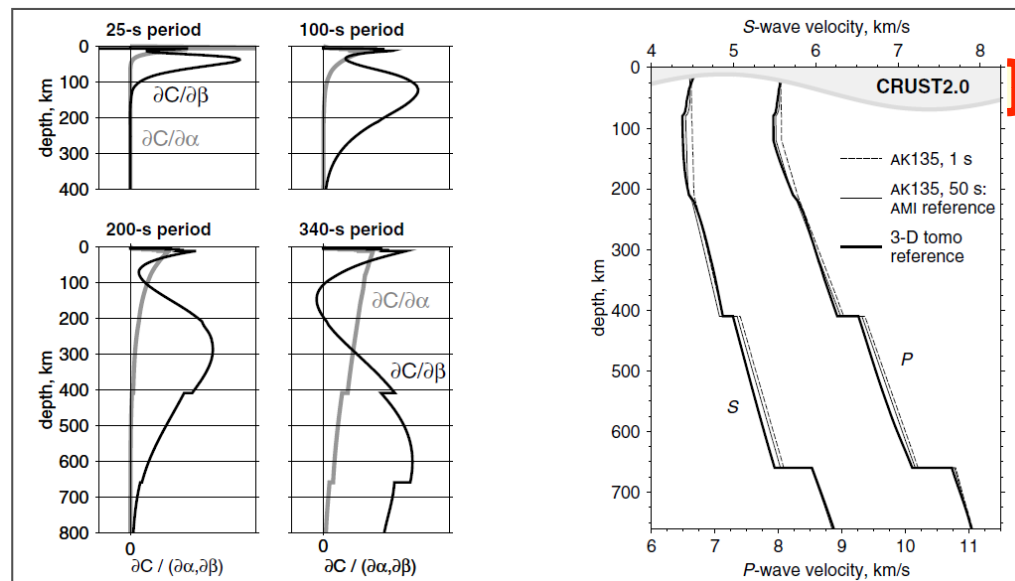
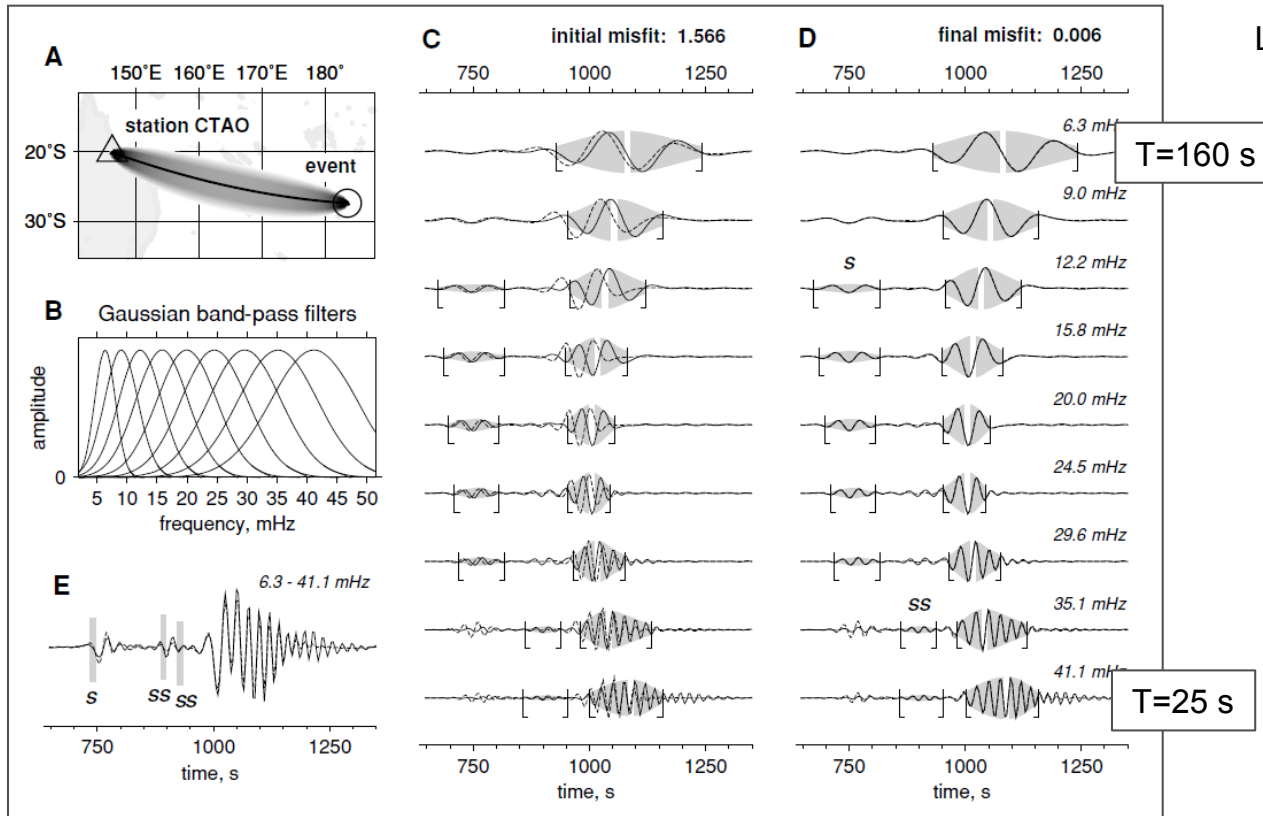
Traditional Approach to Tomography

DATA (Massive Sensor Networks;
Signal from Earthquakes)

**ballistic (source-to-receiver) wave
propagation**

Tomography
(Asymptotic or Full-Wave)
(Body waves, surface waves)

3-D Velocity Model that
best explains data

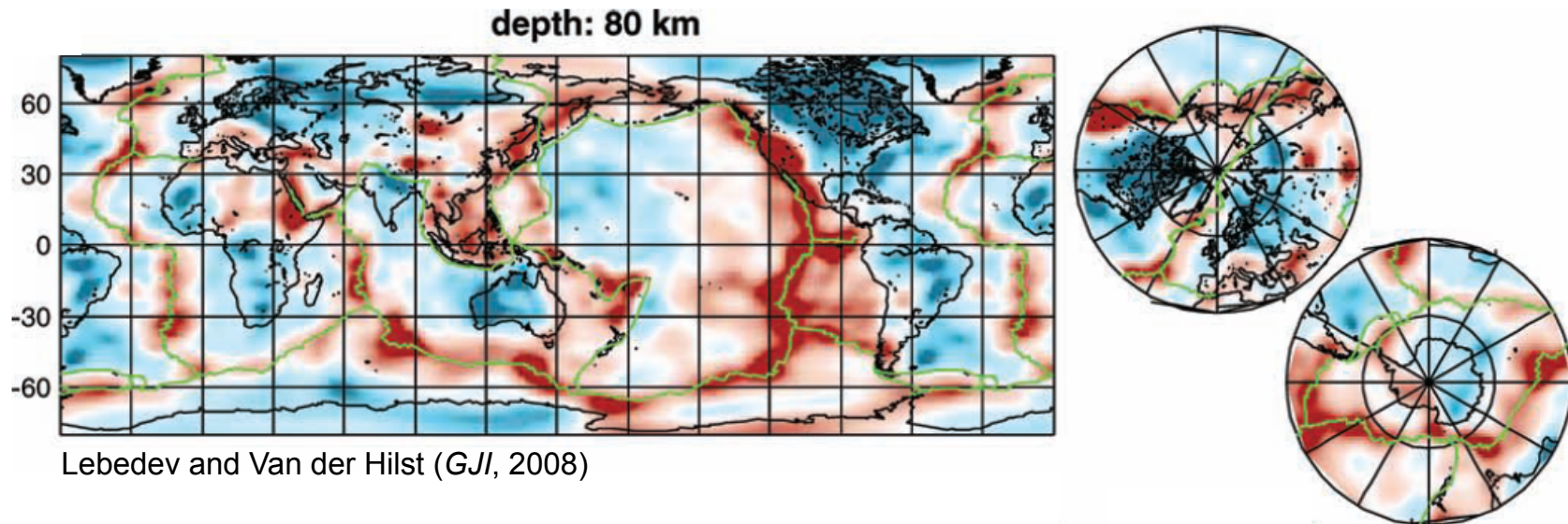
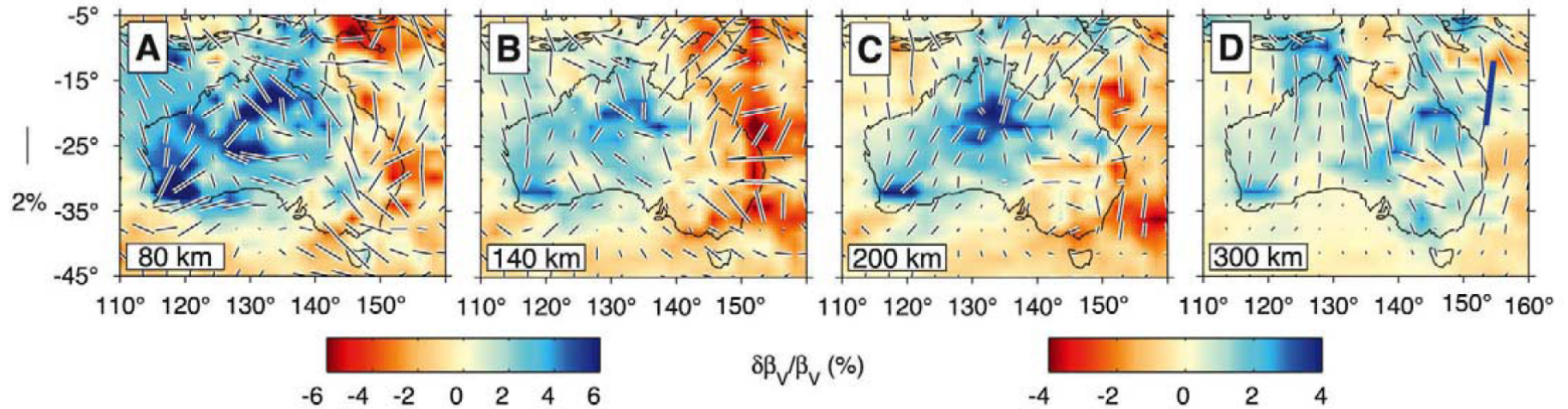


Crust = Problem!

Examples from traditional surface wave tomography with earthquake waves: relatively low frequencies → deep structures

T > 30 s → upper mantle

Simons and Van der Hilst (*EPSL*, 2008)



Lebedev and Van der Hilst (*GJI*, 2008)

Ambient Noise Tomography

DATA (Massive Sensor Networks;
background noise)

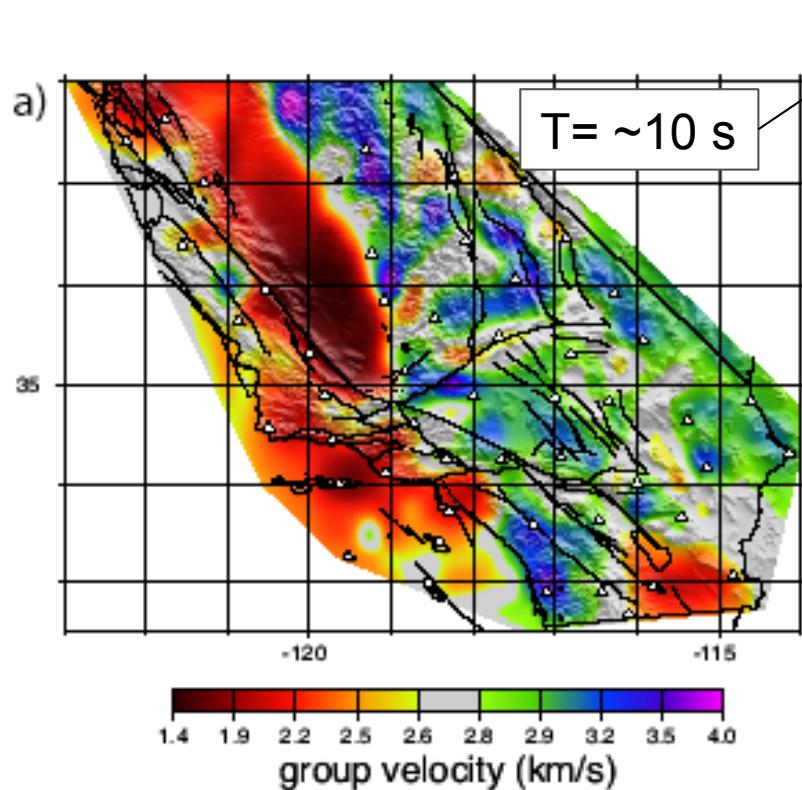
Alternative:
“sourceless” imaging/tomography

create data by means of
interferometry/cross-correlation

Tomography
(Asymptotic or Full-Wave)
(Body waves, surface waves)

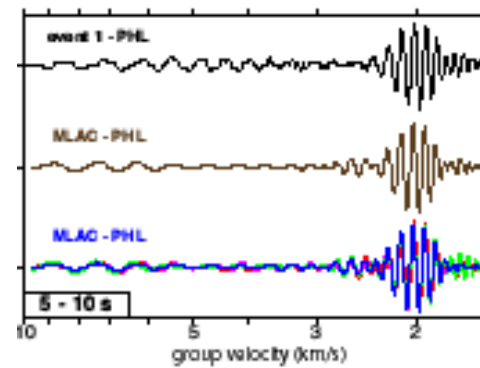
3-D Velocity Model that
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Shapiro, N.M., M. Campillo, L. Stehly, and M.H. Ritzwoller, 2005, High-Resolution Surface-Wave Tomography from Ambient Seismic Noise: *Science* **307**:1615-1618



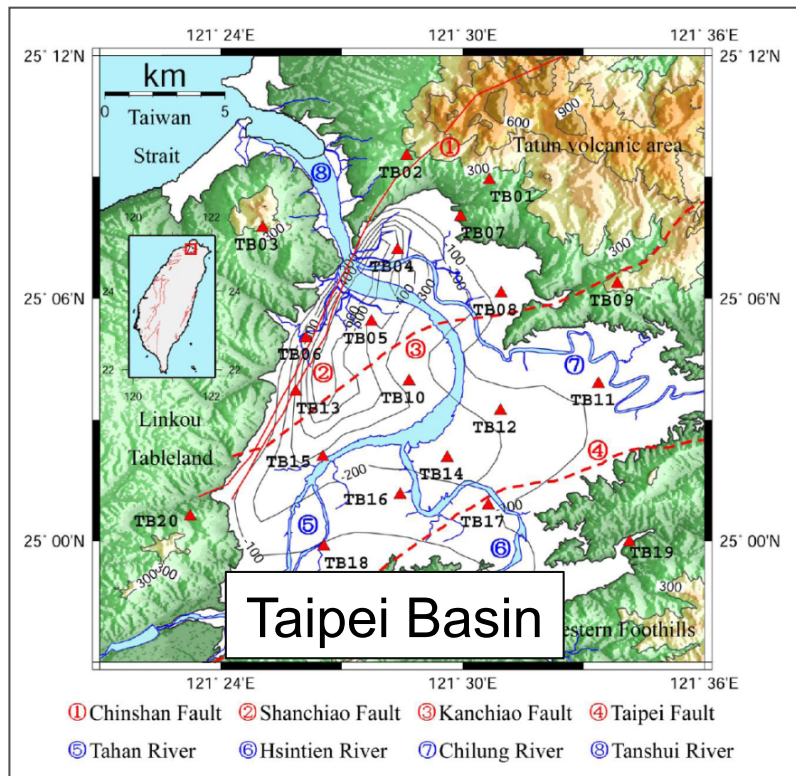
A map of Surface-wave Velocity in California

Obtained from correlating seismic noise

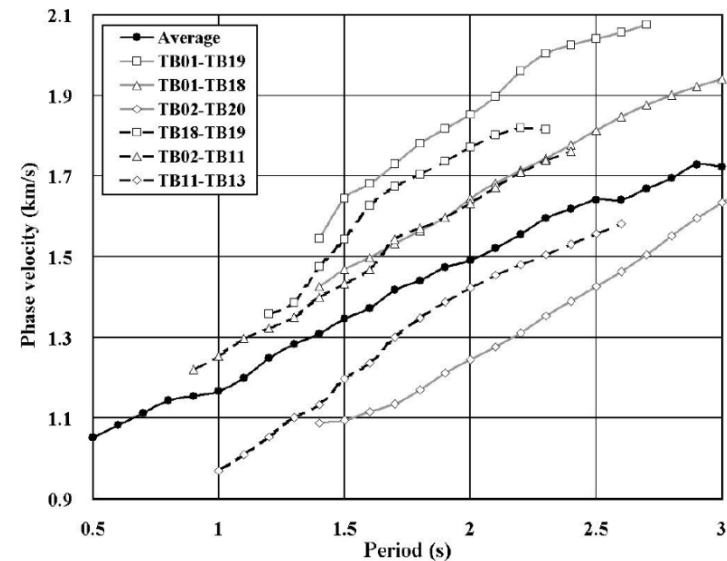
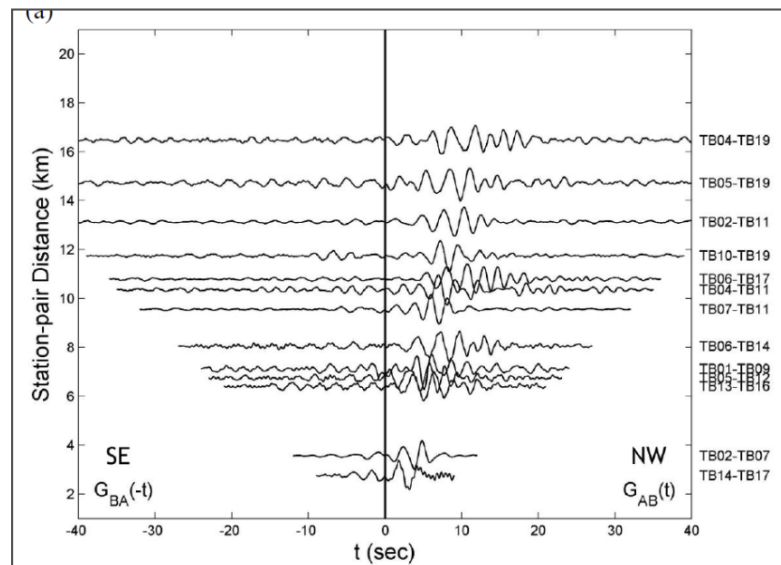
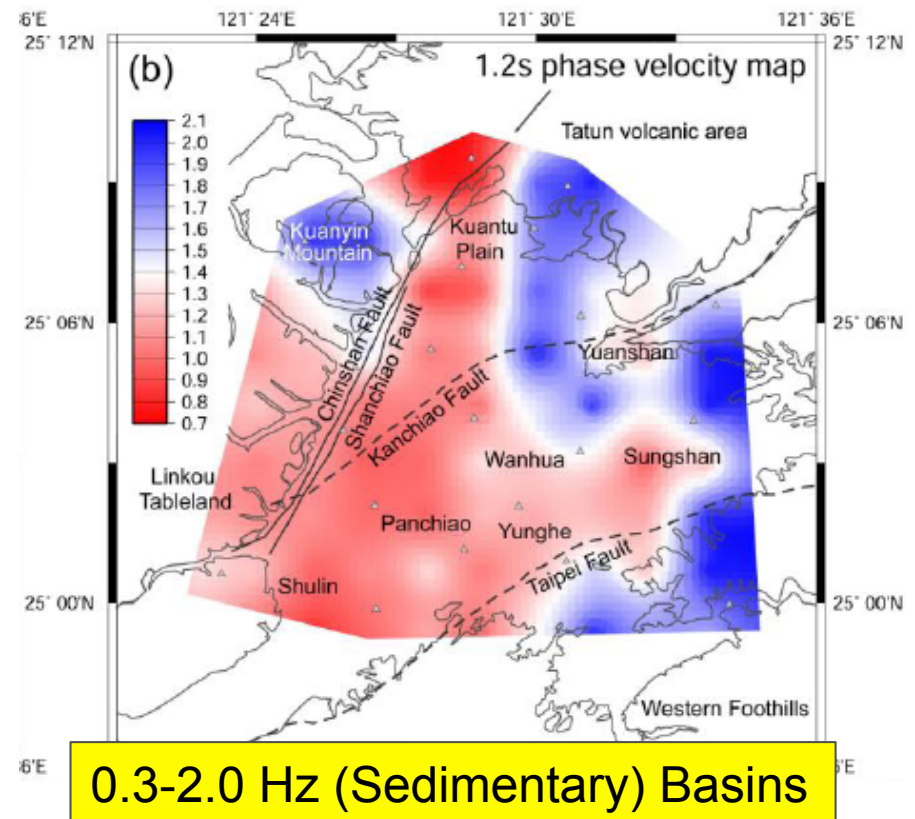


earthquake
1 year of correlations
4 one-month correlations

also Sabra, et al Surface wave tomography from microseisms in Southern California
Geophys Res Lett **32** (2005)



Huang et al. (BSSA, 2010)



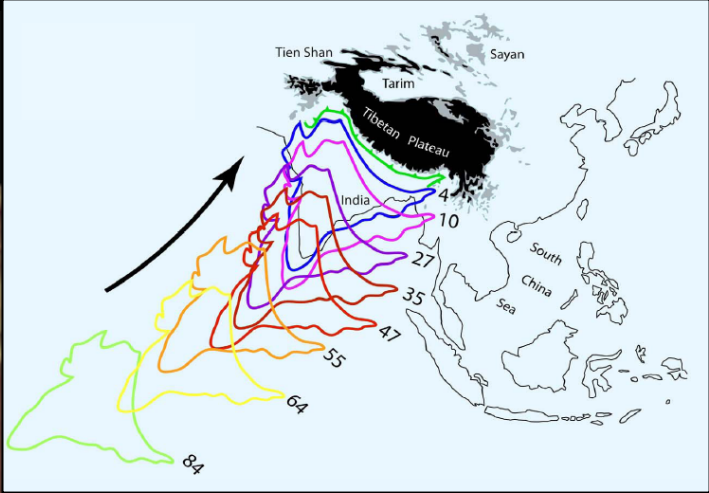
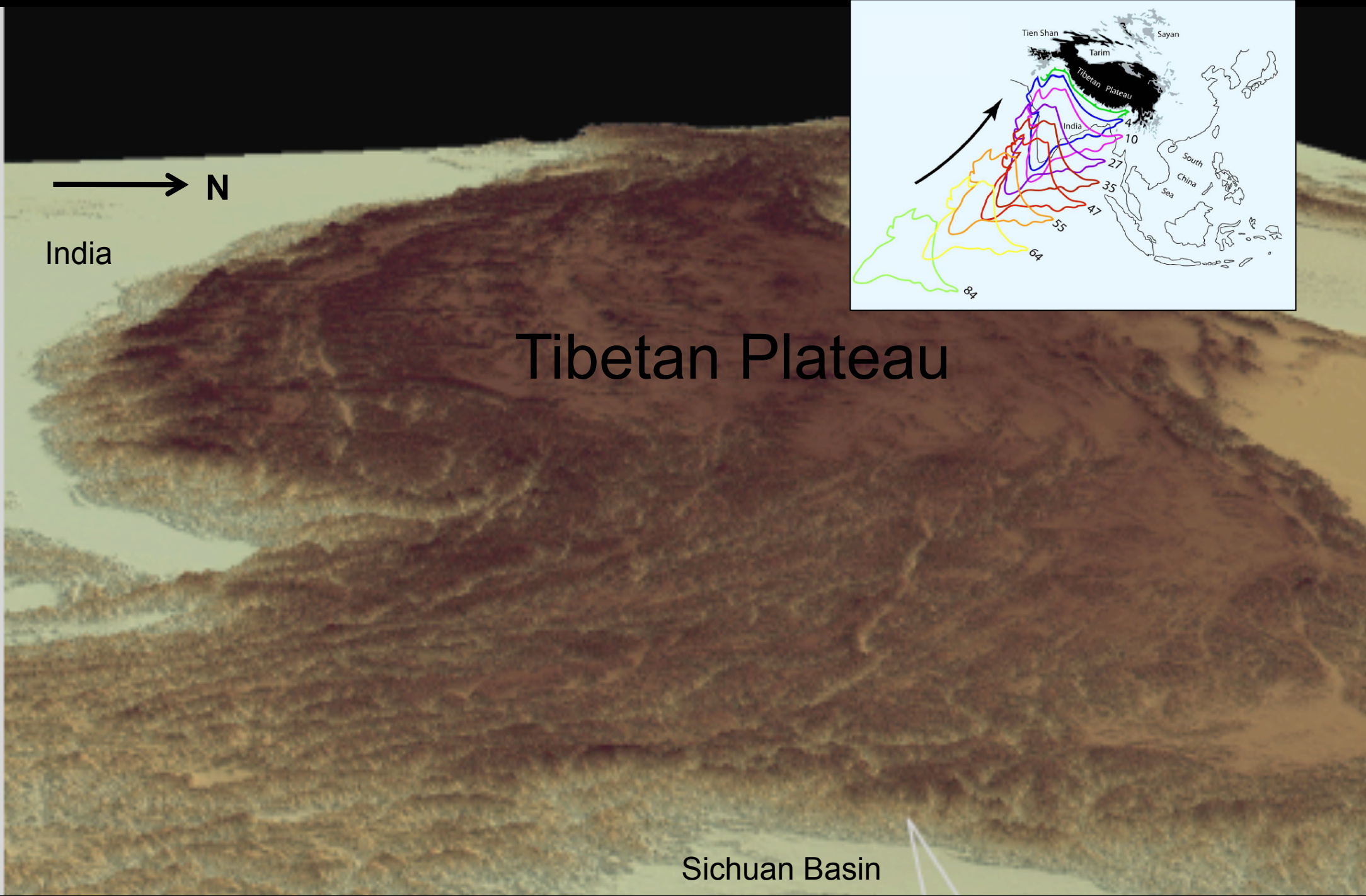
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Boundaries are blurring
 broader frequency bandwidth →
 larger depth rang
 (when arrays are available ...)
 Surface geology ↔ Deeper dynamic processes

Field Projects Sichuan & Yunnan Provinces and E. Tibet (2003-2004)

Crust-Mantle study E Tibet – SW China





Tibetan Plateau

→ N

India

Sichuan Basin

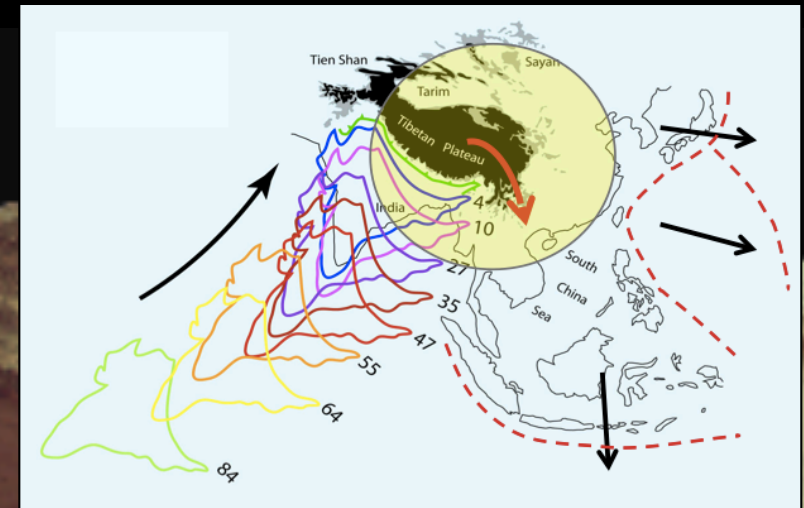
Why SE Tibet?

1. understanding eastward expansion of plateau

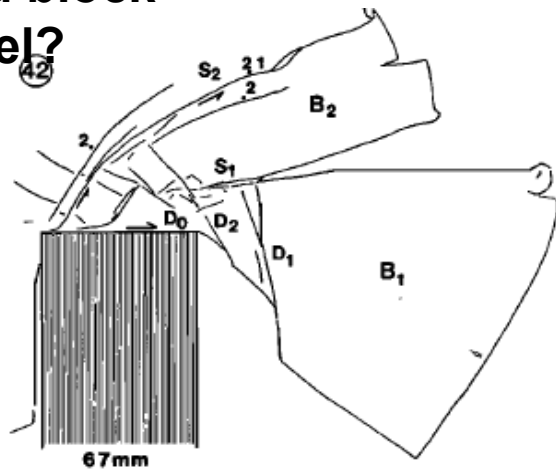
→ N

India

Tibetan Plateau

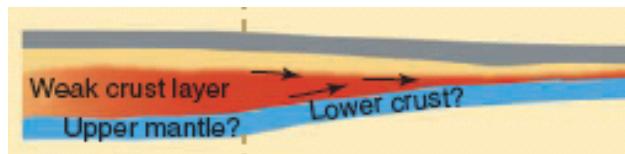


Rigid block model?



Peltzer and Tapponnier (1988)

Crustal (channel) flow?

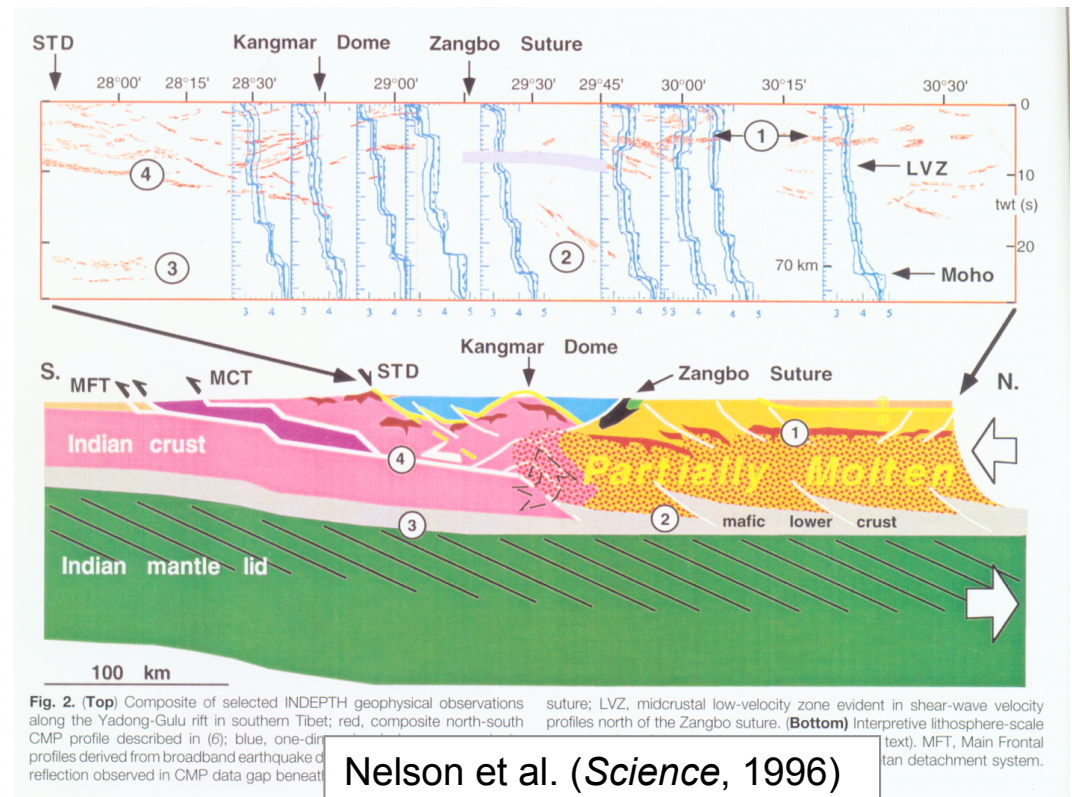


Royden et al. (1996)

How does this work?

Rigid blocks? Crustal flow?

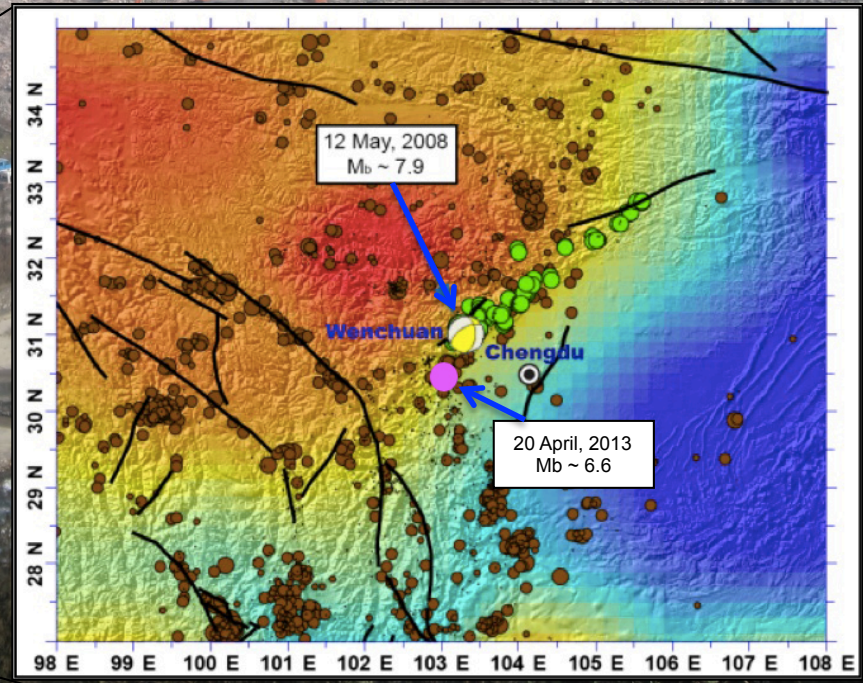
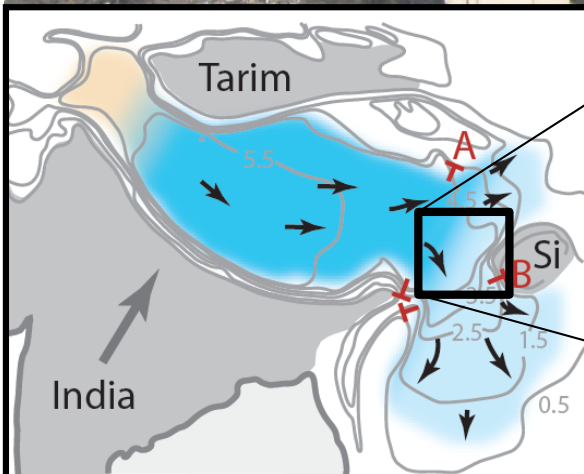
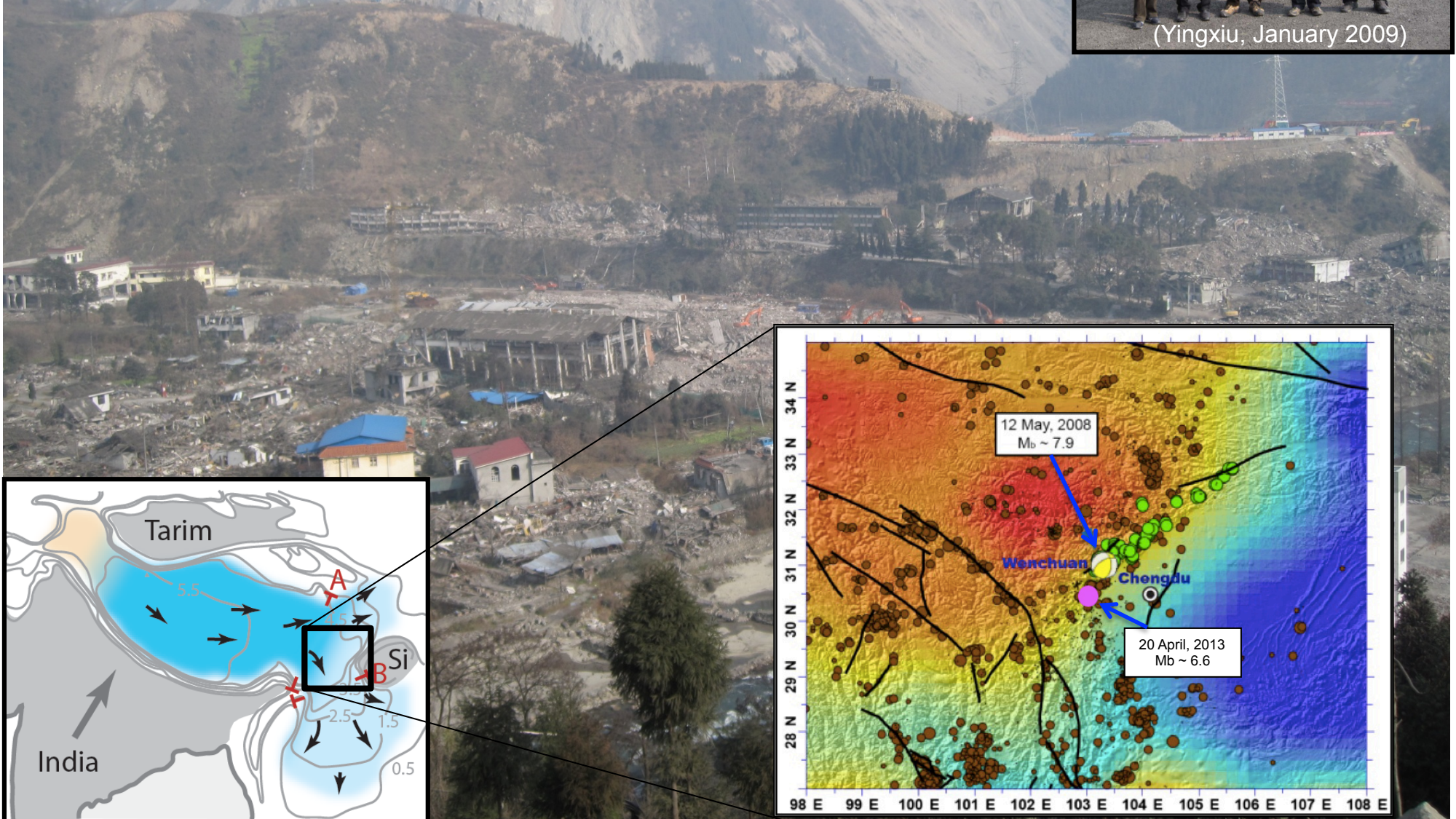
Need to know structure of the crust!



Why SE Tibet?

2. Southern end of Trans China Seismicity Belt

E.g. Sichuan, 12 May 2008
~80,000 people killed ...



Overview of lecture:

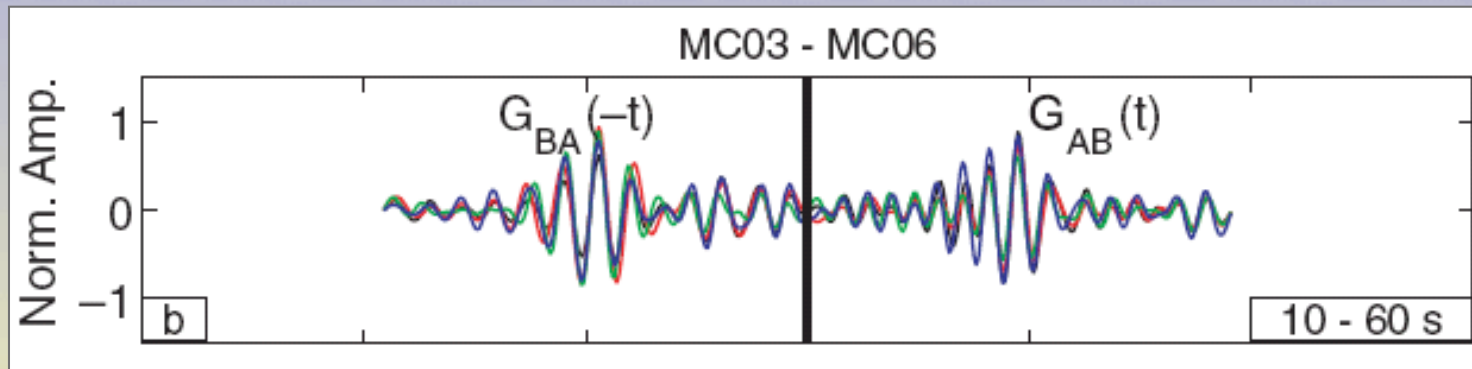
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3. Reverse time migration of converted waves
4. Interferometry of teleseismic (coda) waves

Interferometry:

long-term noise correlation \rightarrow new data
for crustal tomography

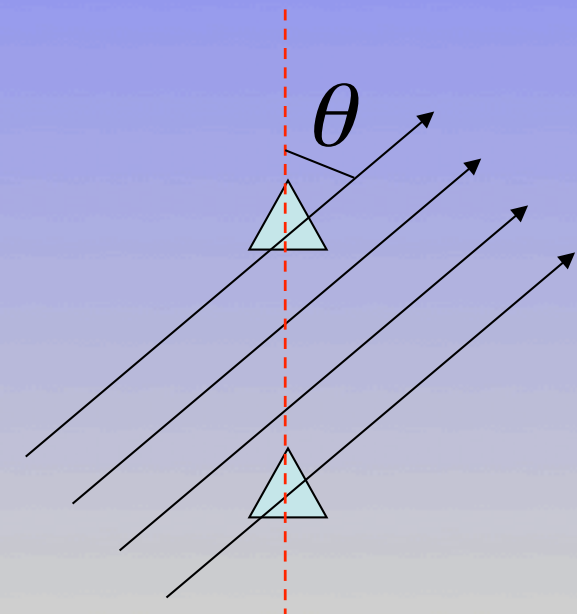
$$\frac{dC_{AB}(t)}{dt} \approx -\hat{G}_{AB}(t) + \hat{G}_{BA}(-t) \approx -G_{AB}(t) + G_{BA}(-t).$$

G = Green's function



Yao et al. (*GJI*, 2006)

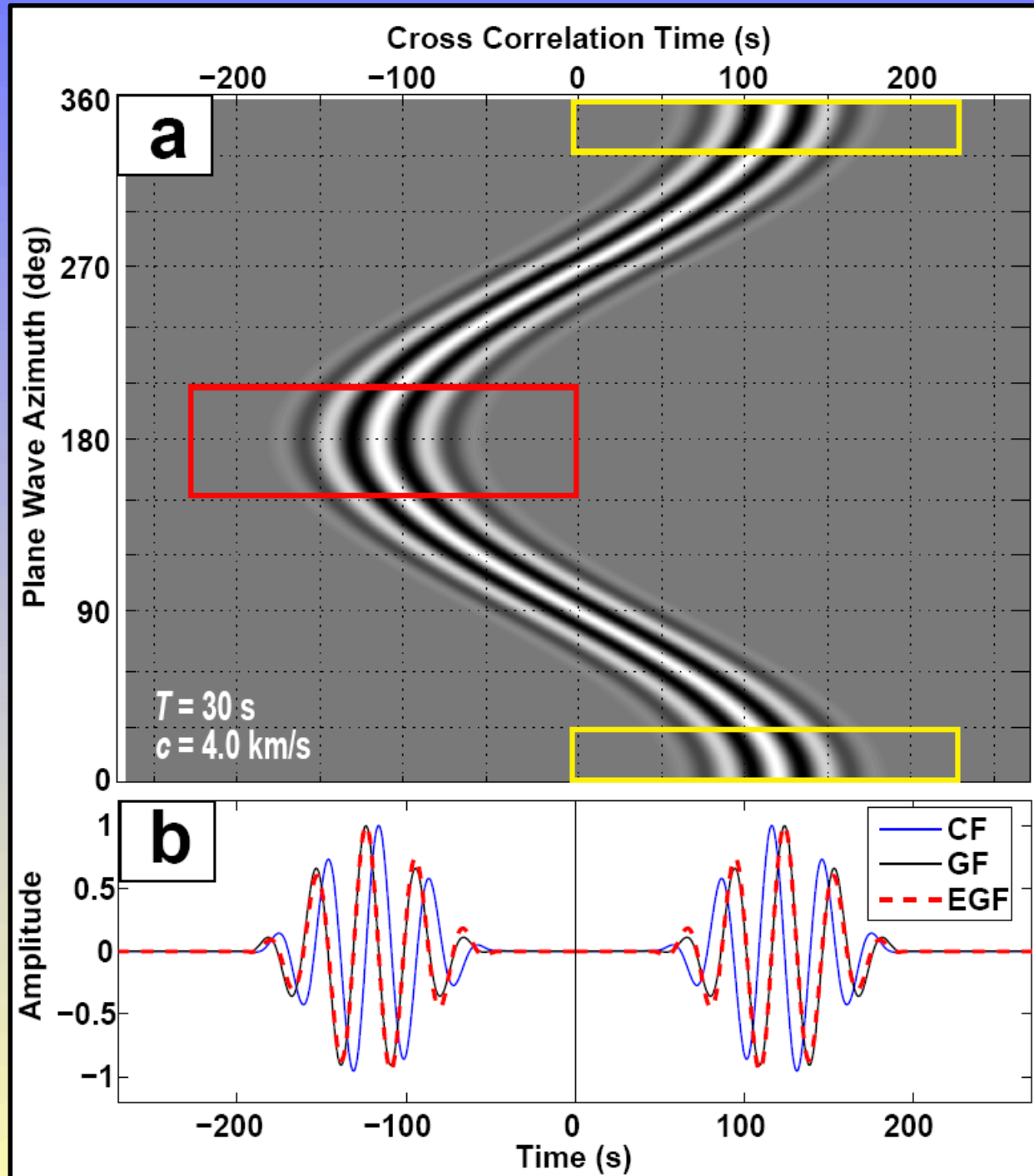
Recovery of surface waves (2D case)



Homogen. + iso medium

isotropic incident plane wave

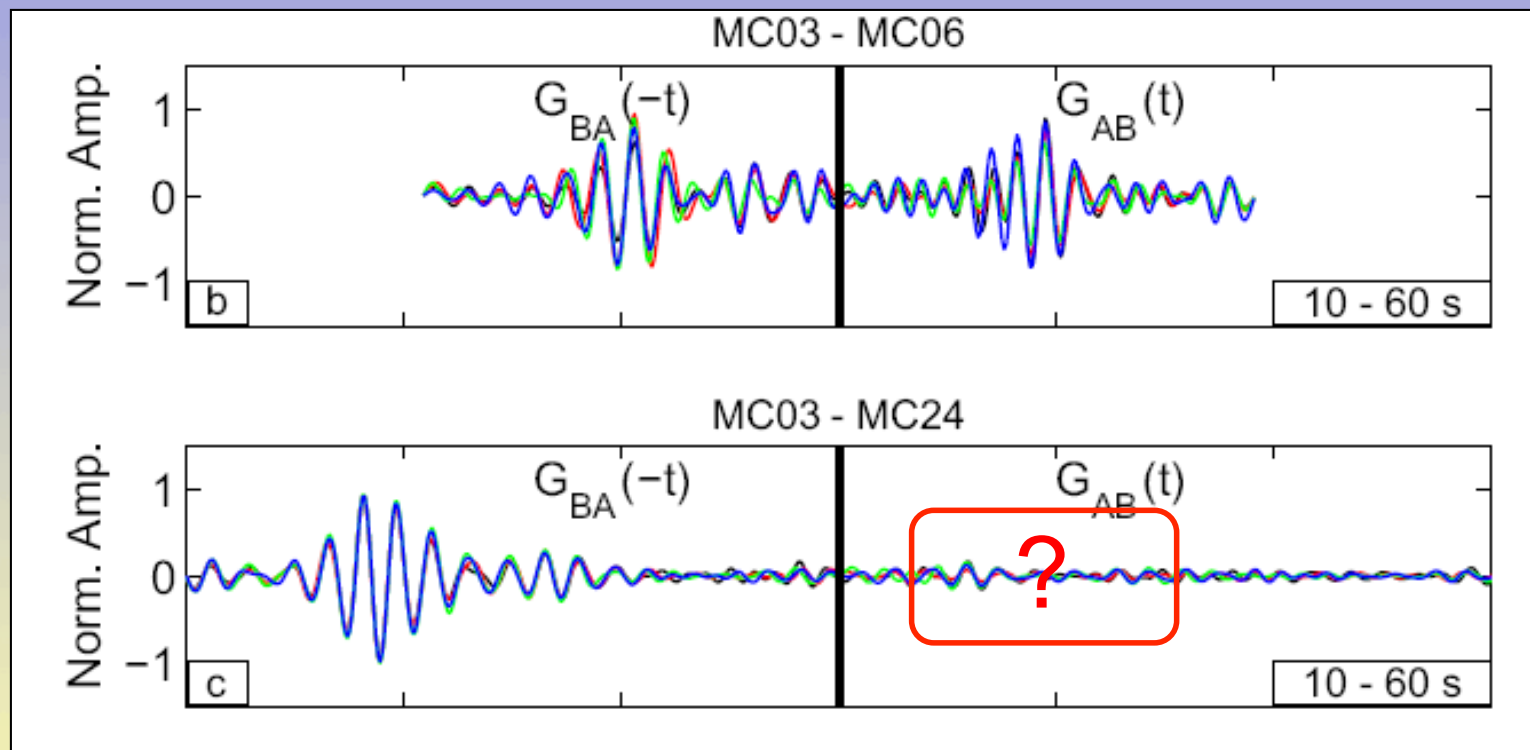
Yao & Van der Hilst (2009)



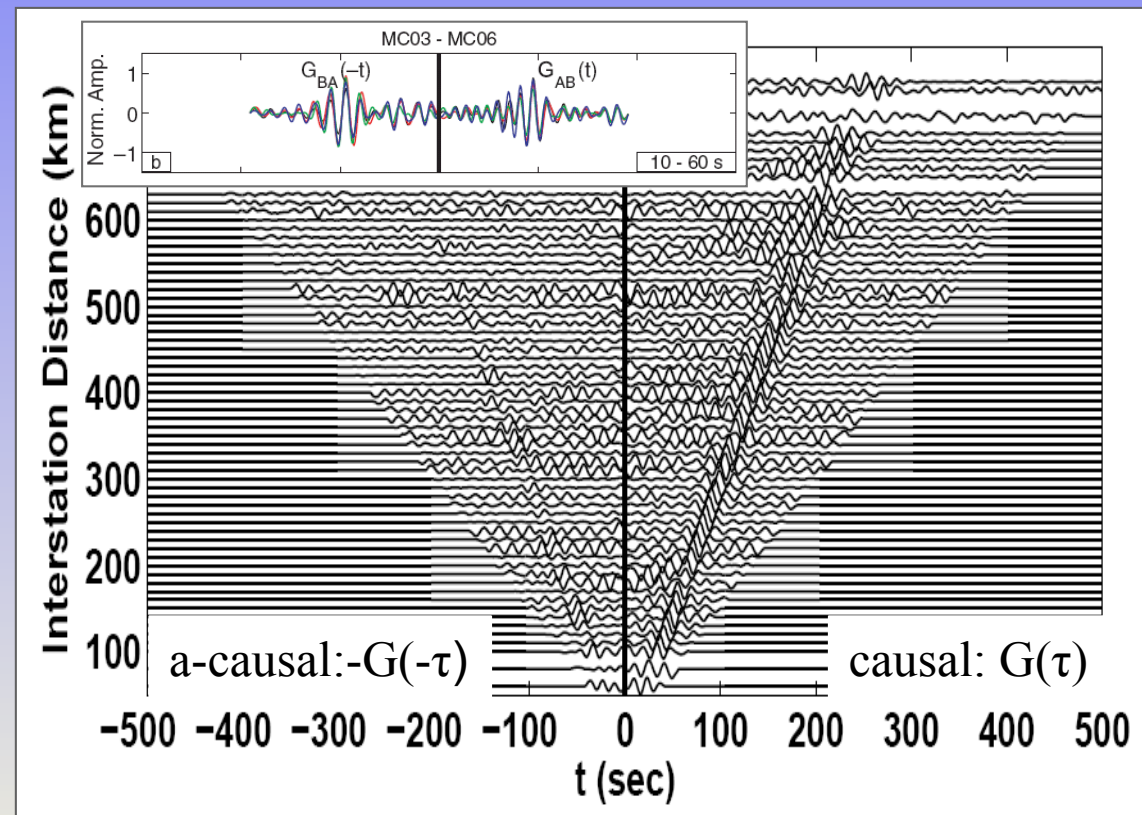
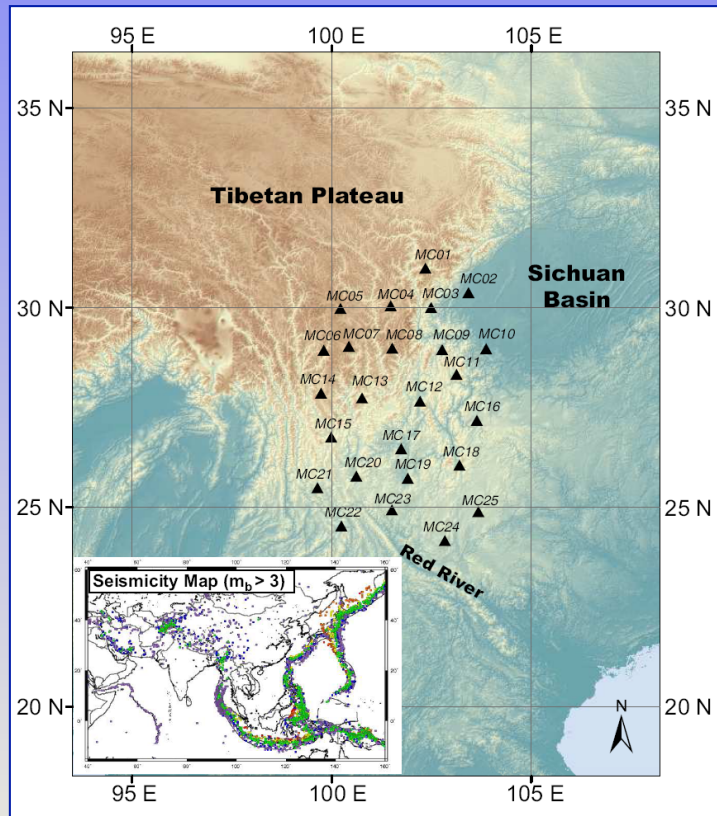
Interferometry:

long-term noise correlation \rightarrow new data
for crustal tomography

(simple in concept, but devil is in the detail ...)



Crust and Lithosphere: Multi-resolution surface wave tomography

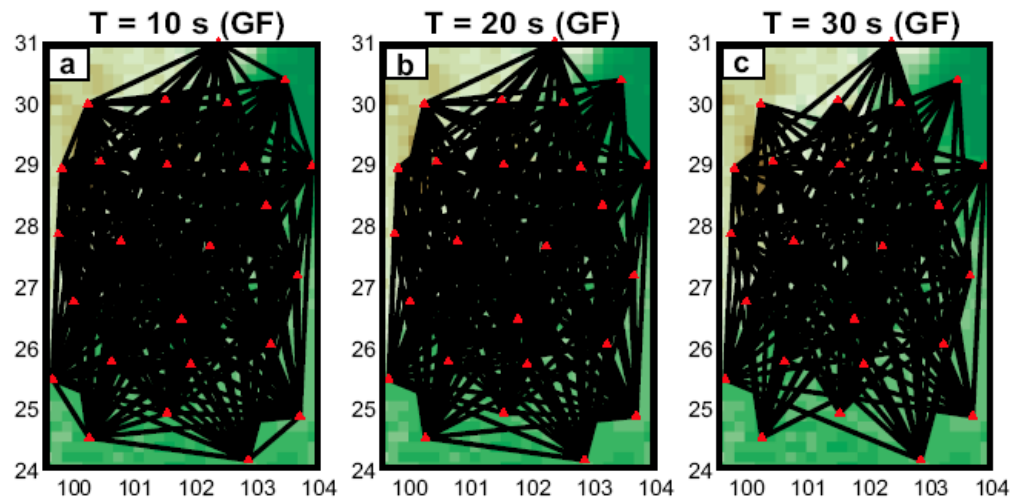


Seismic interferometry → estimate data from background

“noise”

(NB we ignore asymmetry and sum causal and a-causal signals)

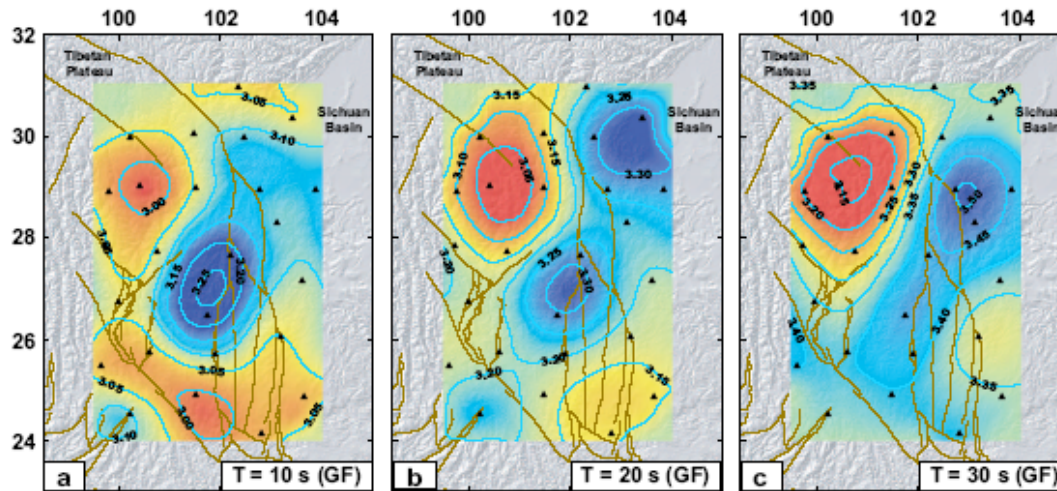
Example: “ambient noise” surface wave tomography



“source”-receiver pairs at different periods

Interferometry (scattering) \rightarrow works well for relatively short periods (high frequency)

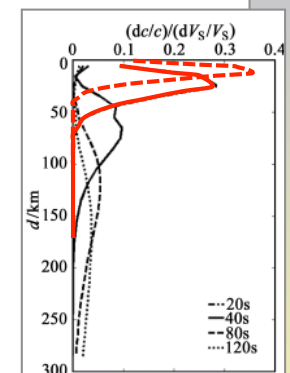
Example: “ambient noise” surface wave tomography



Phase velocity maps at different periods

Interferometry (scattering) → relatively short periods (high frequency)

For surface wave tomography that means: “shallow” sub-surface



Use both 'active' and 'passive' data

DATA (Massive Sensor Networks;
earthquakes AND background noise)

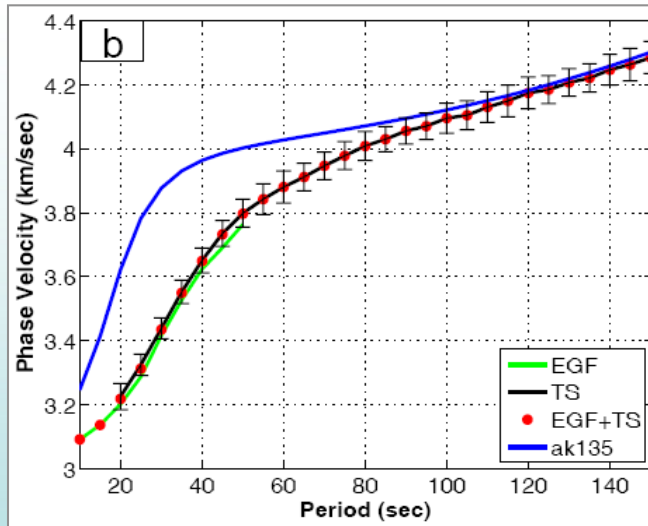
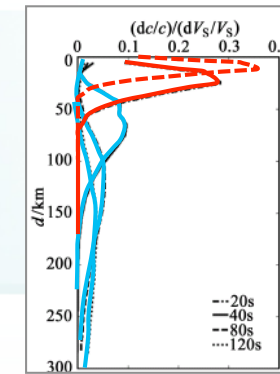
**ballistic (source-to-receiver) wave
propagation**

**create data by means of
interferometry/cross-correlation**

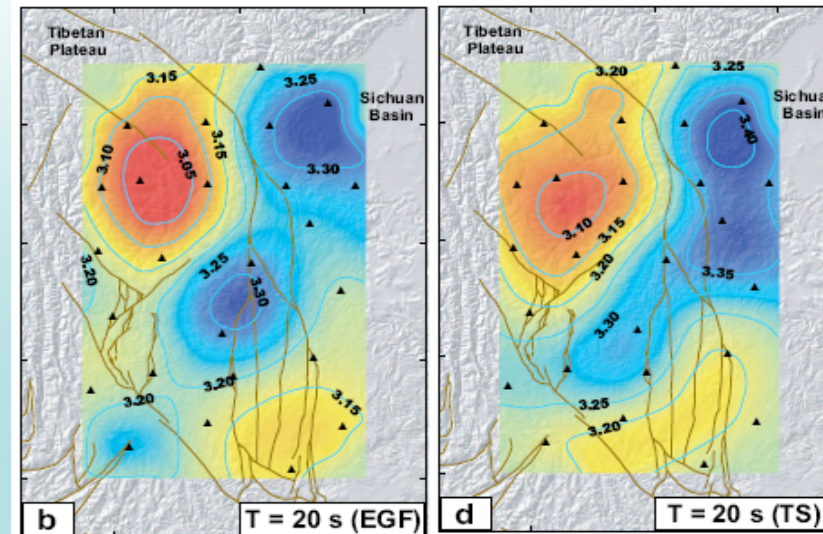
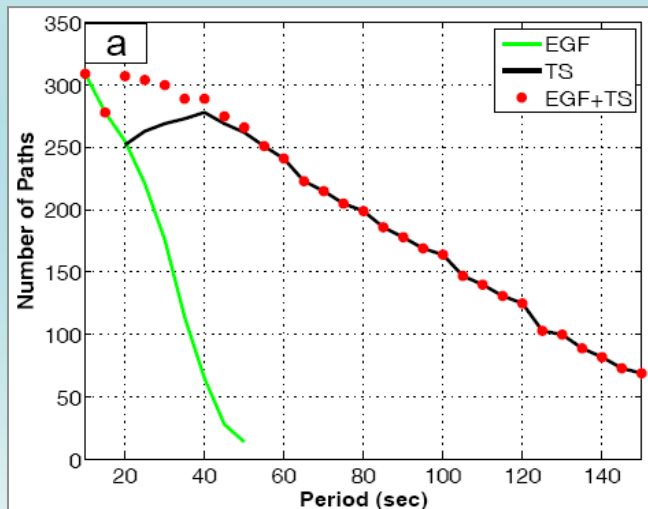
Tomography
(Asymptotic or Full-Wave)
(Body waves, surface waves)

3-D Velocity Model that
best explains data

Combination of ambient noise and earthquake data: extend frequency range → extend depth range

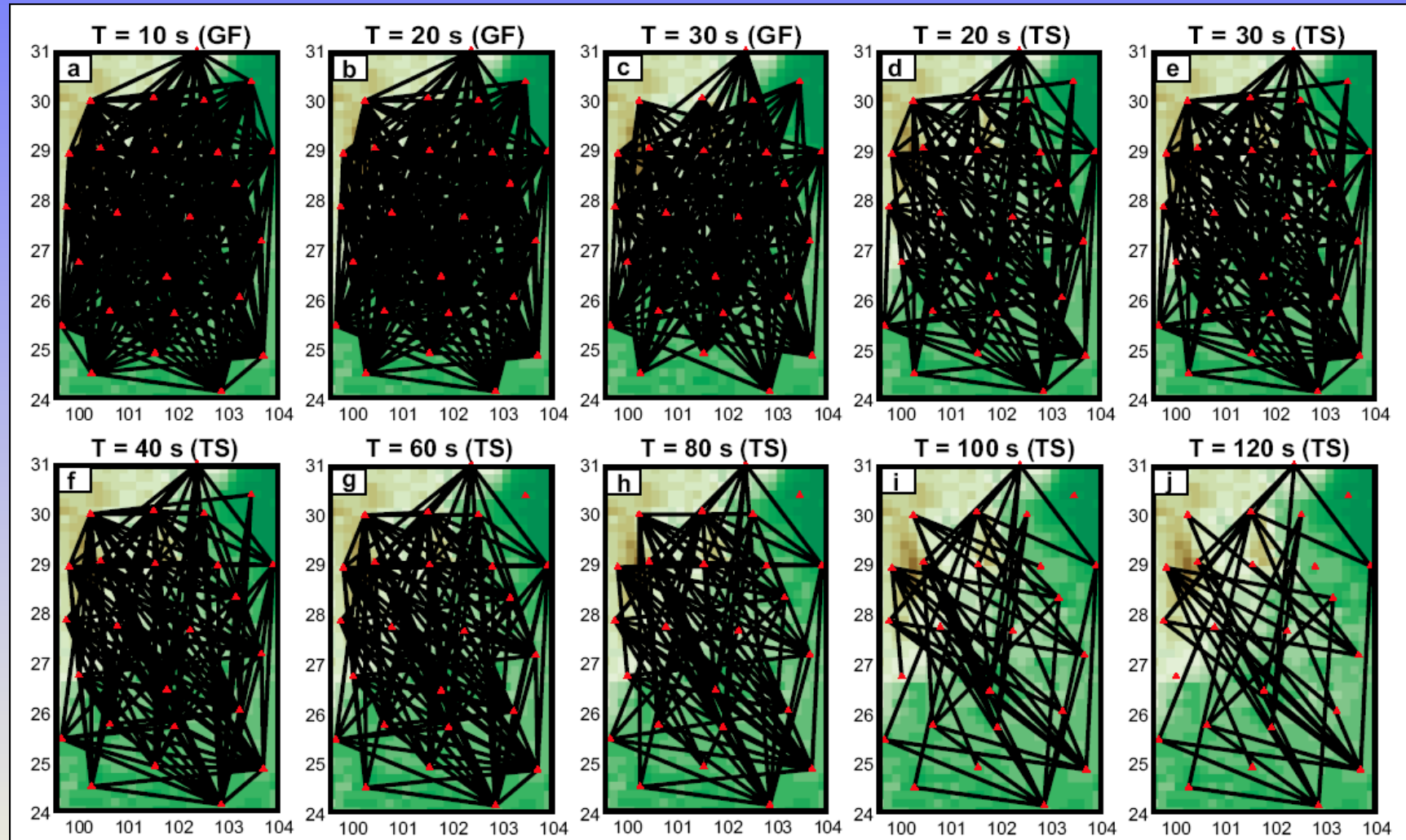


At overlapping periods, Rayleigh wave phase velocities from EGF (from 10 months Z-comp. data) and TS analyses are similar



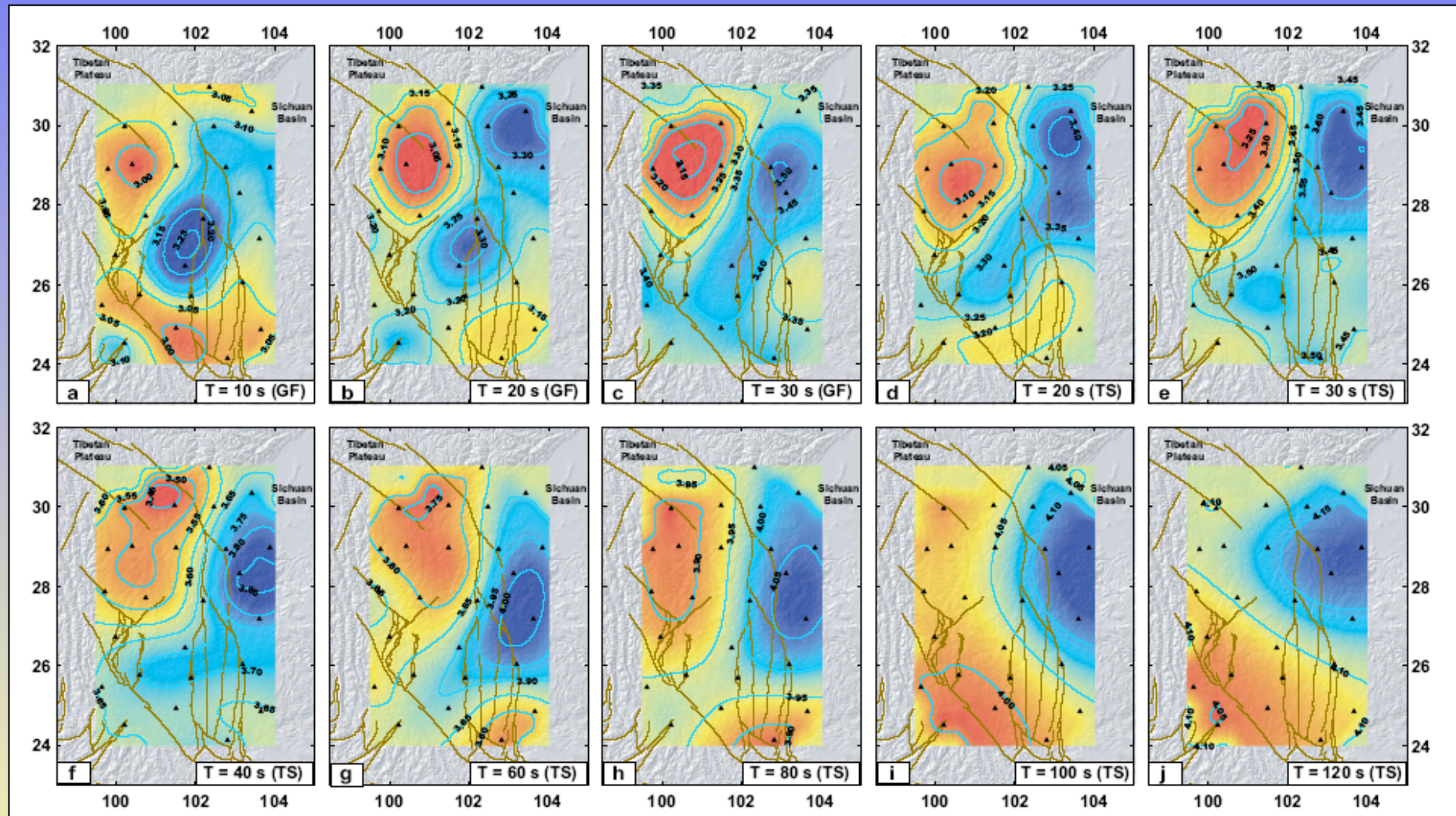
- TS slightly higher (< 0.7%) due to differences in finite frequency effect
- Difference << medium perturbations (< 10%)

Multi-resolution surface wave tomography



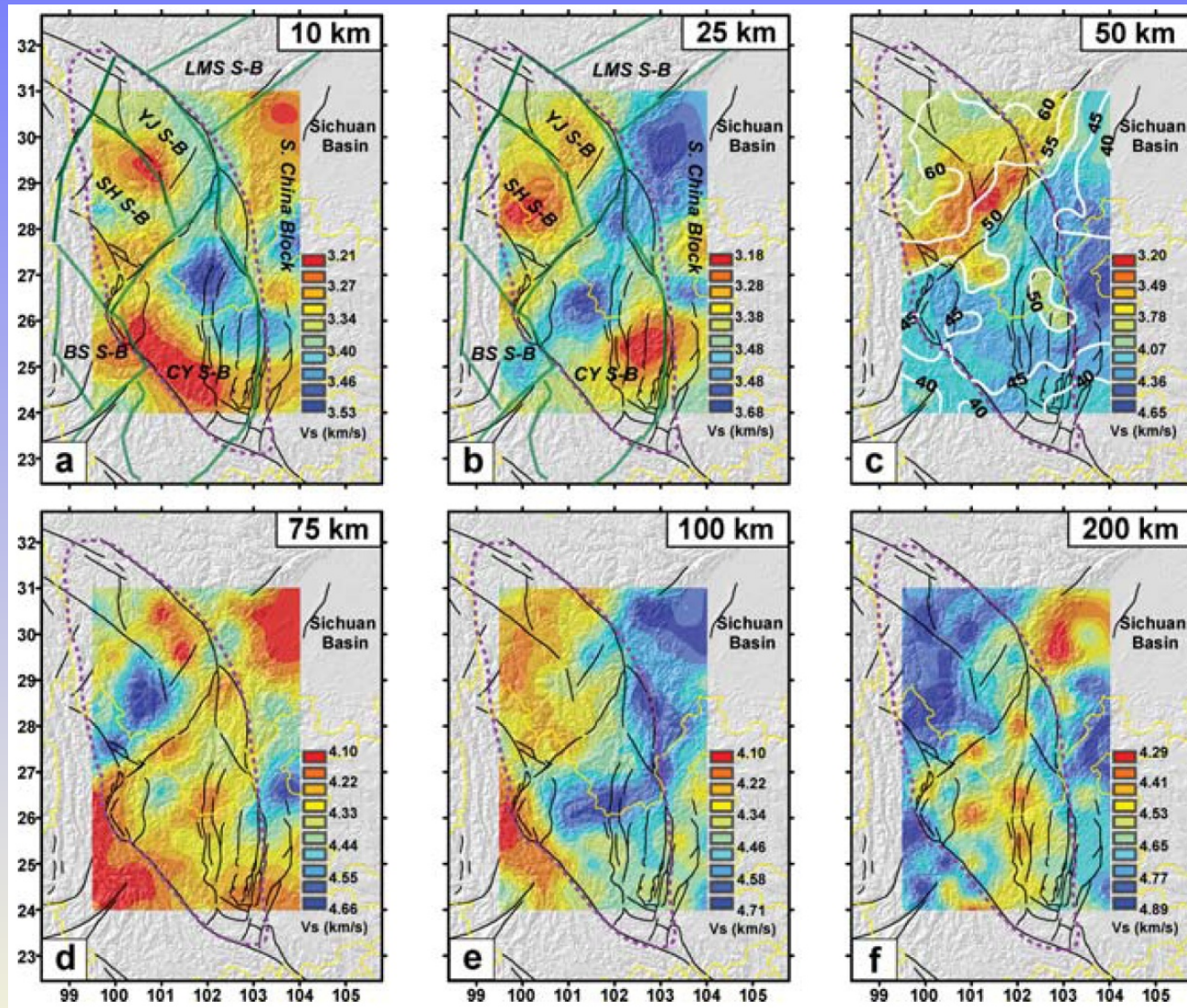
Yao, Van der Hilst, and De Hoop (*GJI*, 2006)

Phase velocity maps at different periods



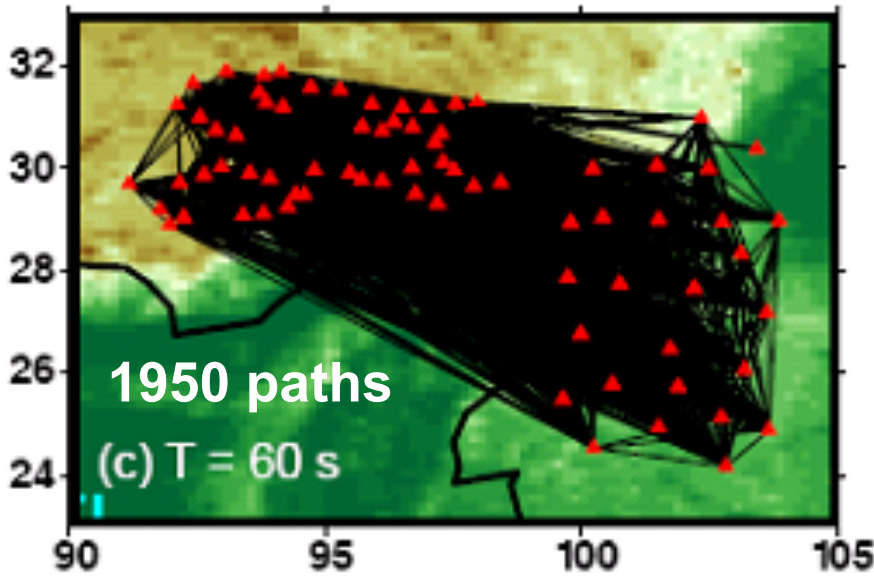
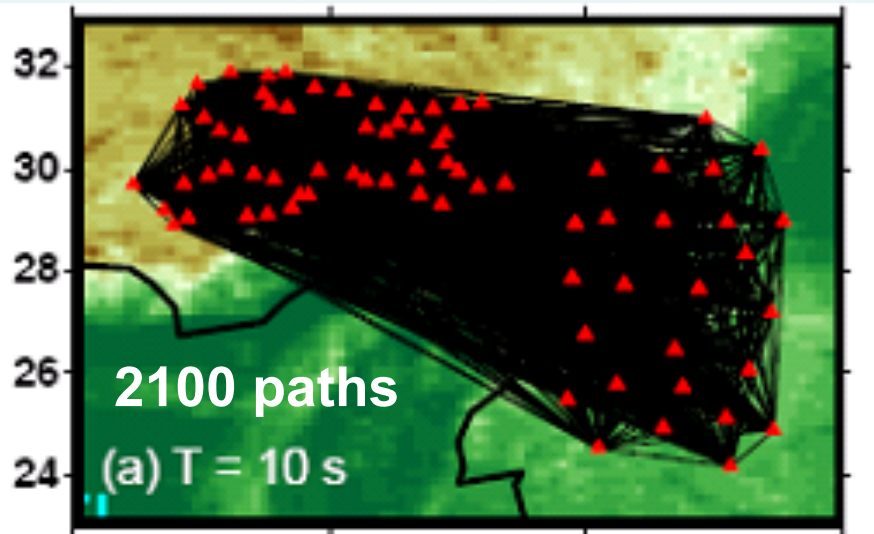
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Multi-resolution surface wave tomography

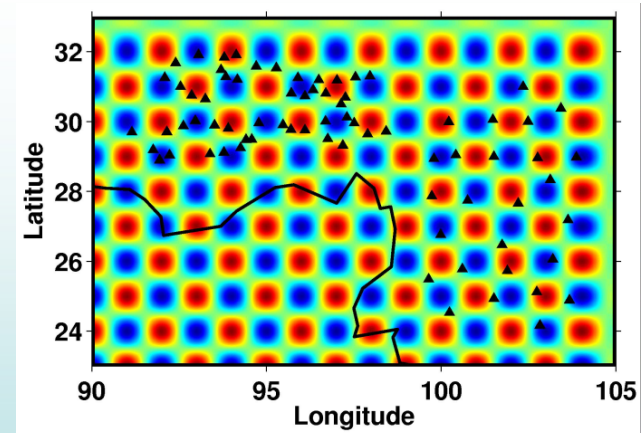


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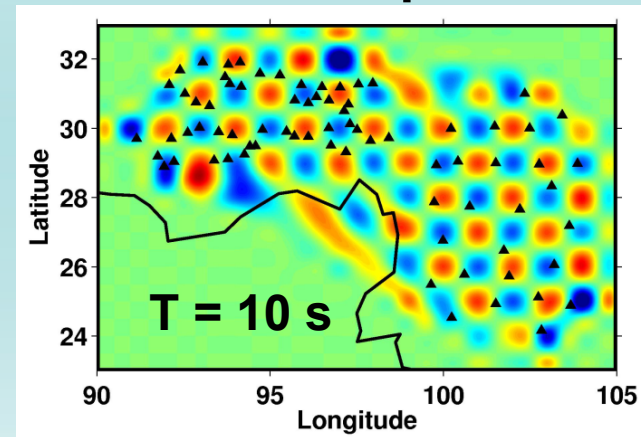
Path coverage and lateral resolution of phase velocity maps



$1^\circ \times 1^\circ$ input

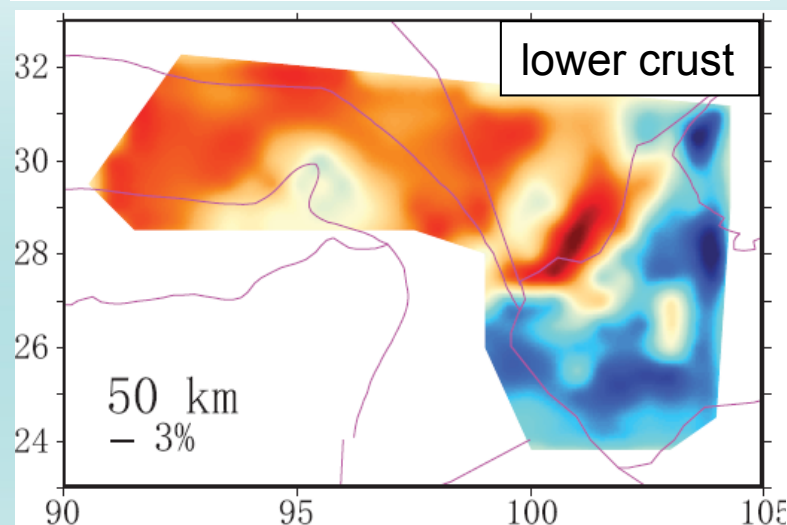
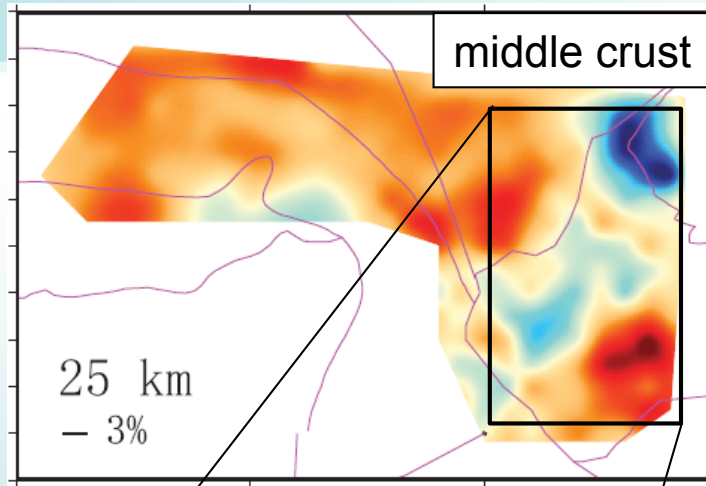
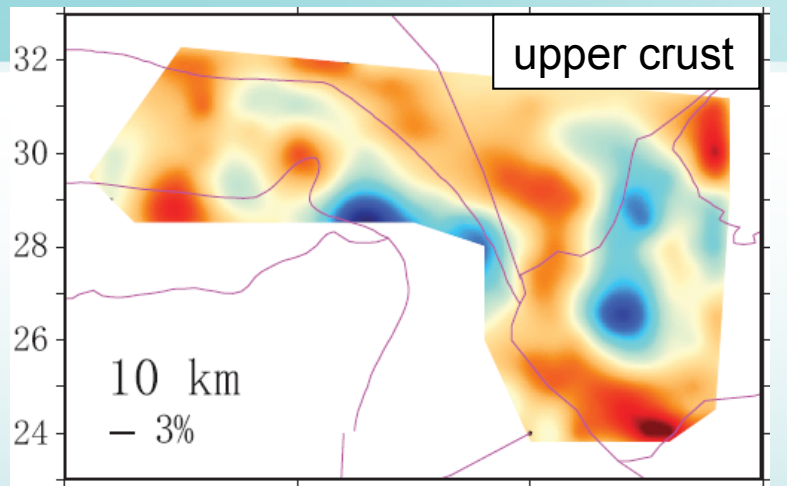


$1^\circ \times 1^\circ$ output

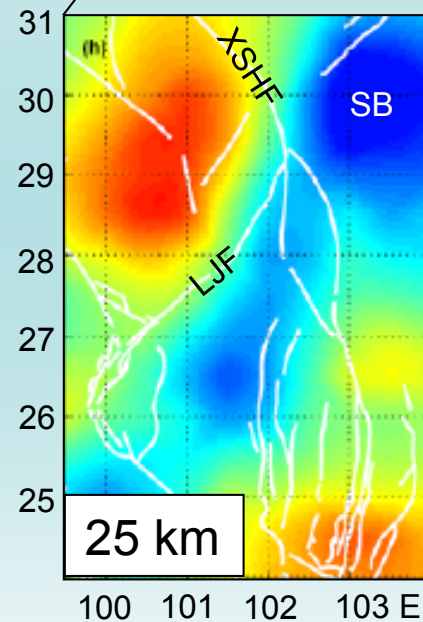


Horizontal resolution ~ 100 km

Crustal wavespeeds in SE Tibet and Sichuan Province (from Ambient Noise – Rayleigh wave – tomography)



slow fast

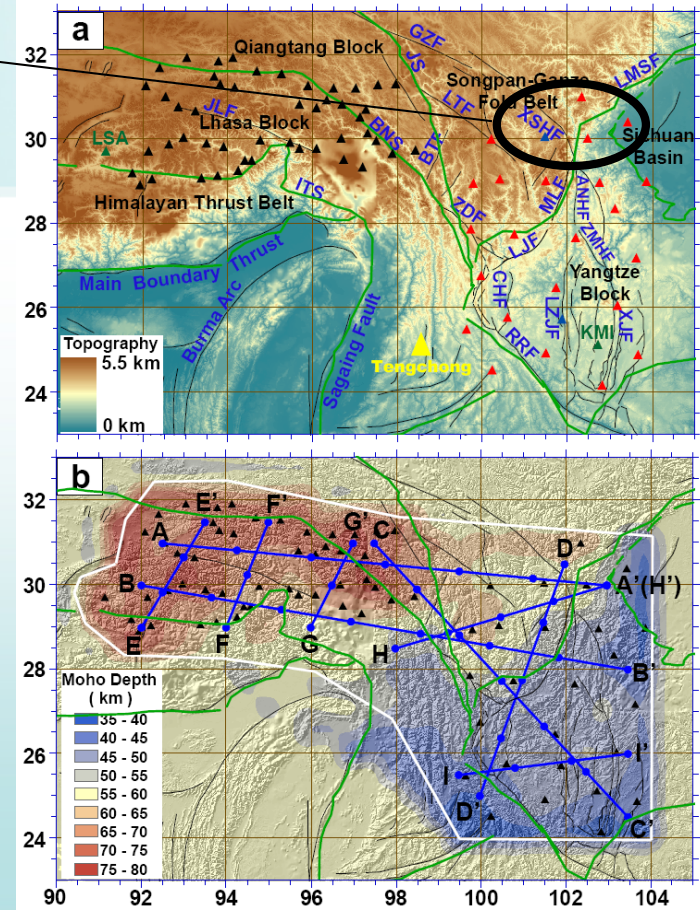


Complex 3D pattern of
low velocity layers

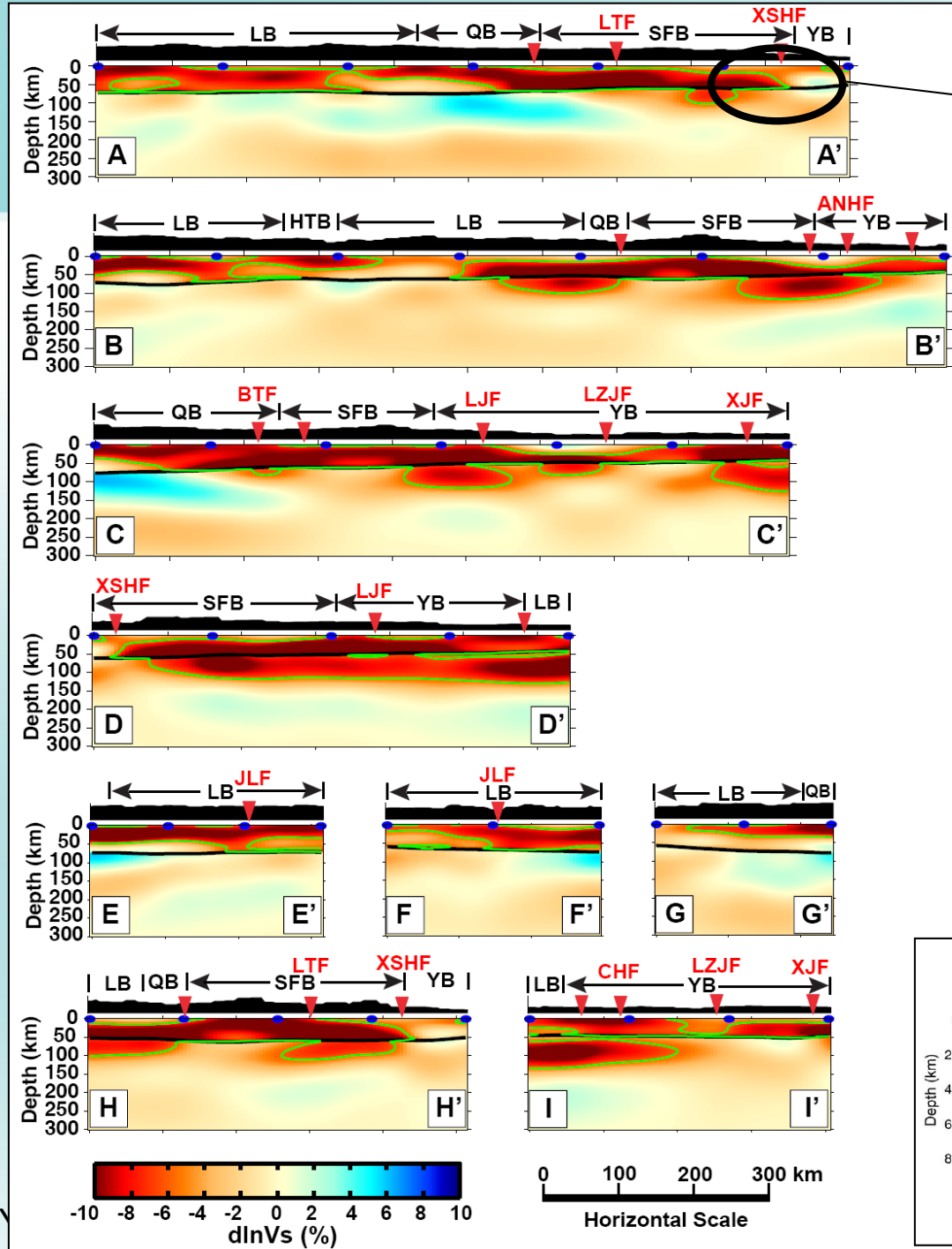
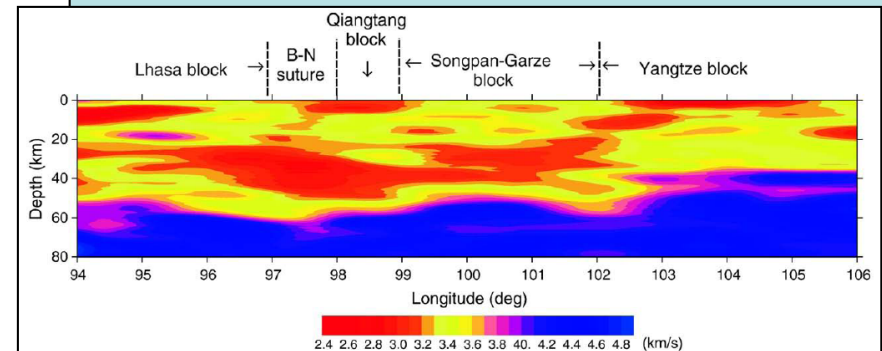
Yao, Van der Hilst, and Montagner (*JGR*, 2010)

Huang, Yao, Van der Hilst (*GRL*, 2010)
(average Love-Rayleigh speed)

Yao, Van der Hilst, and Montagner (JGR, 2010)

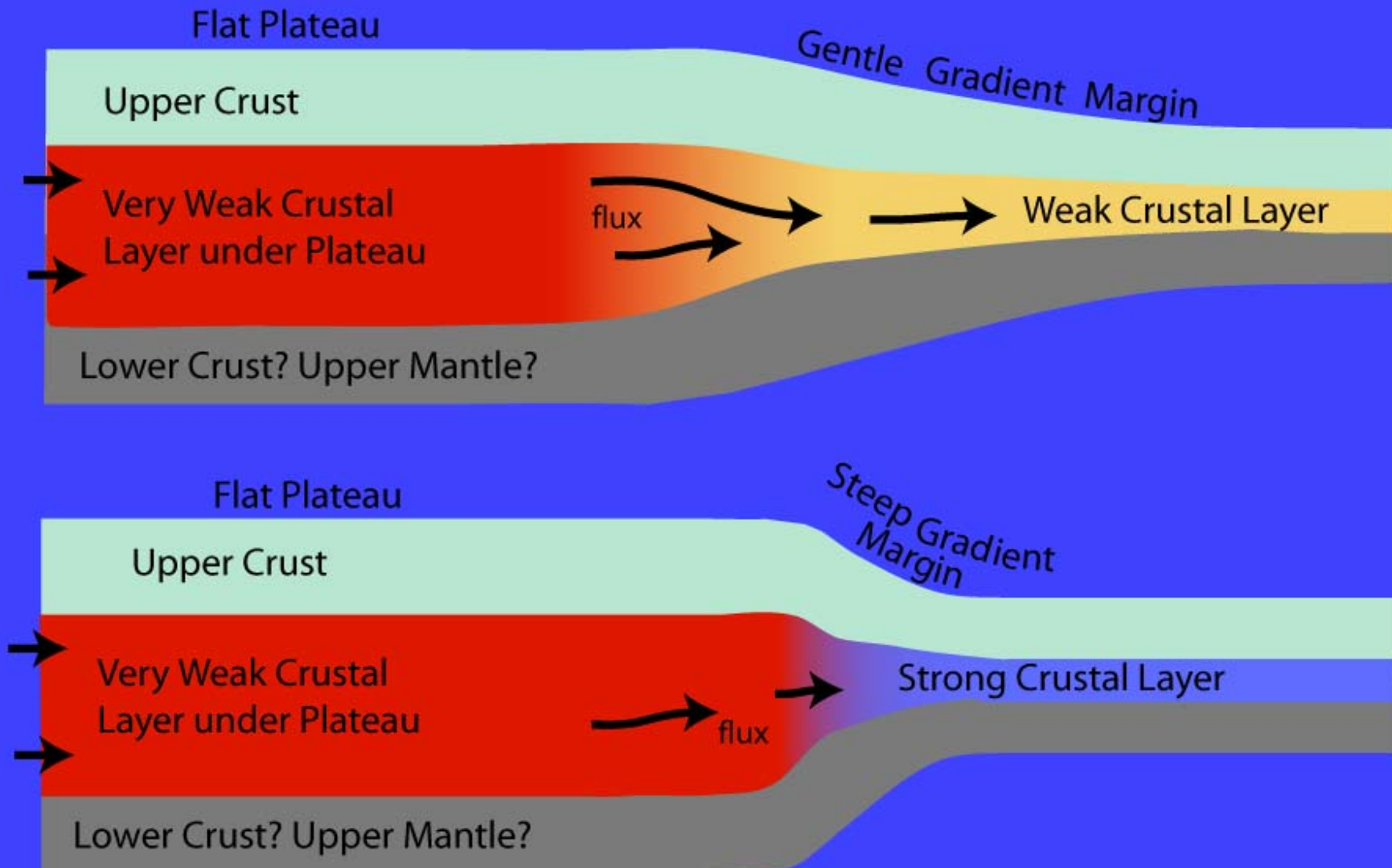


Receiver Functions – Wang et al. (EPSL, 2010)

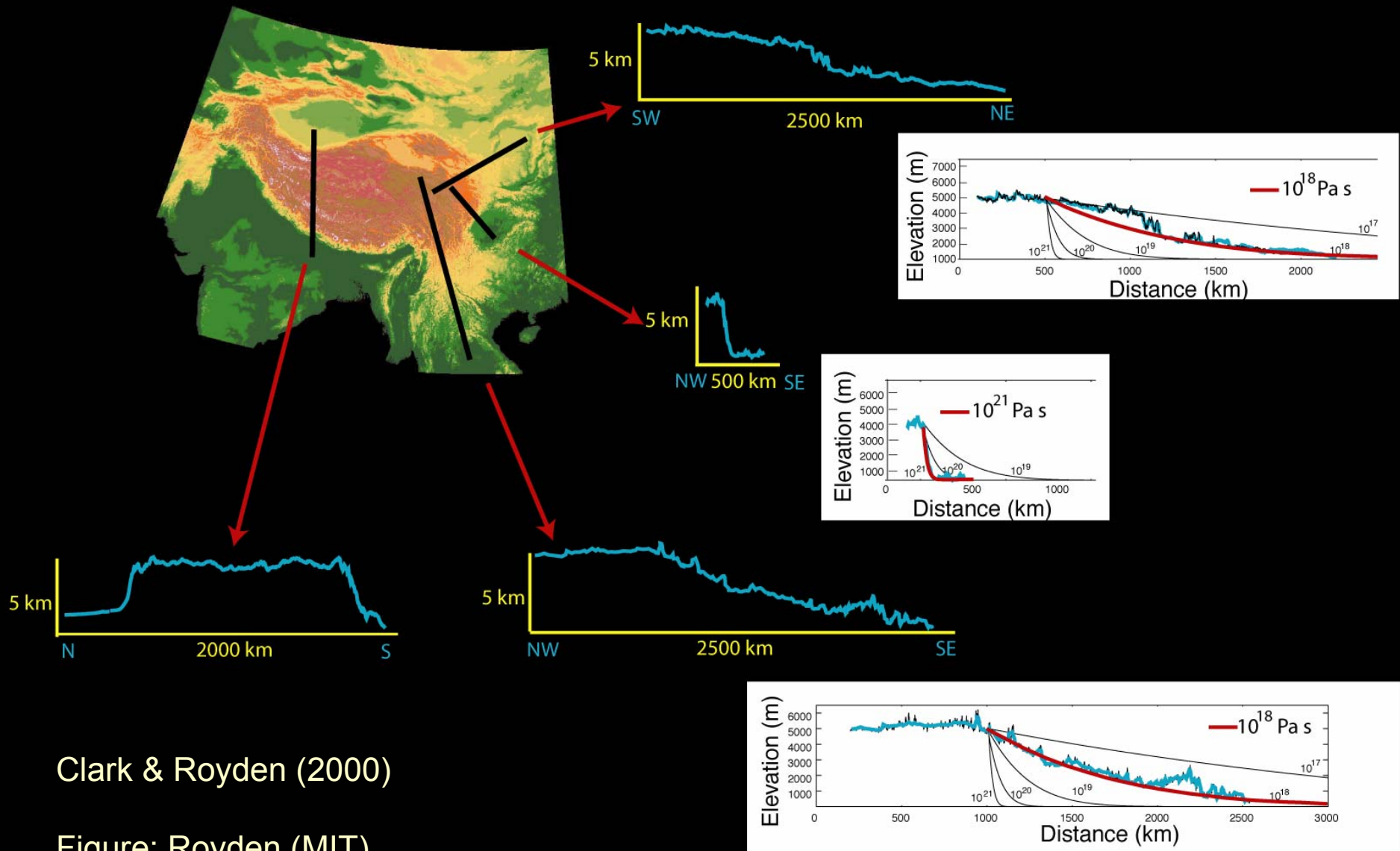


Topographic gradients on plateau margin reflect the strength (effective viscosity) of the weakest layer in the underlying crust

Figure: Royden (MIT)



Regional variation in topographic gradient at the margins of the Tibetan Plateau



Clark & Royden (2000)

Figure: Royden (MIT)

Anisotropy I: Azimuthal Anisotropy

(i.e., dependence of wavespeed on direction of propagation in horizontal plane)

- Step 1: inter-station phase velocities from **EGF** → azimuthally anisotropic phase velocity maps

$$c(\omega, \psi) = c_0(\omega) [1 + a_0(\omega) + a_1(\omega) \cos 2\psi + a_2(\omega) \sin 2\psi]$$

- Step 2: phase velocity maps → shear wave speed & anisotropy

$$\delta c_R(x, y, \omega, \psi) \approx \int_0^H \left[\frac{\partial c_R}{\partial L} (\delta L + G_c \cos 2\psi + G_s \sin 2\psi) \right] \frac{dz}{\Delta h}$$

At each point (x,y), the reference crustal thickness is constrained from receiver functions (Xu et al., 2007; Zurek et al, 2005)

$$\hat{\beta}_{SV} \approx \beta_{SV} \left(1 + \frac{G_c}{2L} \cos 2\psi + \frac{G_s}{2L} \sin 2\psi \right)$$

Transverse isotropic V_{SV} : $\beta_{SV} = \sqrt{L/\rho}$

Magnitude of azimuthal aniso $A_{SV} = \frac{1}{2L} \sqrt{(G_c)^2 + (G_s)^2}$

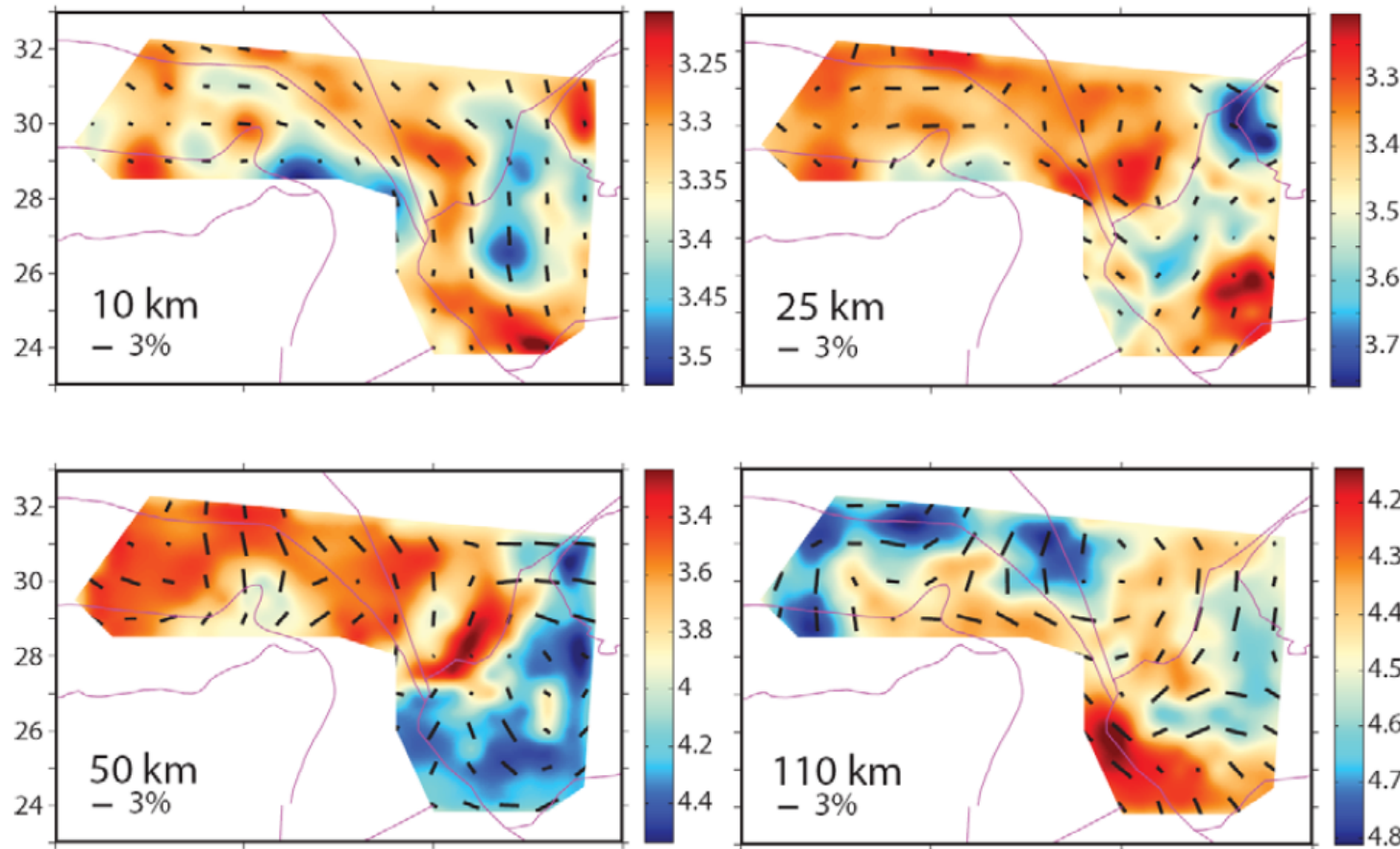
Fast axis of azimuthal aniso : $\phi = \frac{1}{2} \tan^{-1} (G_s/G_c)$

3D lithospheric heterogeneity & azimuthal anisotropy

Complicated deformation pattern:

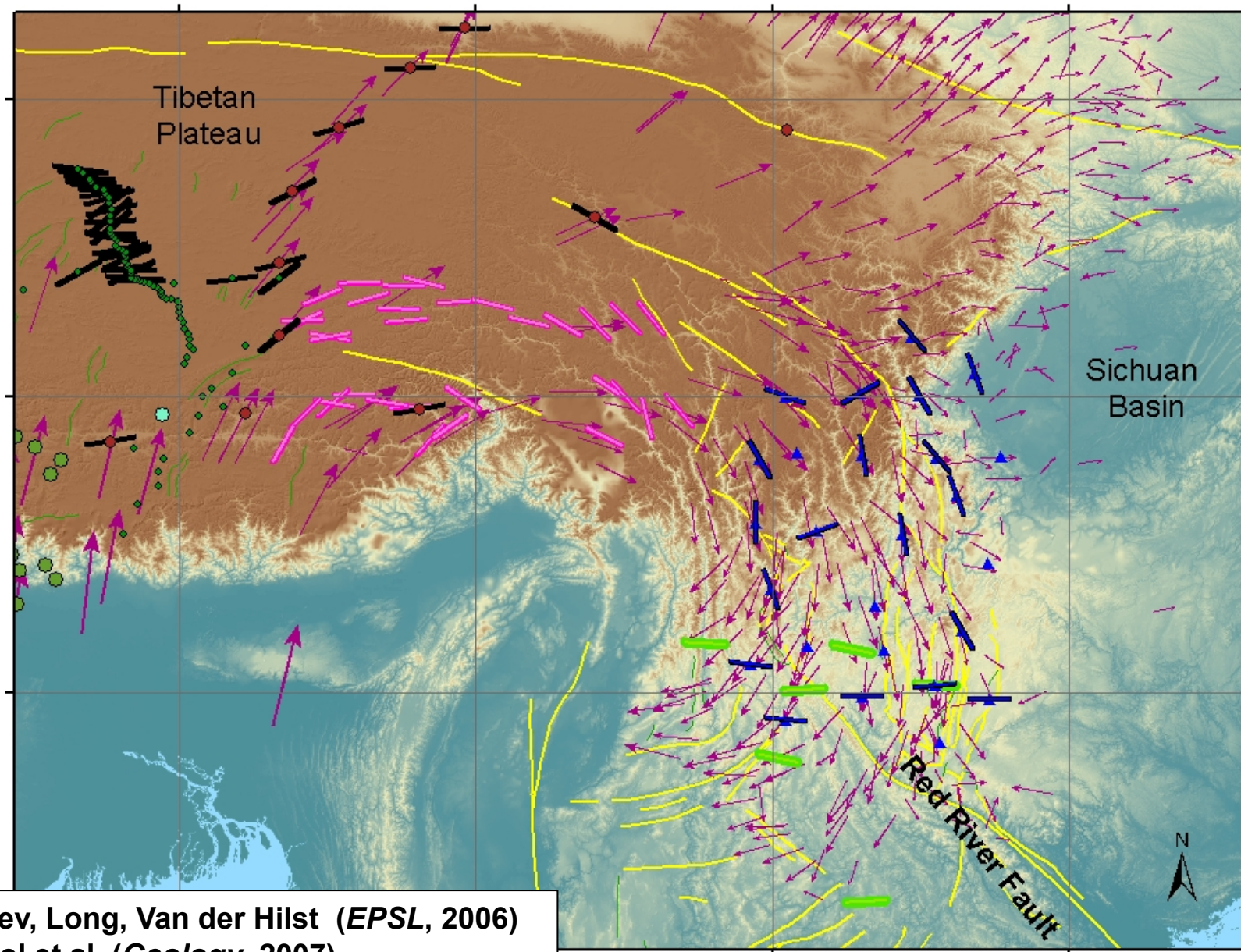
Upper crust: consistent with clockwise rotation (GPS)

Uppermost mantle: fast direction along the LVZ of the margin of Yangtze block

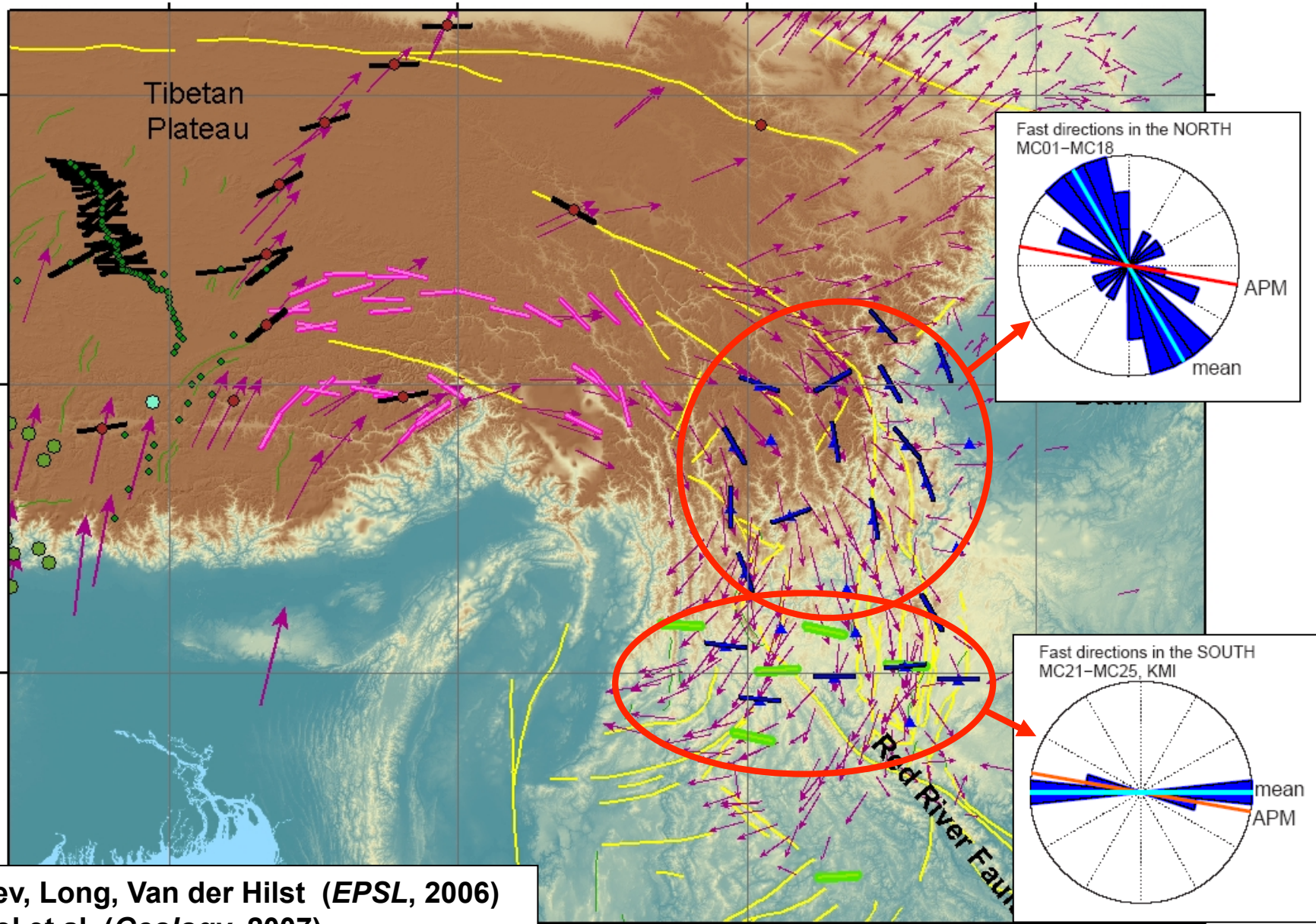


Yao, Van der Hilst, and Montagner (JGR, 2010)

SKS splitting (~ azimuthal anisotropy) and GPS (purple arrows)

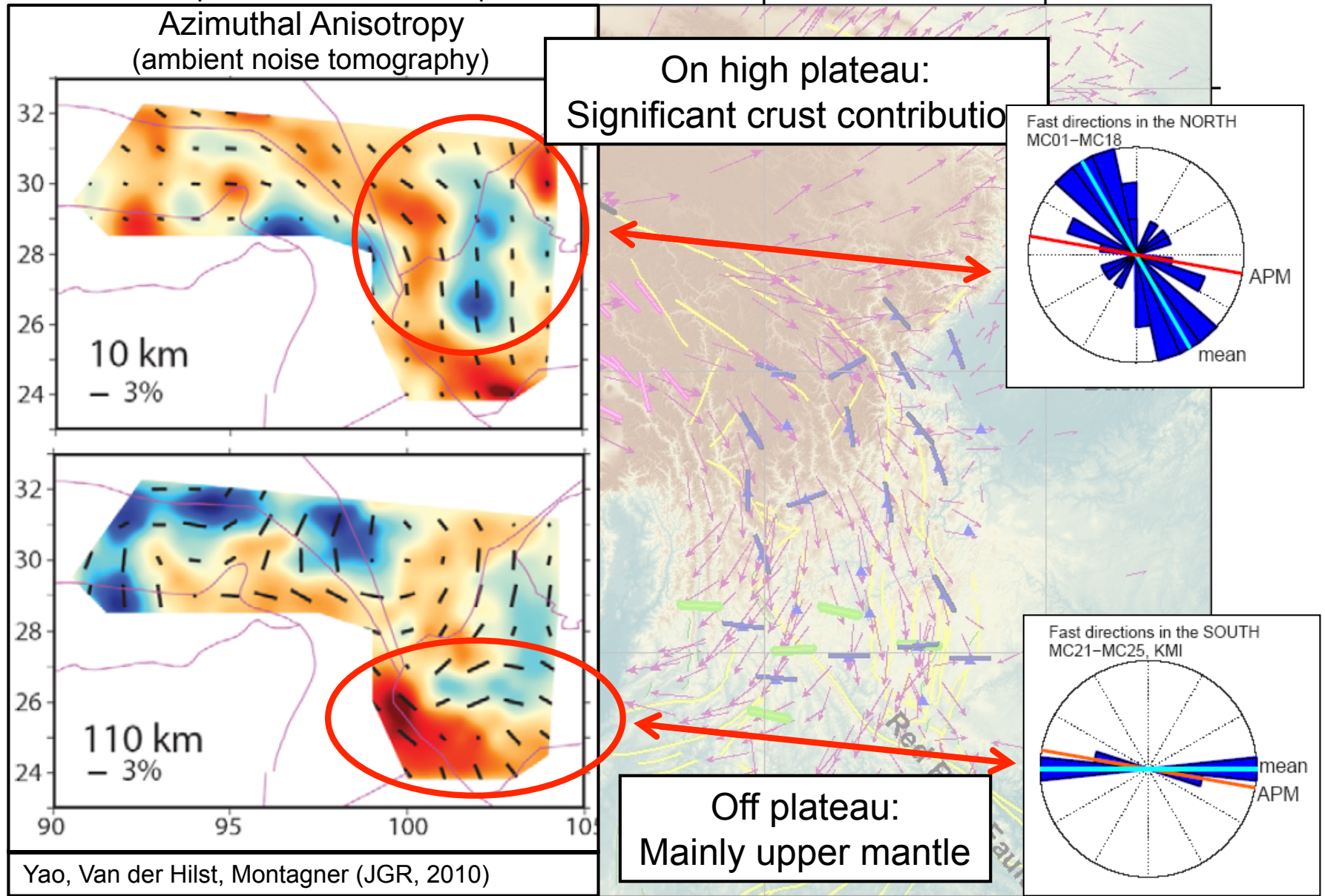


Lev, Long, Van der Hilst (*EPSL*, 2006)
Sol et al. (*Geology*, 2007)

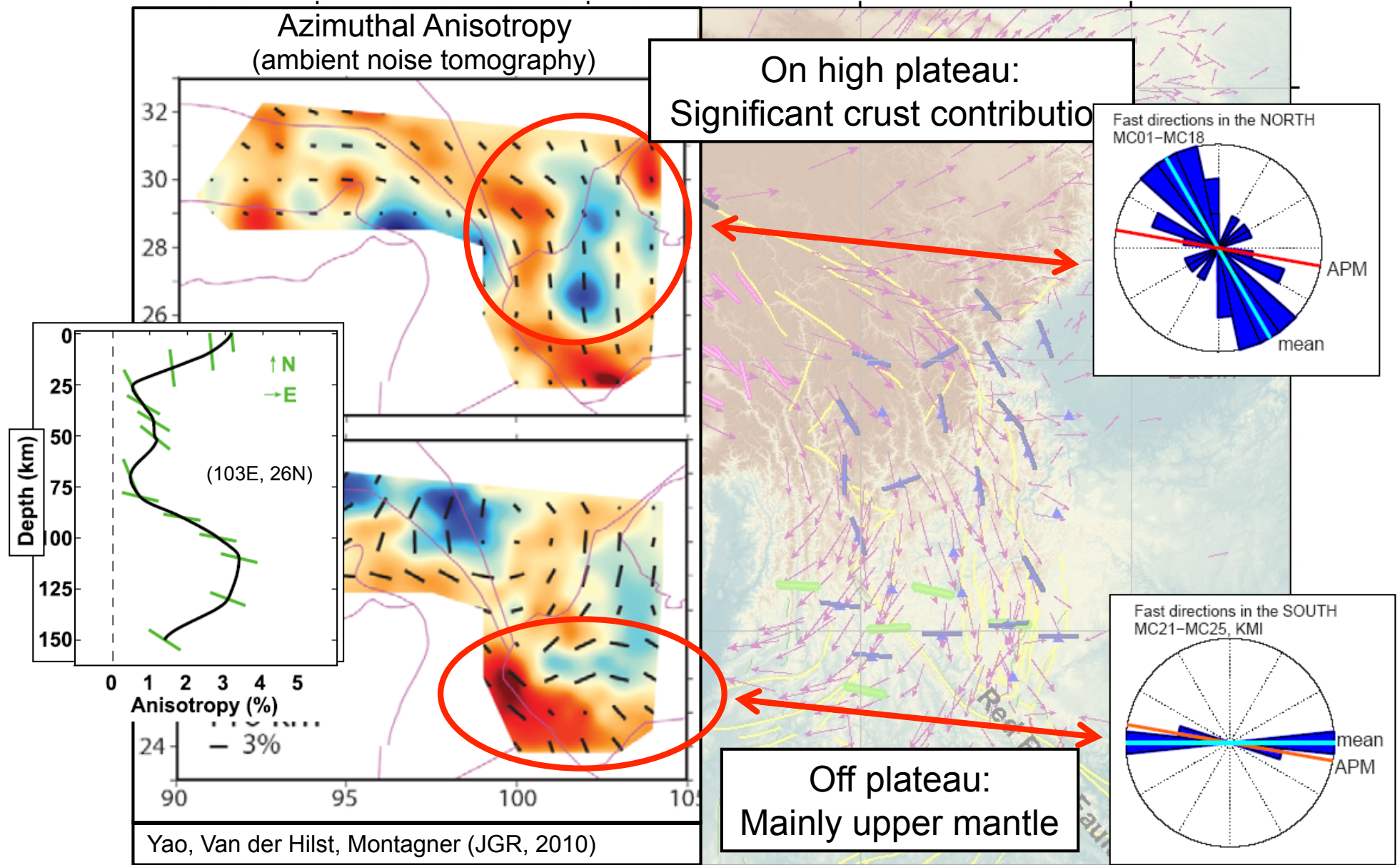


Lev, Long, Van der Hilst (*EPSL*, 2006)
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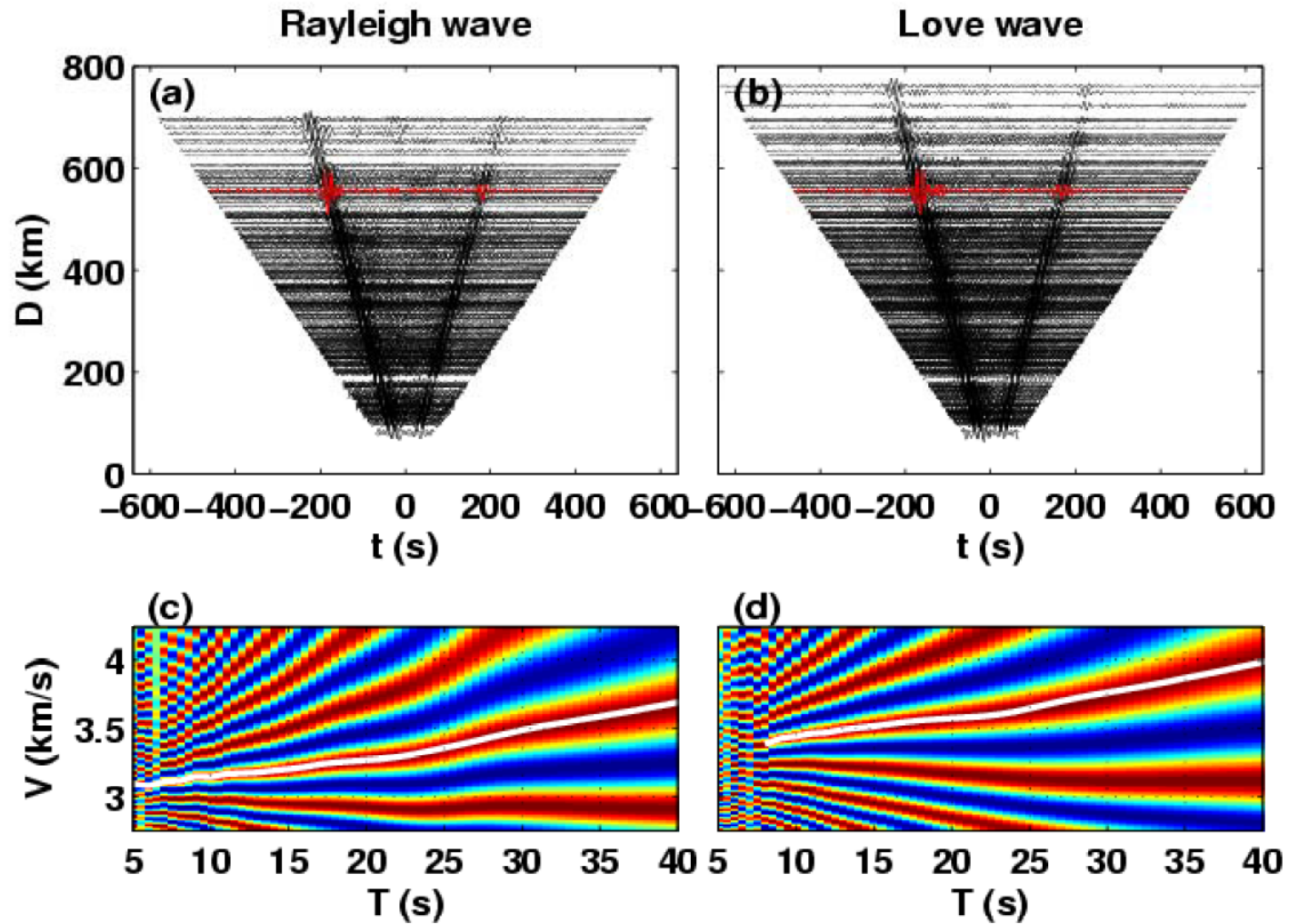
strong variation of azimuthal anisotropy with depth



strong variation of azimuthal anisotropy with depth



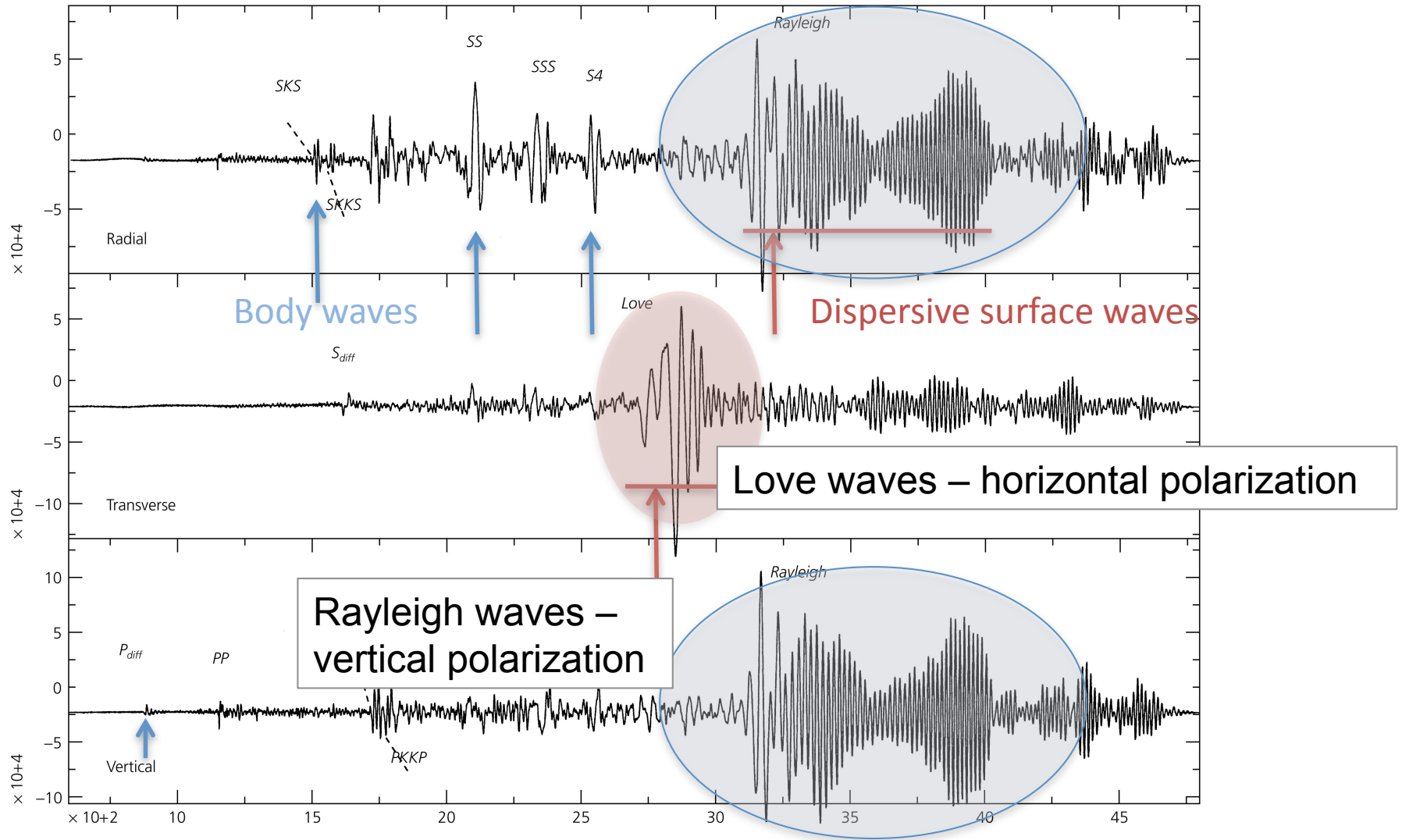
Radial Anisotropy from joint inversion of Love and Rayleigh wave dispersion (empirical Green's functions for noise correlation).



Huang, Yao, and Van der Hilst (GRL, 2010)

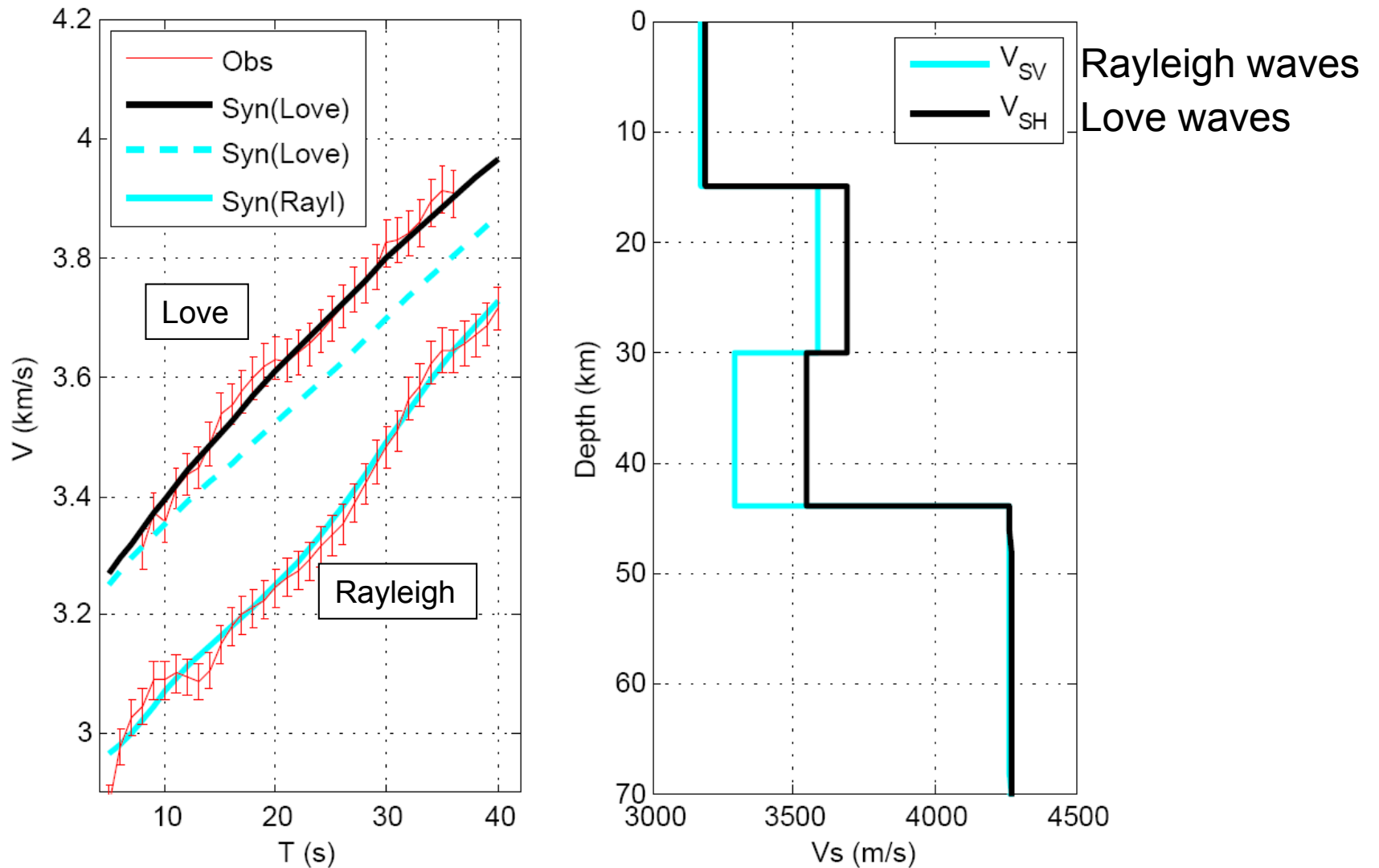
Anisotropy II: Radial Anisotropy (or: transverse isotropy)

(i.e., difference between wavespeed of horizontally and vertically polarized waves)



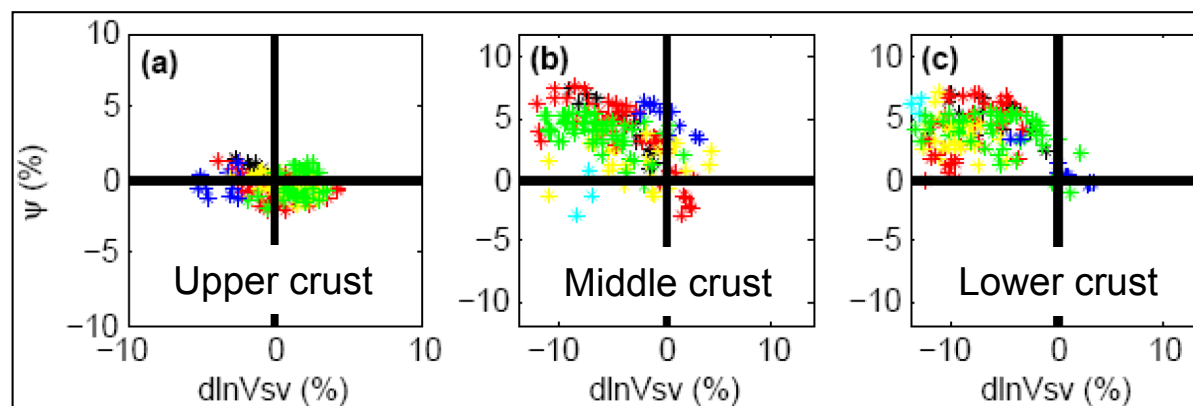
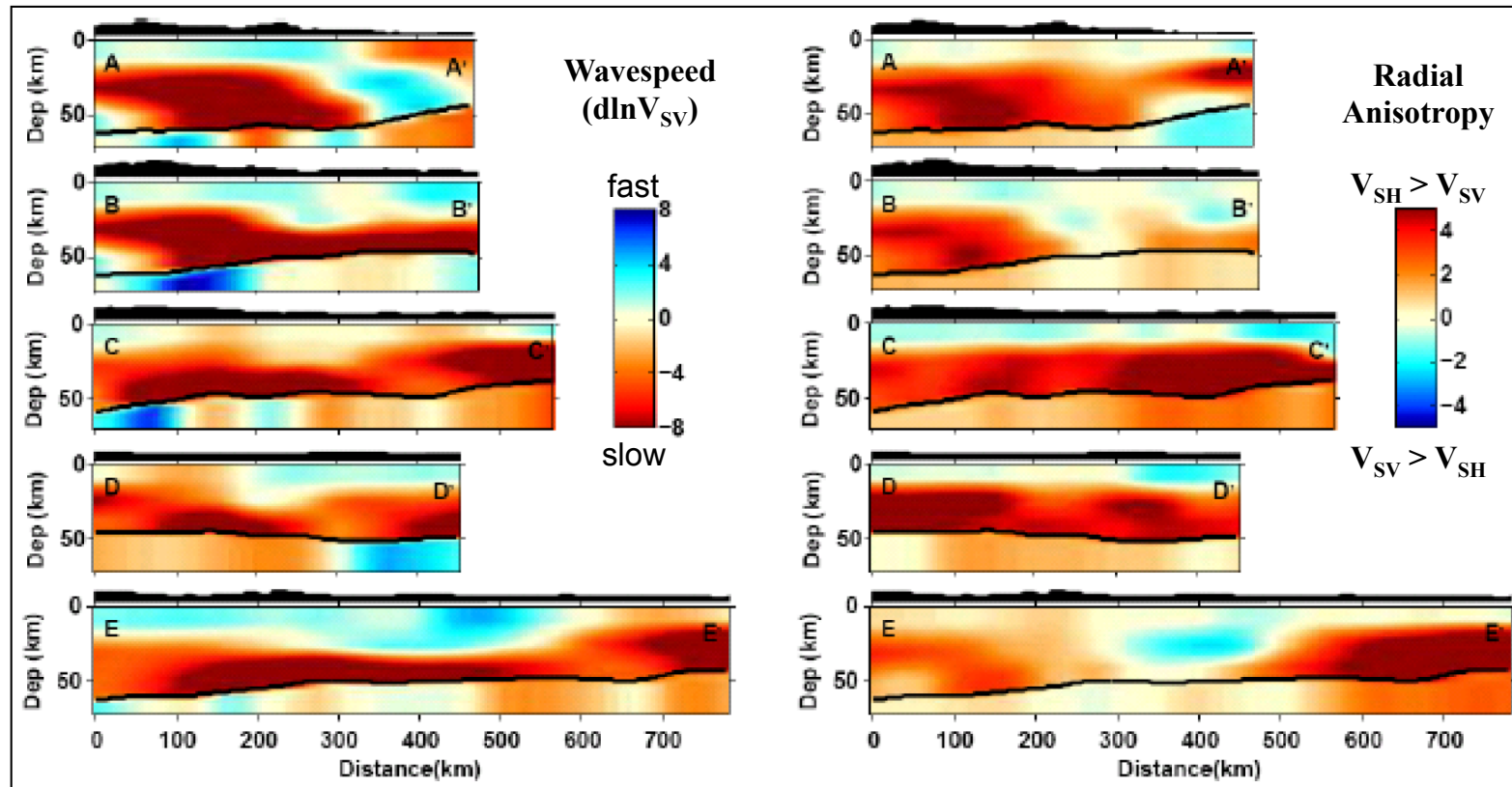
From Stein and Wyession

Radial Anisotropy (from Love and Rayleigh wave dispersion)

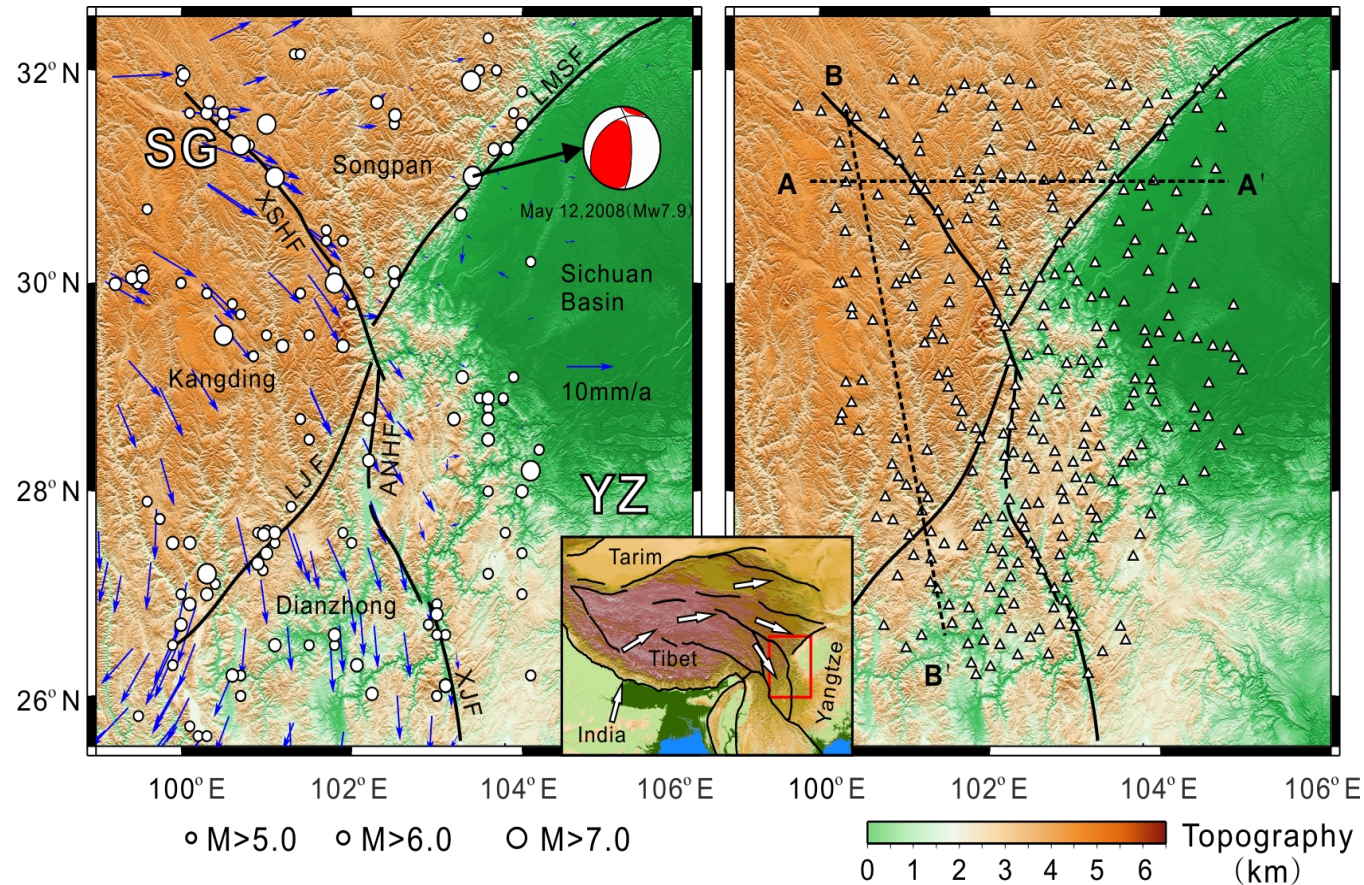


Huang, Yao, and Van der Hilst (GRL, 2010)

Strong correlation with LVZs → horizontal flow in weak zones?



High resolution studies with dense seismograph arrays



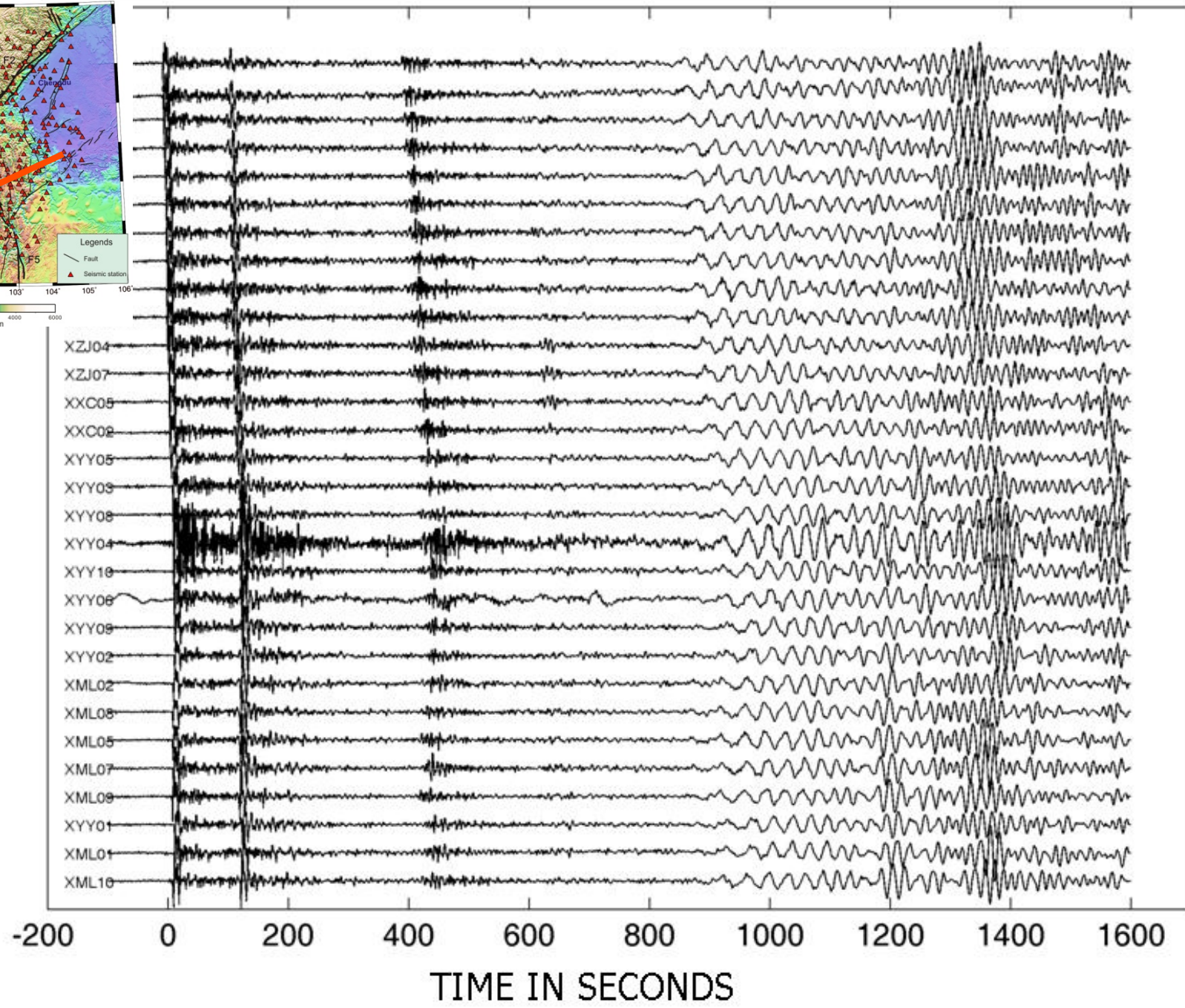
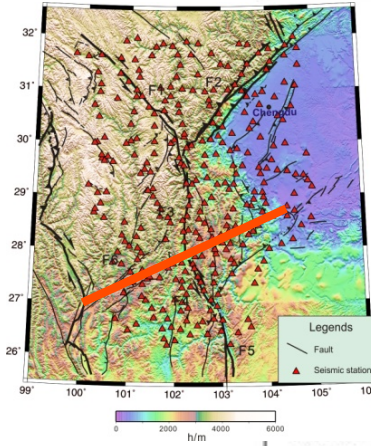
Geological setting and station map of the movable dens seismic array in western Sichuan (State Key Laboratory of Earthquake Dynamics, Institute of Geology, China Earthquake Administration). Black solid lines: major faults; blue triangles: stations; yellow circles: earthquakes ($M_s \geq 5.0$, 1901-2010, 2008 Wenchuan focal mechanism); blue arrows: crustal motion relative to the Yangtze craton from GPS; red dash lines: seismic profile.

[SB=Sichuan Basin; YZ=Yangtze block; CD=Chundian unit; SG= Songpan-Ganze unit]
 [XSH=Xiangshuihe; LMS=Longmen Shan; ANH=Anninghe; LJ=Lijiang fault]

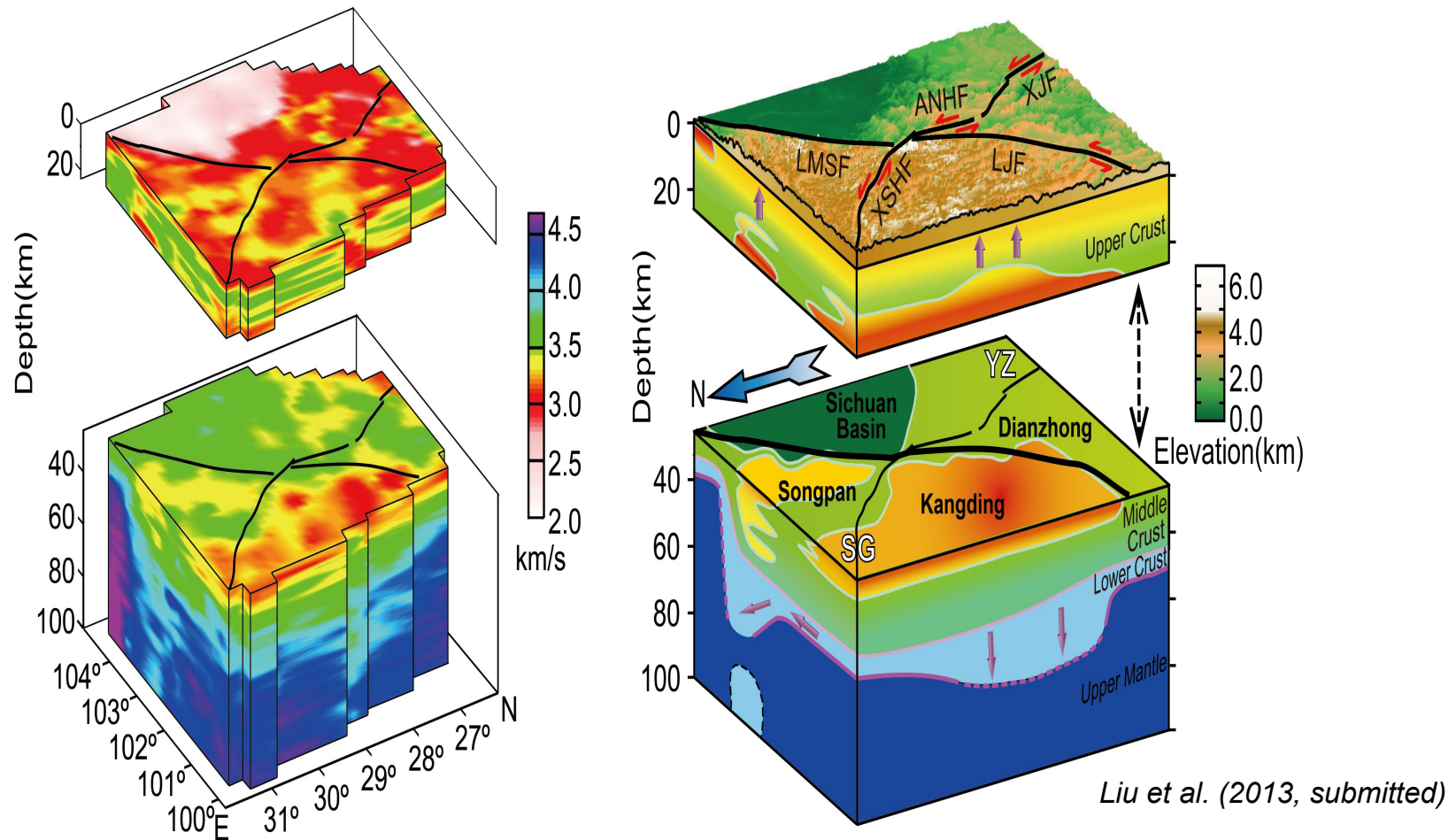
January 13, 2007 04h23m21.16s

MB 7.3

Location: 46.243° N, 154.524° E



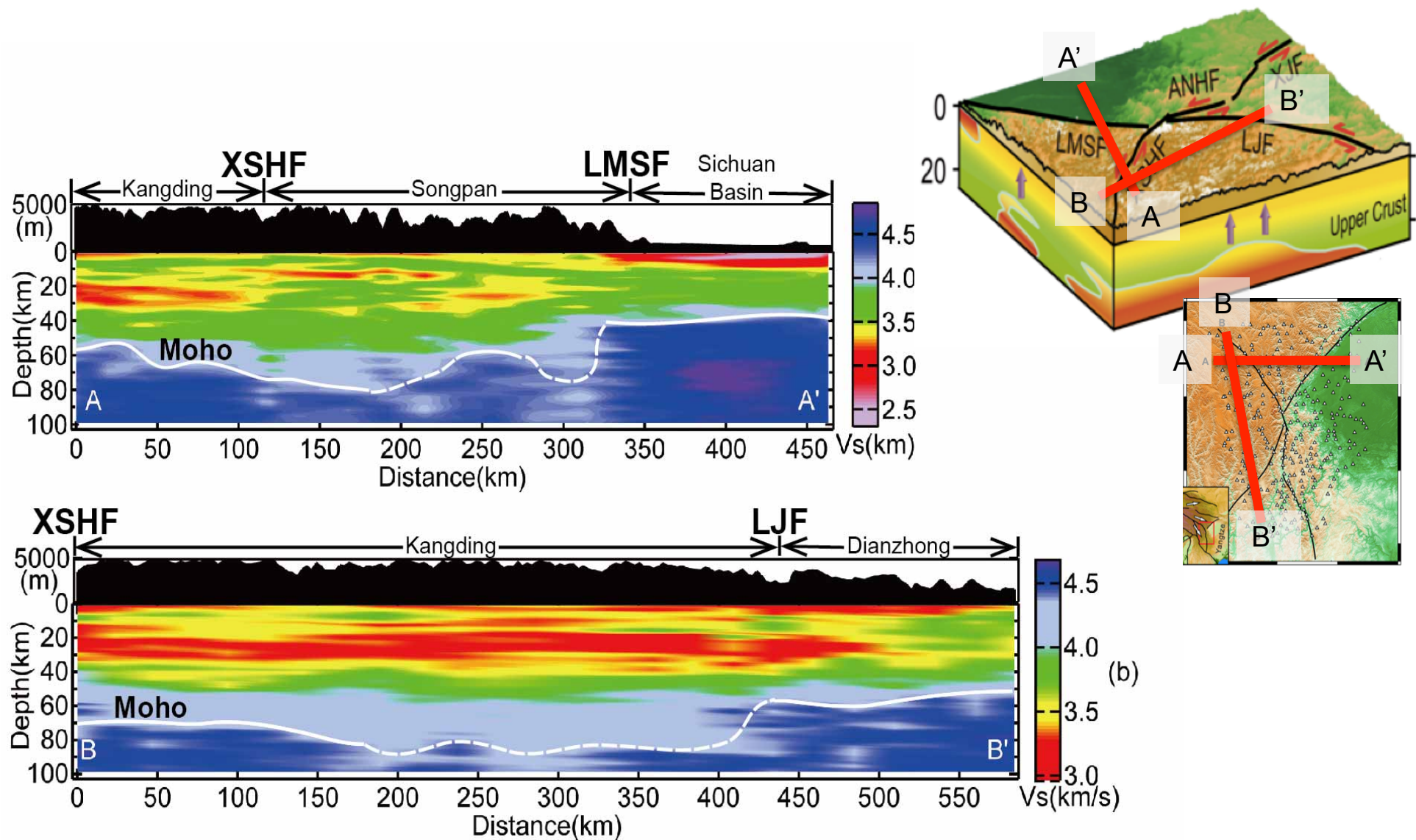
Ambient Noise Tomography (with Moho depth constrained by receiver functions)



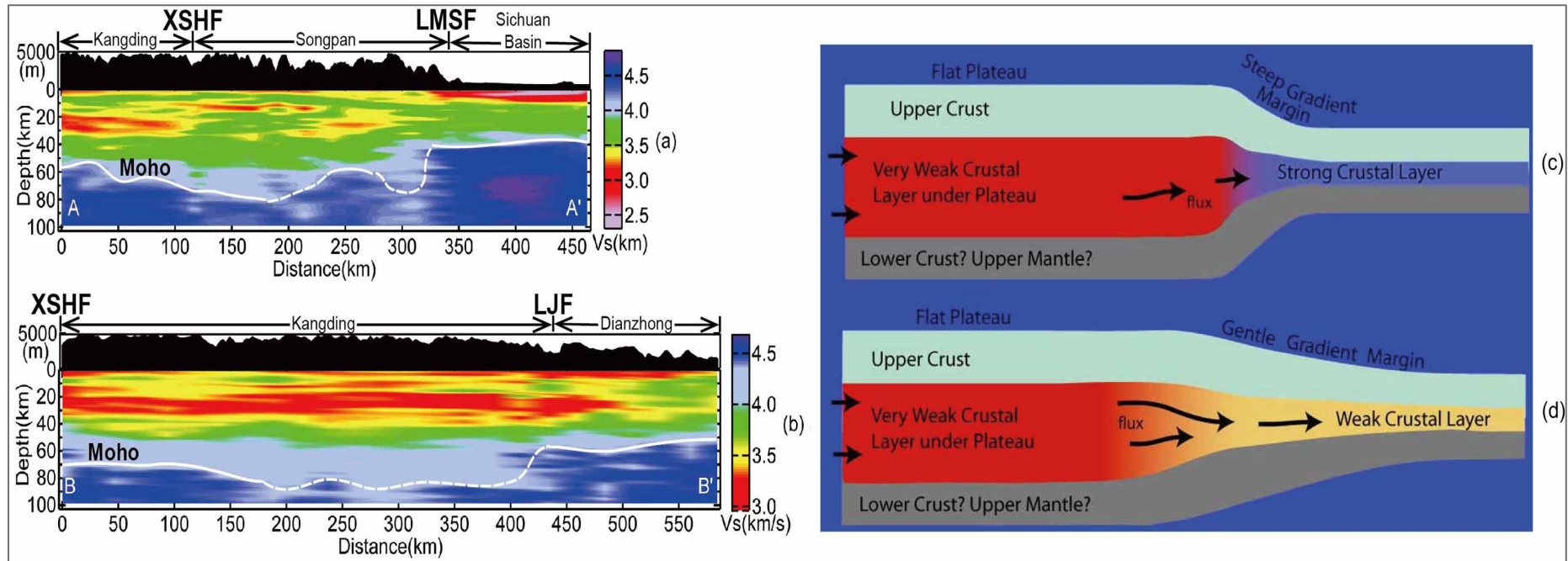
Liu et al. (2013, submitted)

3D perspectives of lithospheric shear-wavespeed variations in relation to surface topography and major fault systems in the region. Left: wavespeeds from joint inversion; Right: cartoon summarizing the main structural and topographic features.

[SB=Sichuan Basin; YZ=Yangtze block; CD=Chundian unit; SG= Songpan-Ganze unit]
 [XSH=Xiangshuihe; LMS=Longmen Shan; ANH=Anninghe; LJ=Lijiang fault]



Topography and shear wavespeed variations from joint inversion of P-receiver functions and Ambient Noise (Rayleigh wave) Tomography across region of steep relief (A-A'; top) and gentle topographic gradient (B-B'; bottom).

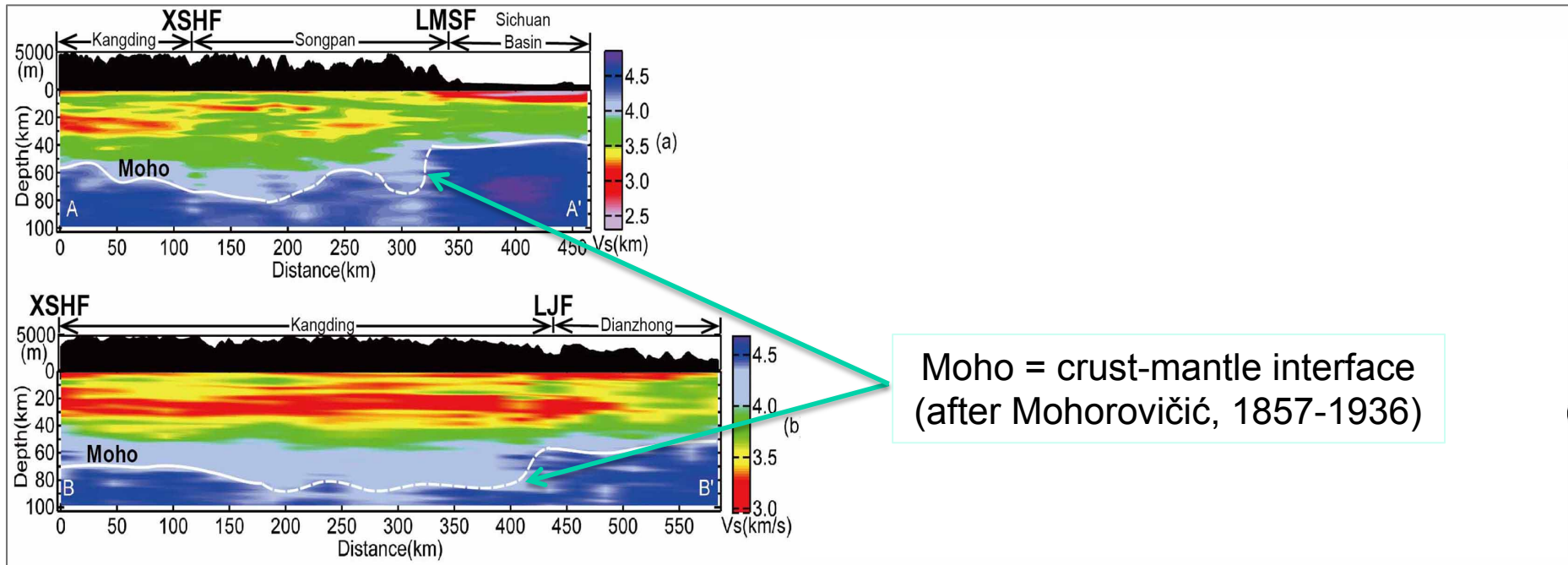


Crustal structure constrained by waveform data obtained by a dense seismography array in western Sichuan.

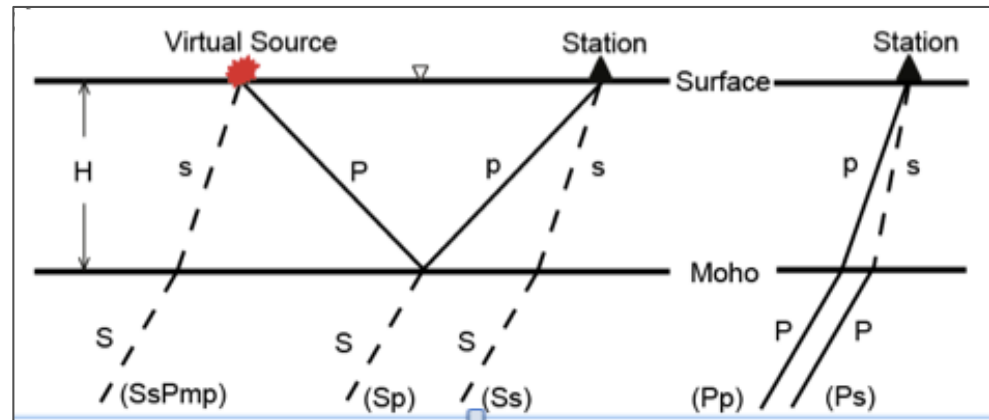
Concept: canonical channel flow model. (Figure courtesy of L. Royden, MIT).

Overview of lecture:

1. Introduction/background
2. Ambient noise and surface wave tomography
- 3. Reverse time migration of converted waves**
4. Interferometry of teleseismic (coda) waves

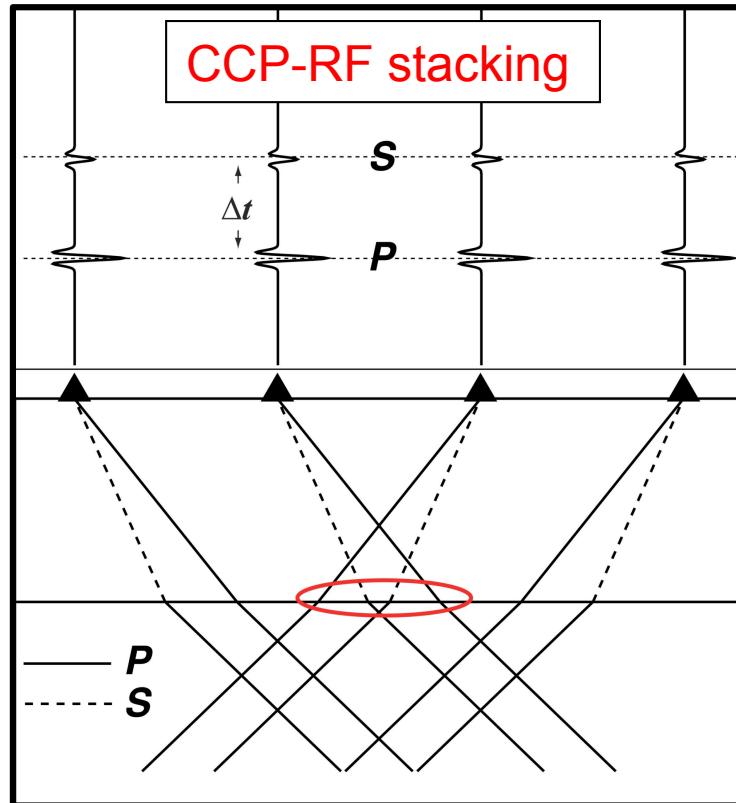


Imaging of the Moho with Converted Waves (*P-to-S* or *S-to-P*)



Yu et al.(EPSL, 2012)

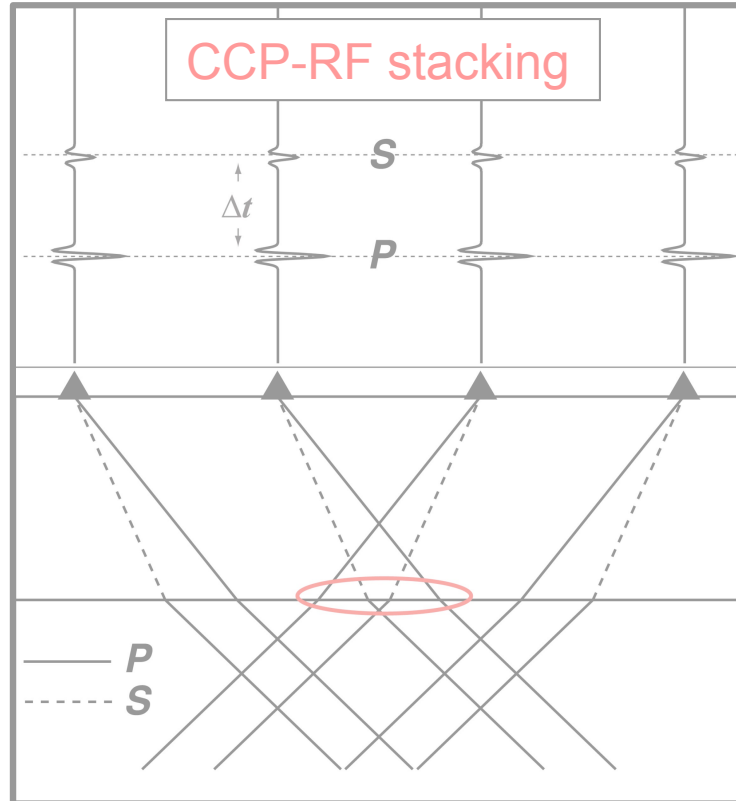
Traditional approach (concept)



Common **C**onversion **P**oint
stacks of converted waves
(**R**eceiver **F**unctions):

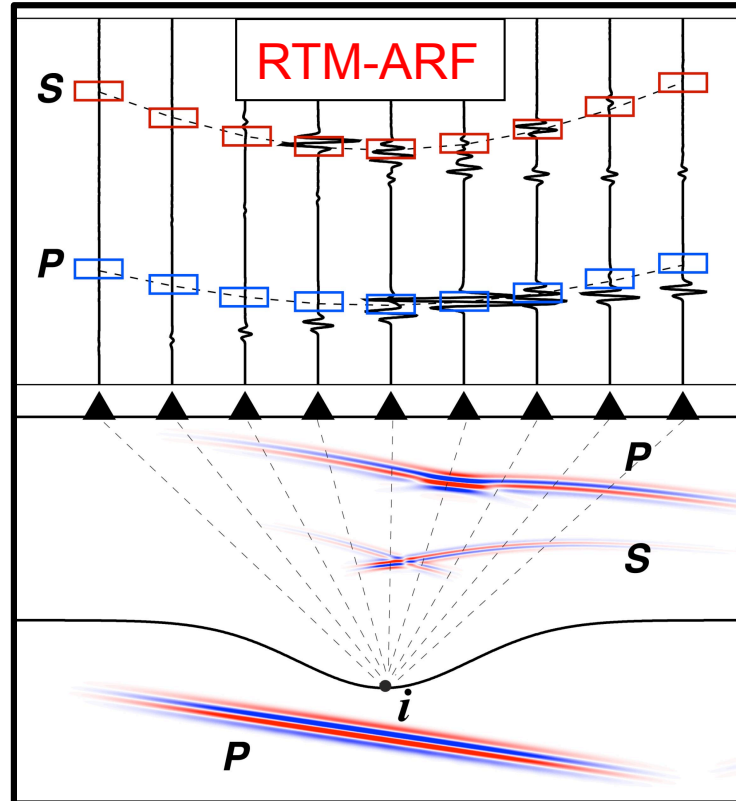
- Time differences mapped
directly to depth
- Horizontal interfaces

Traditional approach (concept)



- C**ommon **C**onversion **P**oint
stacks of converted waves
(**R**eceiver **F**unctions):
- Time differences mapped directly to depth
 - Horizontal interfaces

Shang et al. (GRL, 2012)



- R**everse **T**ime **M**igration of
Array **R**eceiver **F**unctions:
- Cross-correlations: incoming & time reversed and *P* & *S* waves ("imaging condition")
 - No assumption on structure

Synthetic experiments for two test models

data

data

caustic due to lens

Low
velocity
lens



Lens model

Multi-layer step model

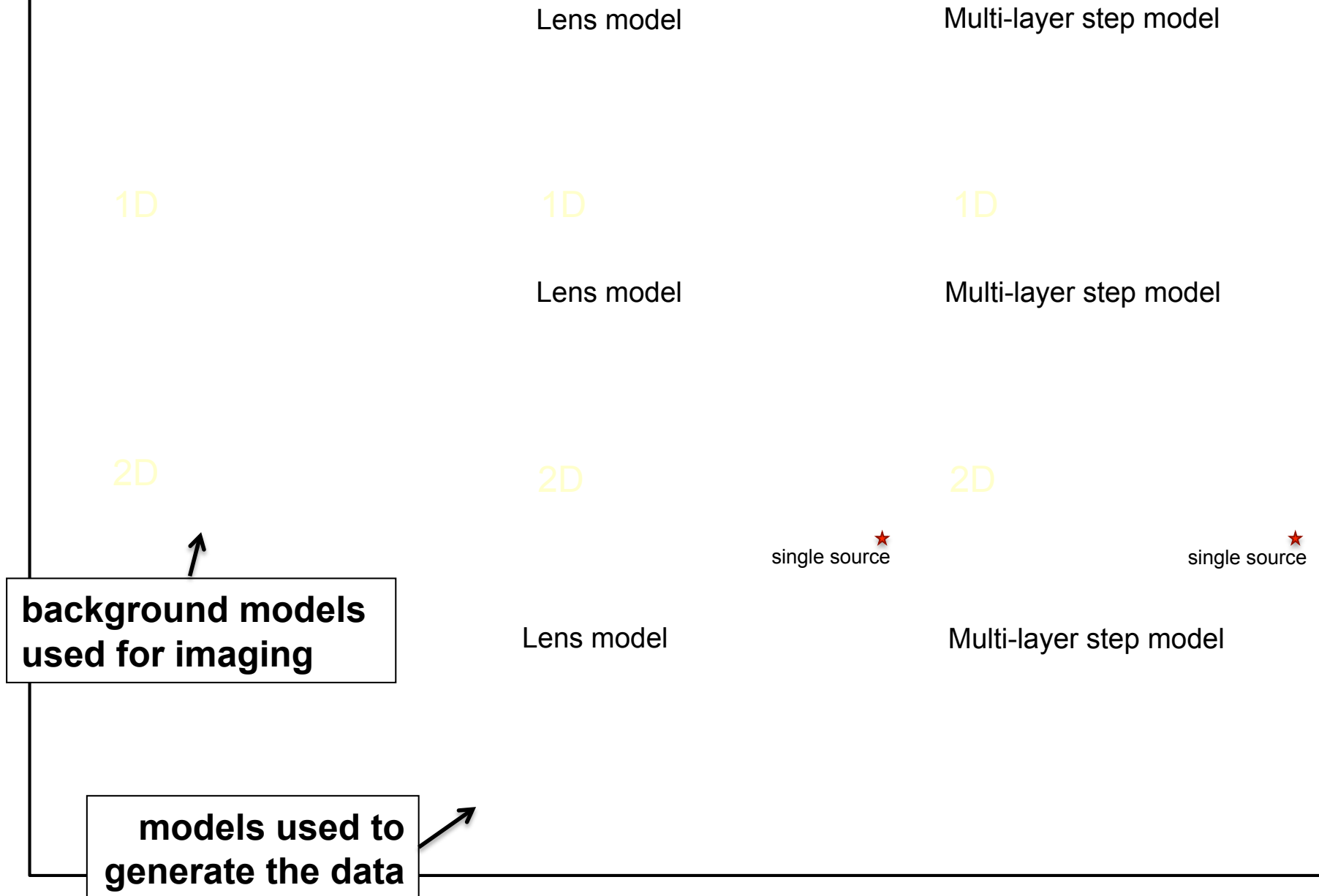
source array



source array



Effect of background model on image quality



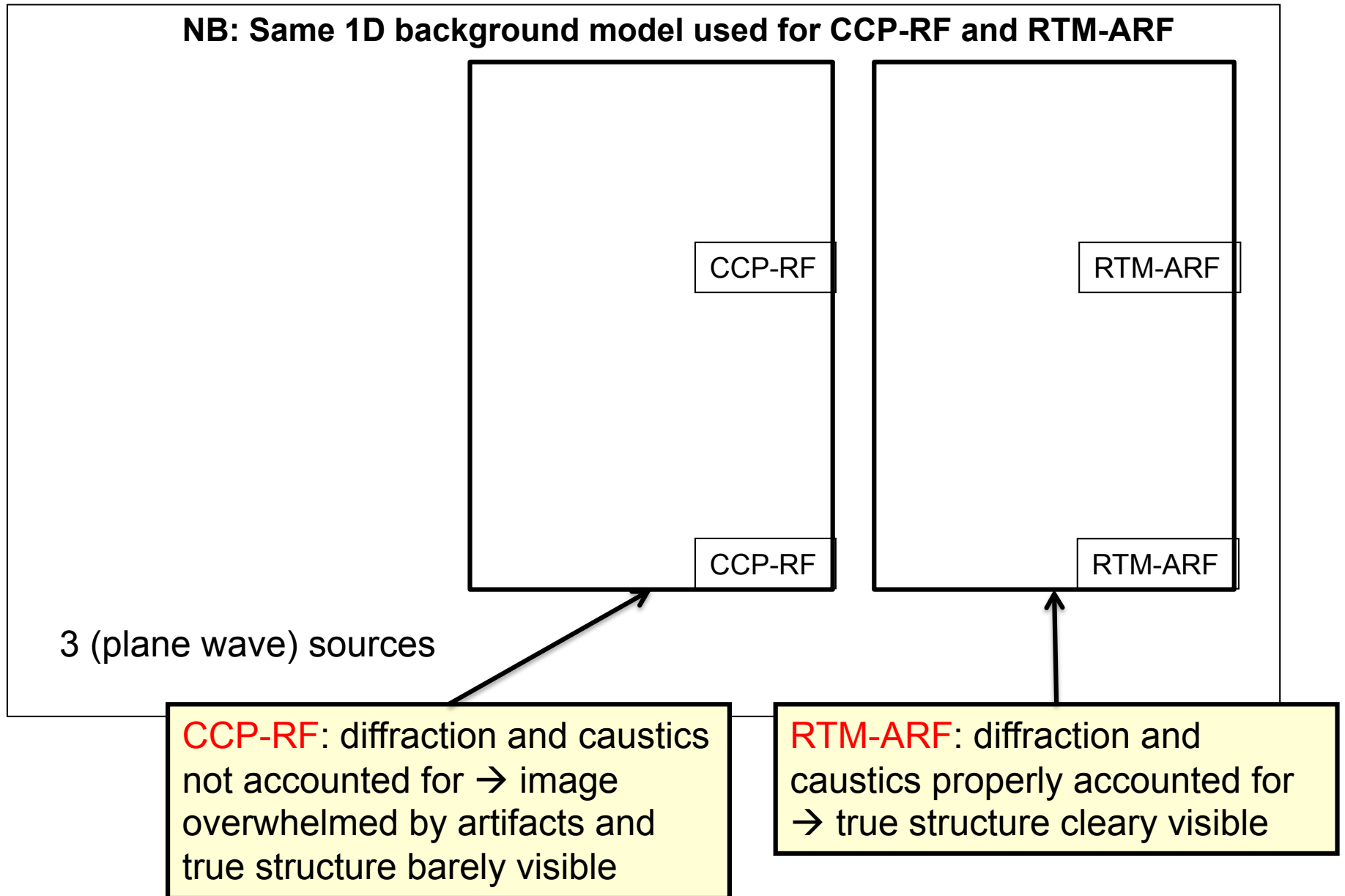


Image accuracy depends on background model

Can be obtained from tomography

E.g., travel time, surface waves, ambient noise ...

Or

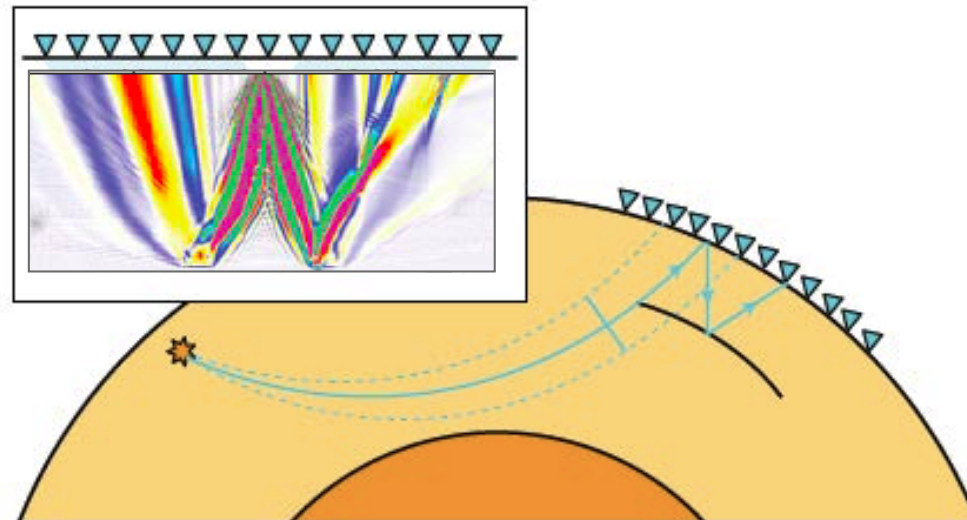
RTM based (teleseismic) reflection tomography

Teleseismic wave-equation reflection tomography using free surface reflected phases

S. Burdick¹, M. V. de Hoop², S. Wang², R. D. van der Hilst¹

¹ Department of Earth, Atmospheric, and Planetary Sciences, Massachusetts Institute of Technology Cambridge, MA 02139, USA

² Department of Mathematics, Purdue University

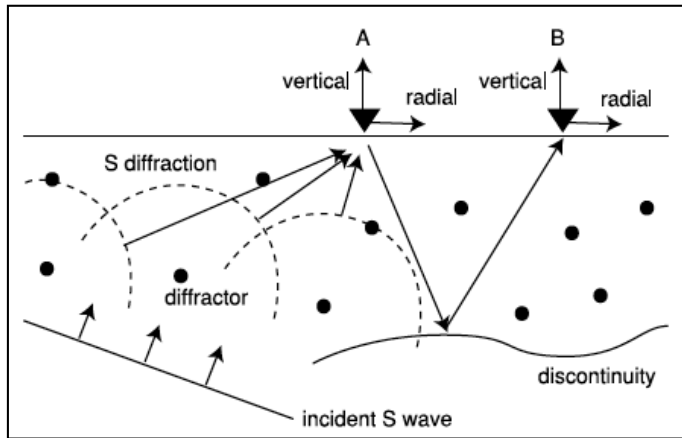


Construct images from converted and multiply-reflected teleseismic phases

Overview of lecture:

1. Introduction/background
2. Ambient noise and surface wave tomography
3. Reverse time migration of converted waves
4. Interferometry of teleseismic (coda) waves

For instance, imaging of the slab interface



Seismic interferometry of teleseismic *S*-wave coda for retrieval of body waves: an application to the Philippine Sea slab underneath the Japanese Islands

Takashi Tonegawa,¹ Kiwamu Nishida,¹ Toshiki Watanabe² and Katsuhiko Shiomi³

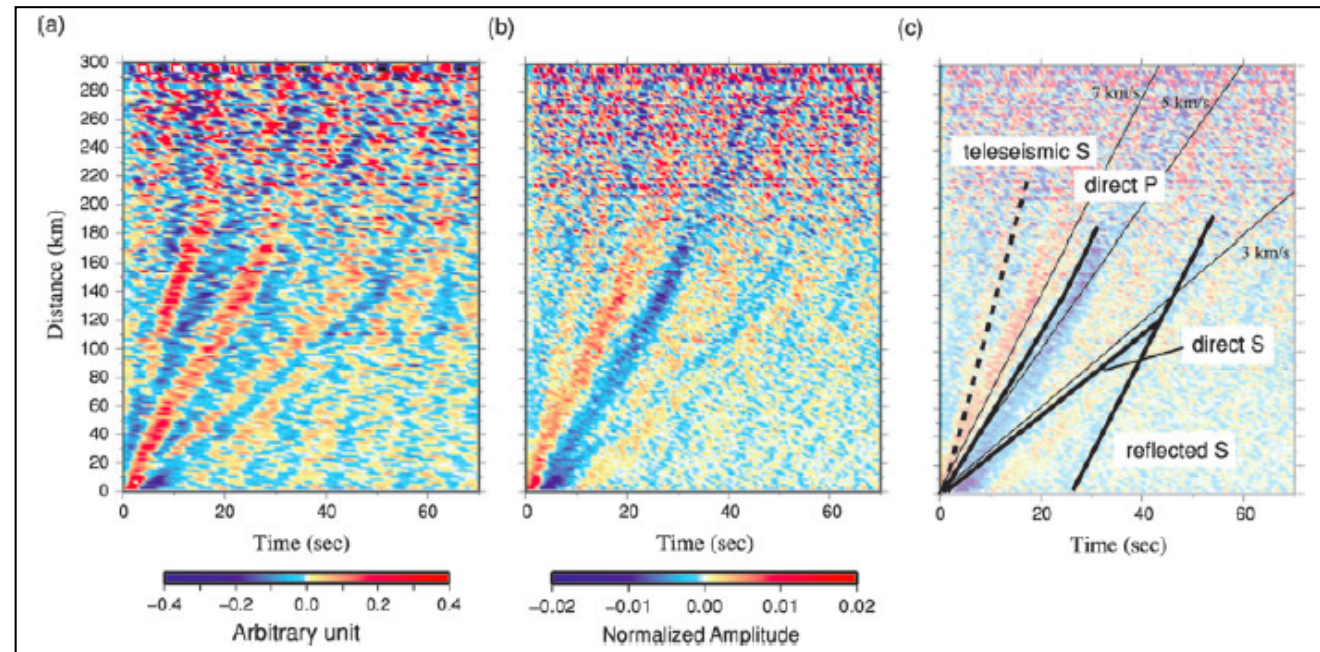
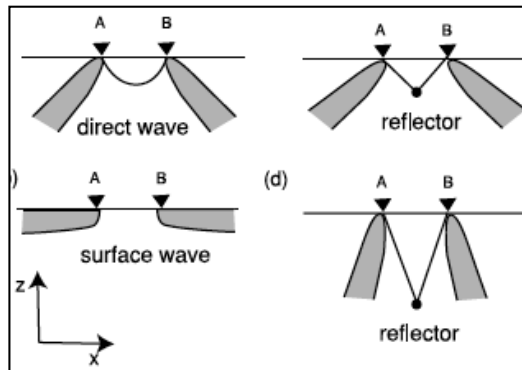
¹Earthquake Research Institute, Univ. of Tokyo, 1-1-1, Yayoi, Bunkyo-ku, Tokyo 113-0032, Japan. E-mail: tonegawa@eri.u-tokyo.ac.jp

²Graduate School of Environmental Studies, Nagoya University, Furo-cho, Chikusa-ku, Nagoya 464-8602, Japan

³National Research Institute for Earth Science and Disaster Prevention, 3-1, Tennodai, Tsukuba, Ibaraki 305-0006, Japan

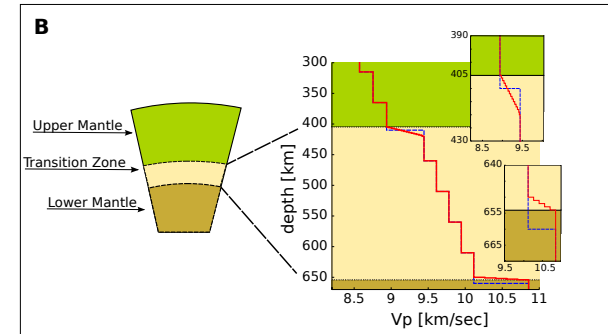
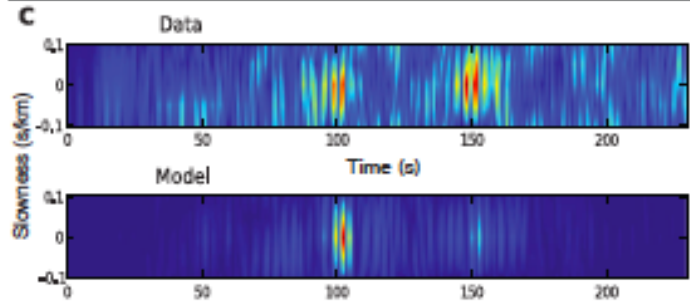
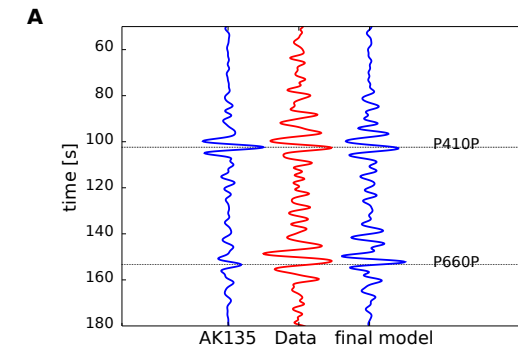
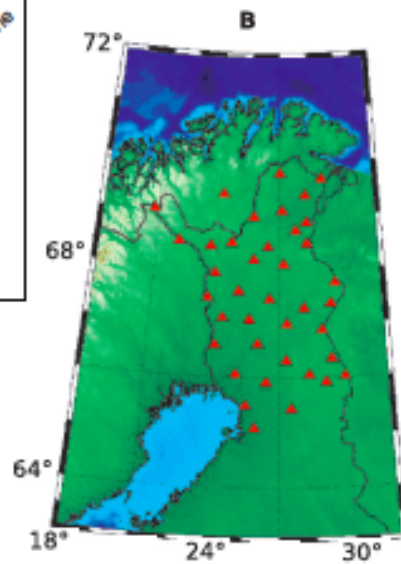
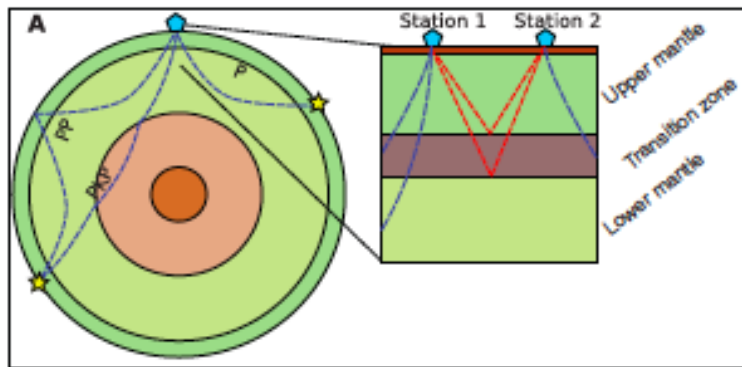
Accepted 2009 May 11. Received 2009 April 20; in original form 2009 January 22

Tonegawa et al. (GJI, 2009)



Or passive imaging: Earth's mantle discontinuities from ambient seismic noise.

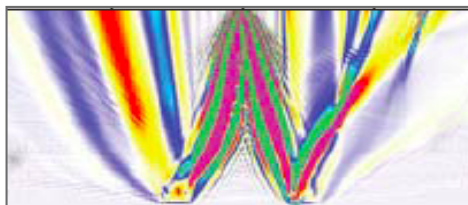
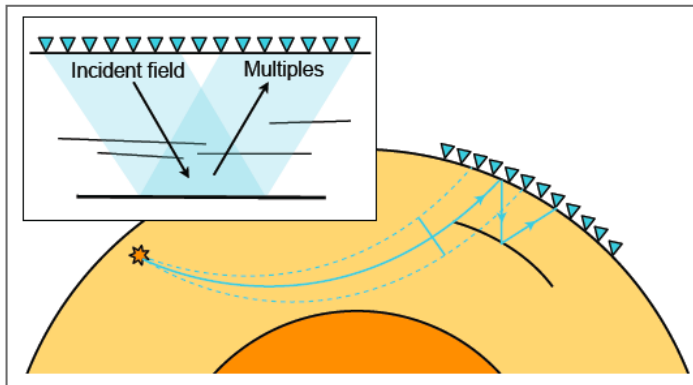
Poli et al. (Science, 2012)



Campillo (Cargese, 2013)

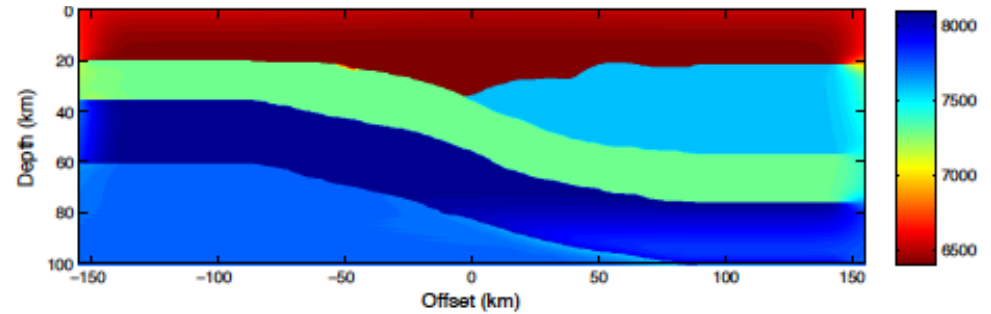
Construct images from converted and multiply-reflected teleseismic phases

Burdick et al. (GJI, submitted)

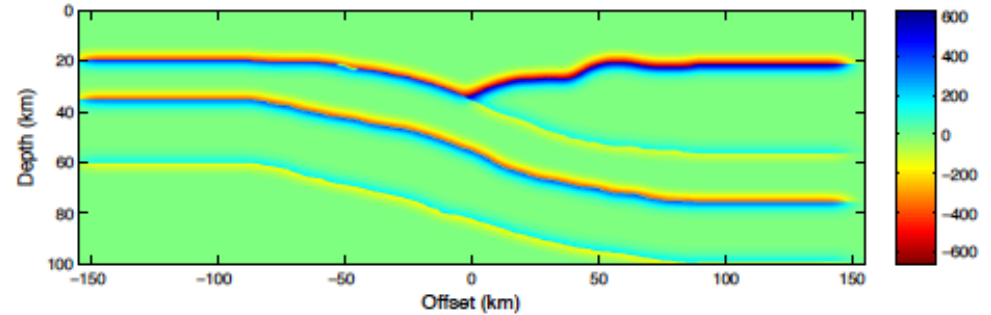


Wave-equation reflection tomography → full finite frequency (De Hoop et al., (GJI, 2006)

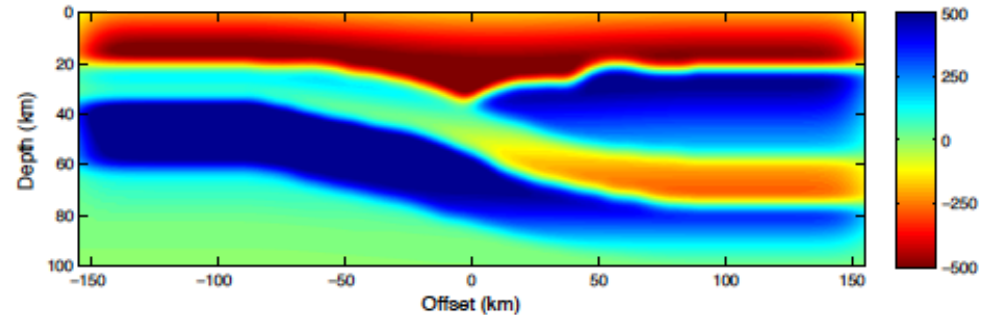
Actual model (used to create synthetic data)



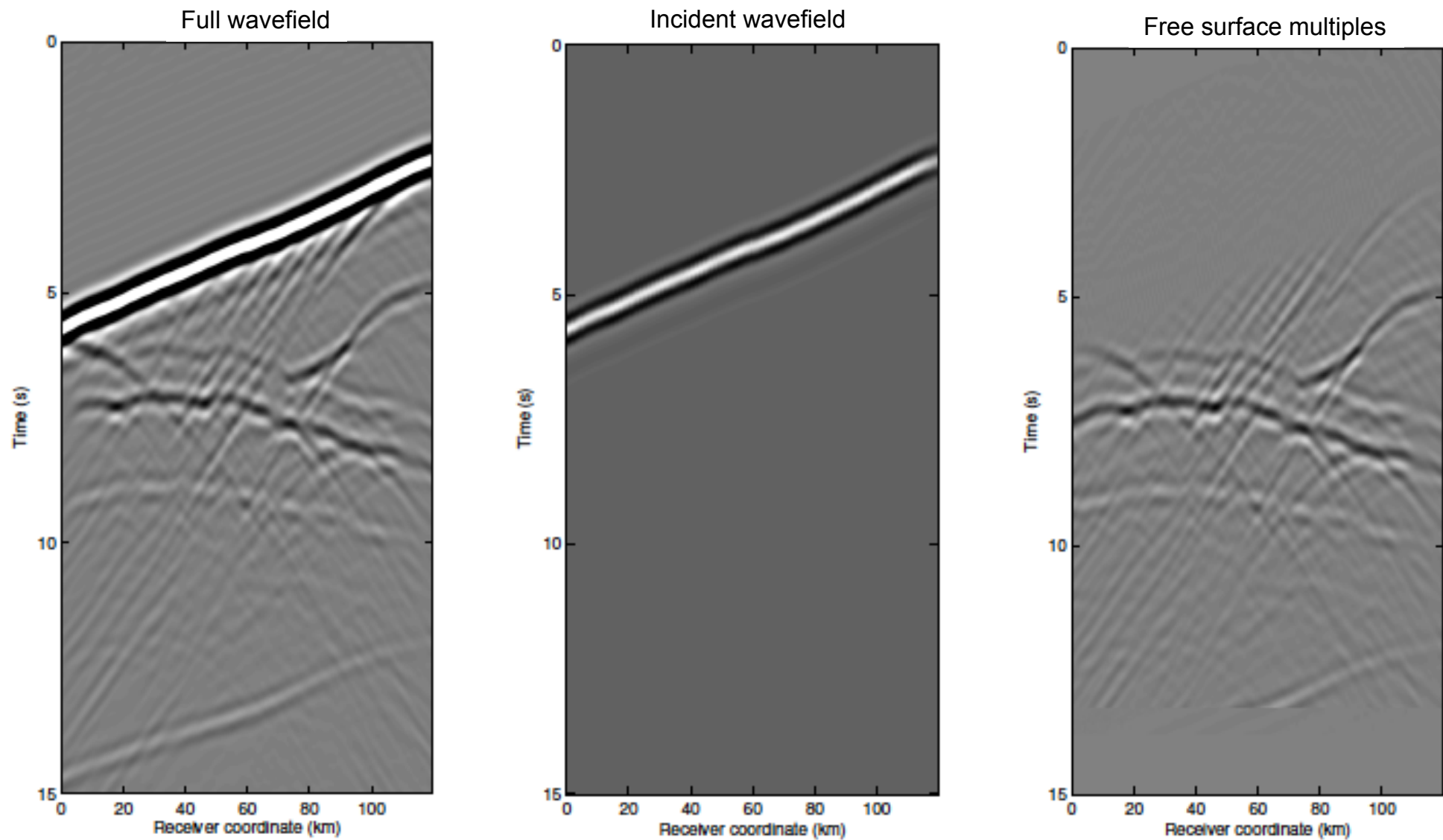
Reflectivity (singular part of model)



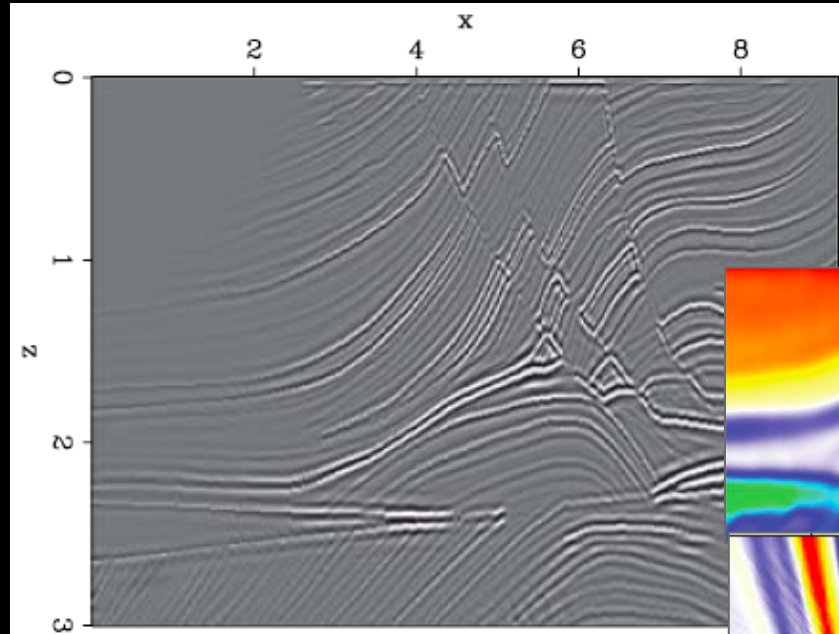
Wavespeed perturbation (smooth part of model)



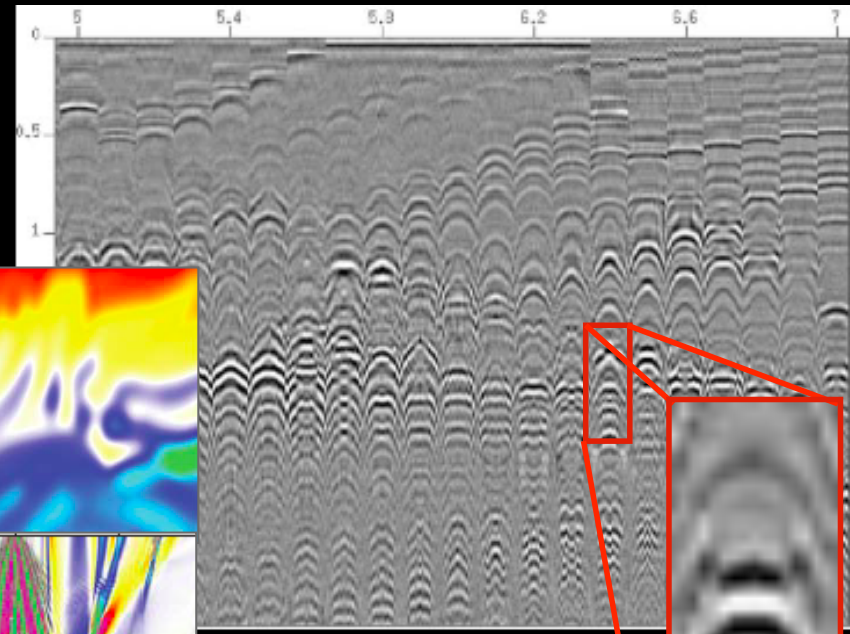
Separation of the direct and multiple fields: interferometry/cross-correlation



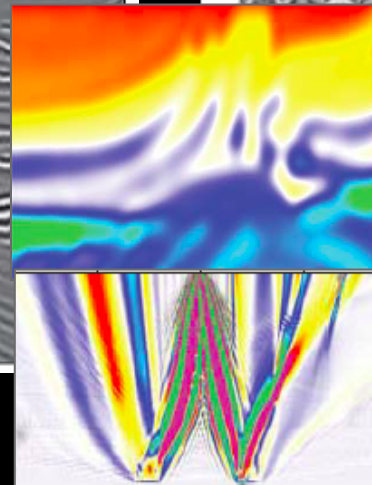
Wave equation reflection tomography



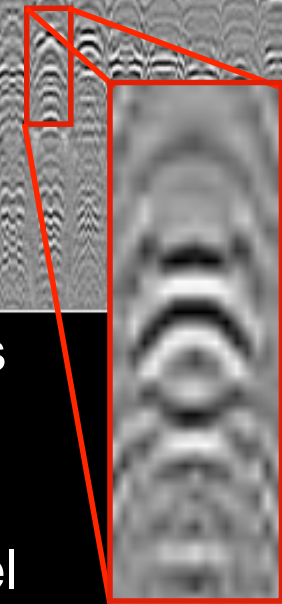
Stacked image



Angle gathers

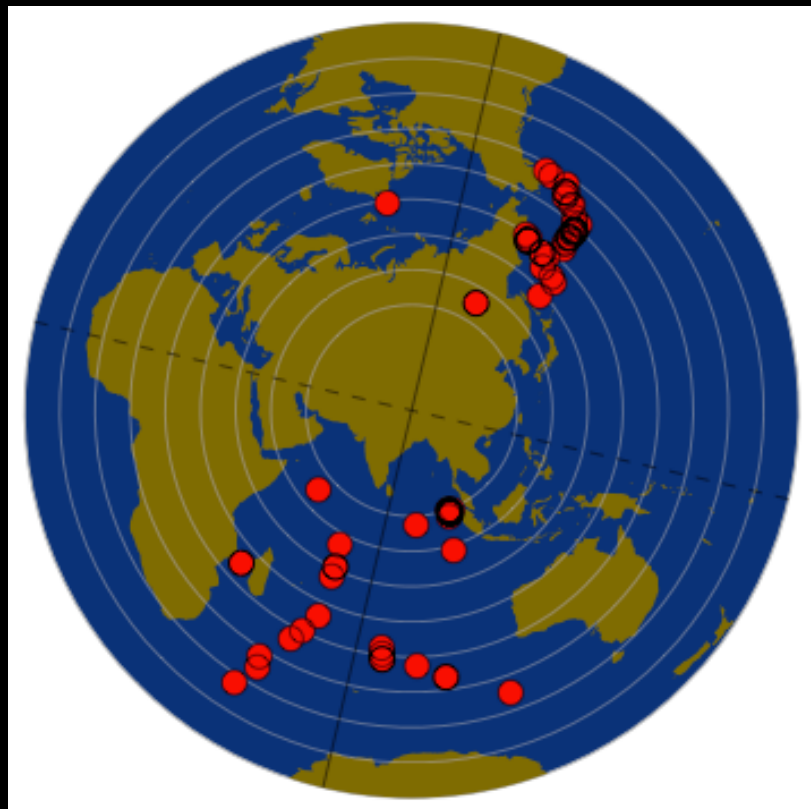


De Hoop et al. (GJI, 2006)



- Use structural image to constrain smooth 3D velocity model
- Determine model error via data redundancy - e.g. angle gathers should be flat → **angle domain annihilators** (based on normal moveout)

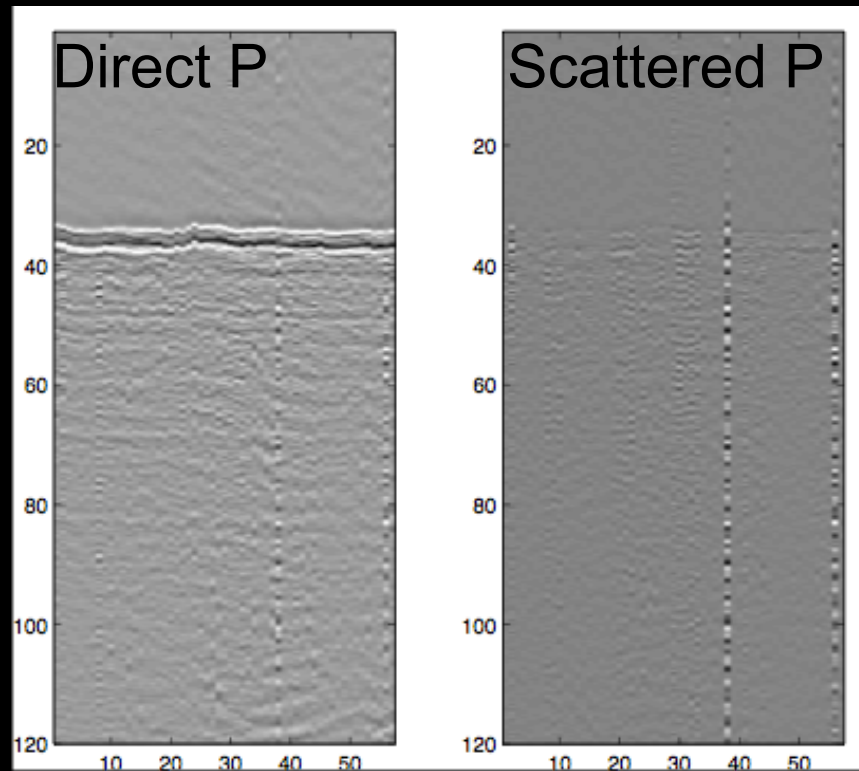
Challenges of teleseismic data



Events magnitude > 5.0
 $< 30^\circ$ from great circle arc

- 1) Limited global seismicity & irregular array configurations \rightarrow limited angular and azimuthal data \rightarrow Angle domain annihilation not effective

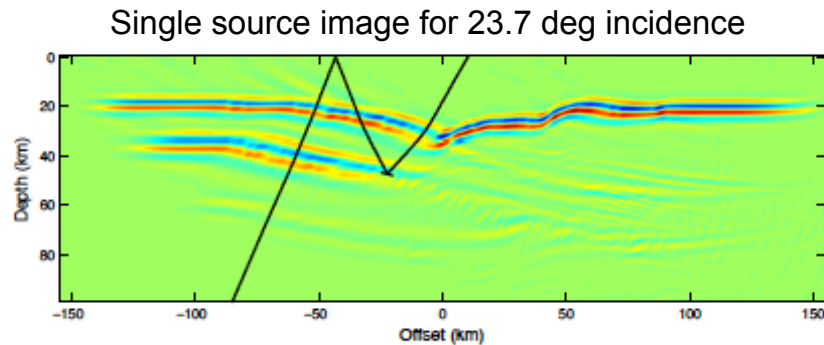
Challenges of teleseismic data



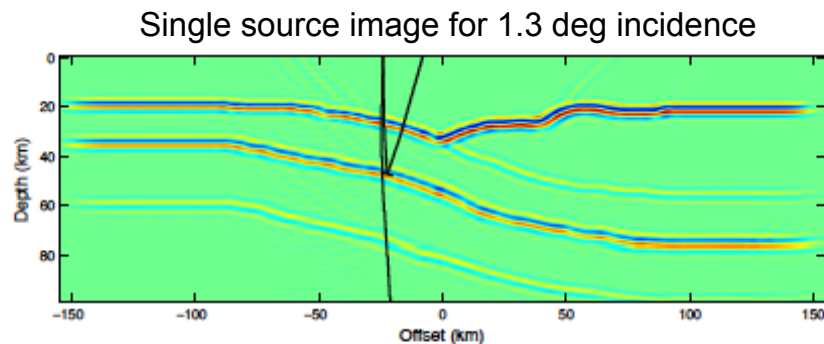
- 1) Limited global seismicity & irregular array configurations → limited angular and azimuthal data
- 2) Unknown source functions, varying frequency content, long source-time signatures → imperfect deconvolution

Direct and scattered fields separated by MCCC, singular value decomposition

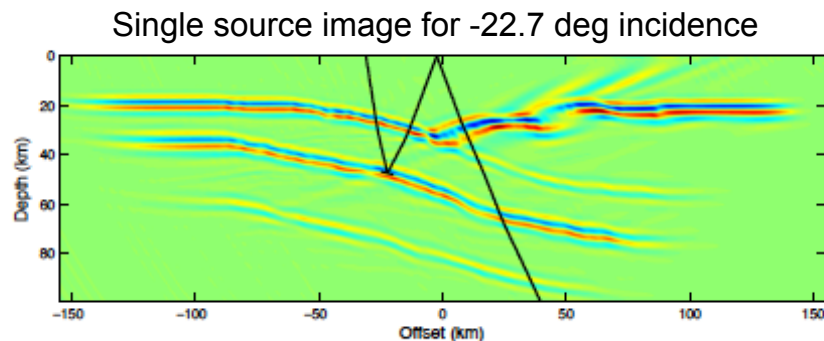
Single source images formed using inverse scattering for teleseismic sources arriving from different directions



(a)



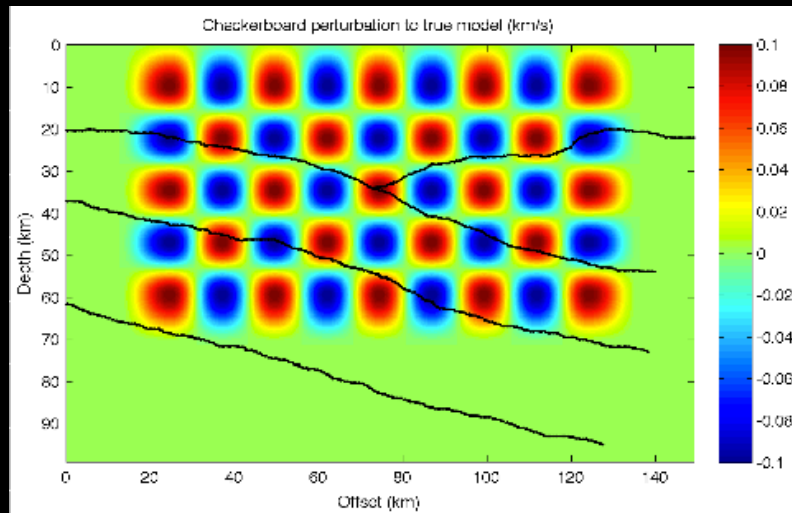
(b)



- Power norm error function
- Misfit criterion based on **correlation of images** formed from different sources → **maximum correlation gives best optimal velocity model**
- More robust than error function based on depth move-out (angle domain annihilation)

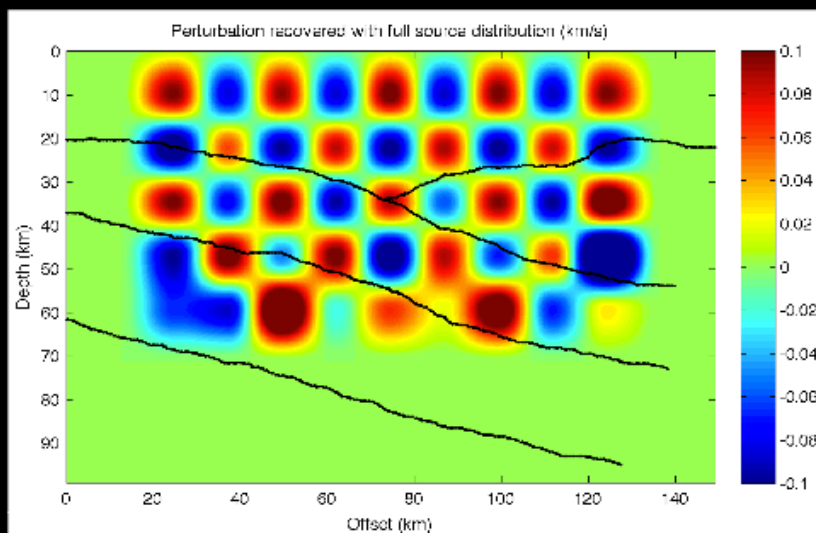
Checkerboard inversion test

True perturbation to model (km/s)

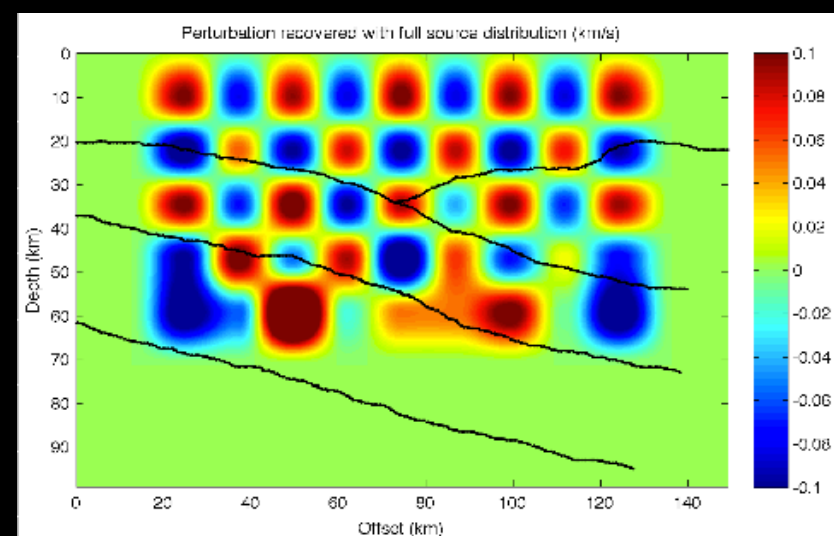


- Simple checkerboard basis projected onto 2D subduction model
- Perturbation recovered via least squares inversion

Inversion w/ all events (km/s)

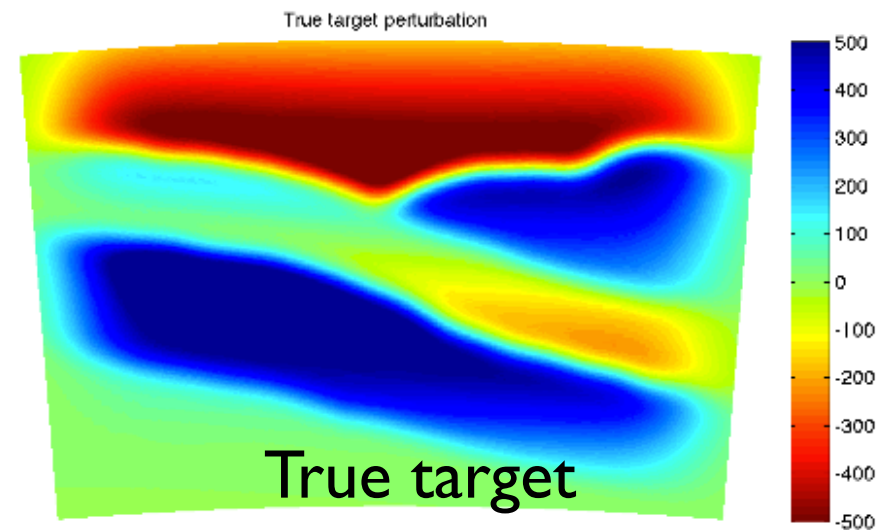
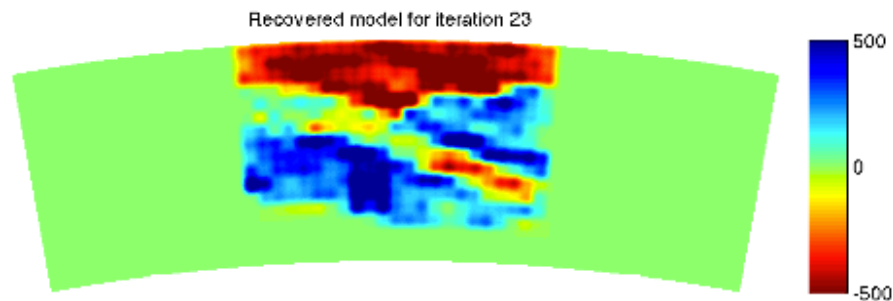
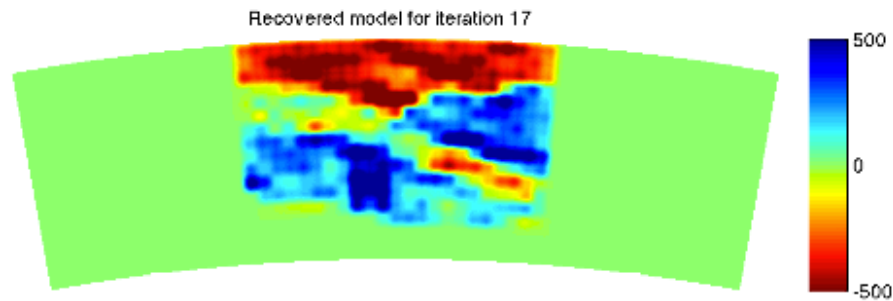
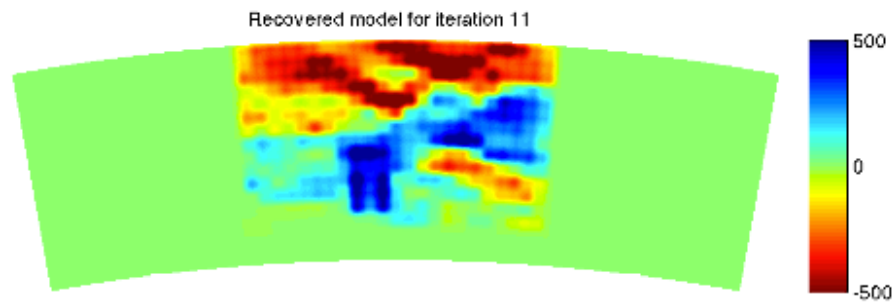
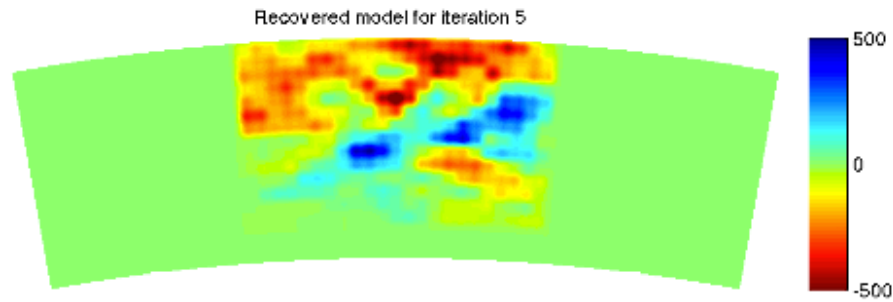


Inversion w/ realistic subset (15-30°)

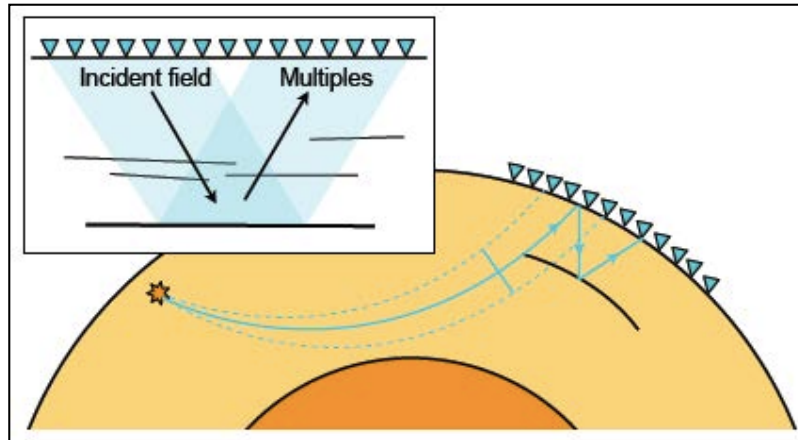


Preliminary results

Inversion with fine basis,
spherical coordinates

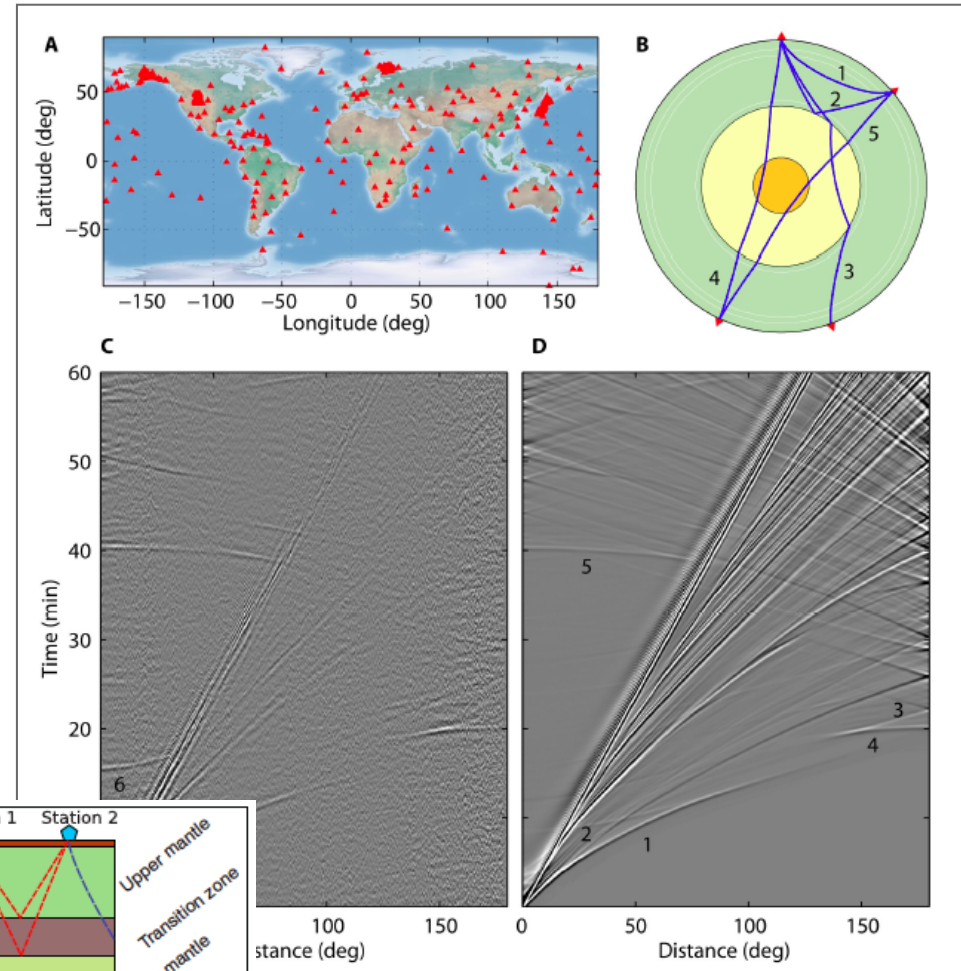


Cargese 2015 (or 2017)?

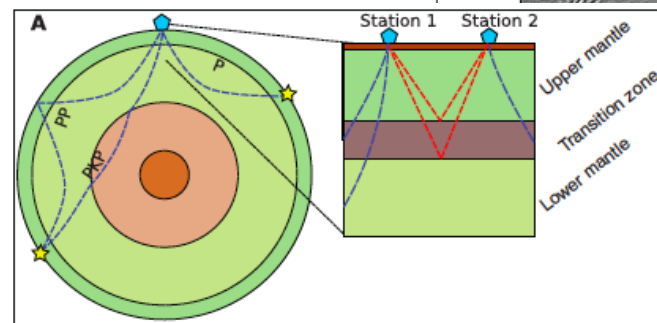


Burdick et al (GJI, submitted)

+



Poli et al (Science, 2012)



Boué et al (GJI, submitted)

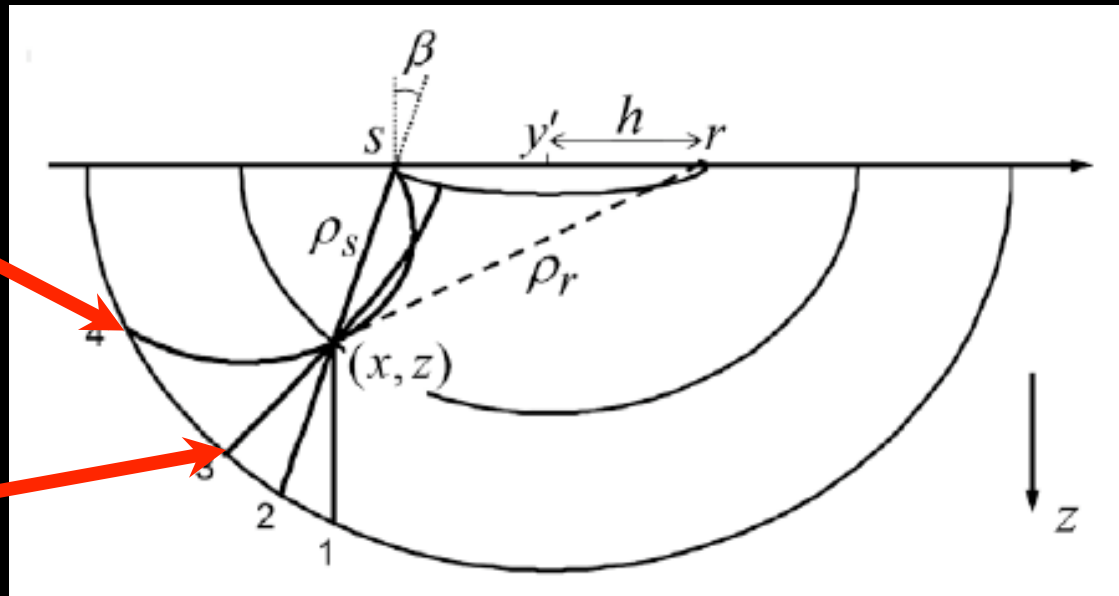
Thank you



Image point moveout? In what direction?

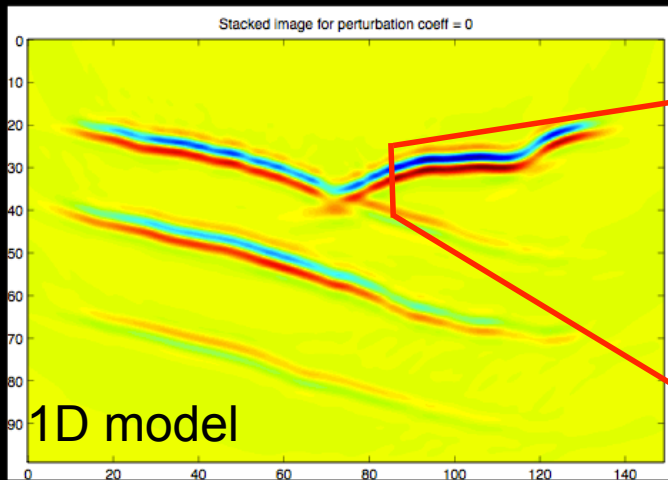
Image
continuation
direction

Reflector
normal

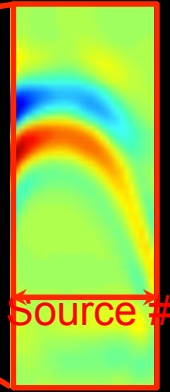


Duchkov et al. 2008

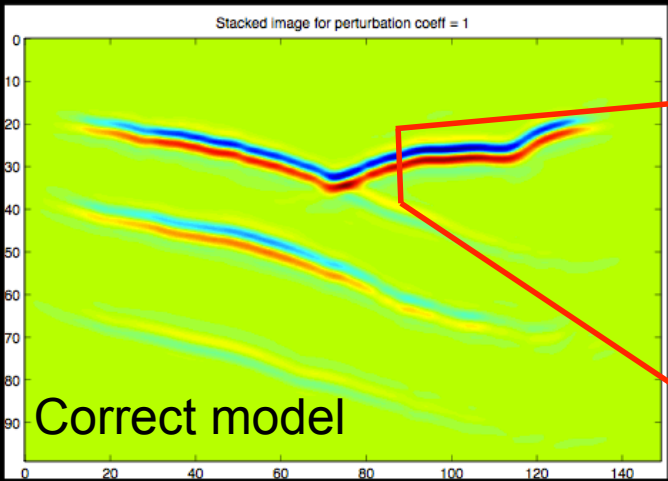
- Image continuation under velocity change is non-linear and not generally normal to reflector
- Solution to continuation ray system needed
- Instead: pure finite frequency measure



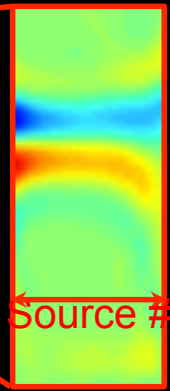
Too fast



Residual moveout in source-index image gathers

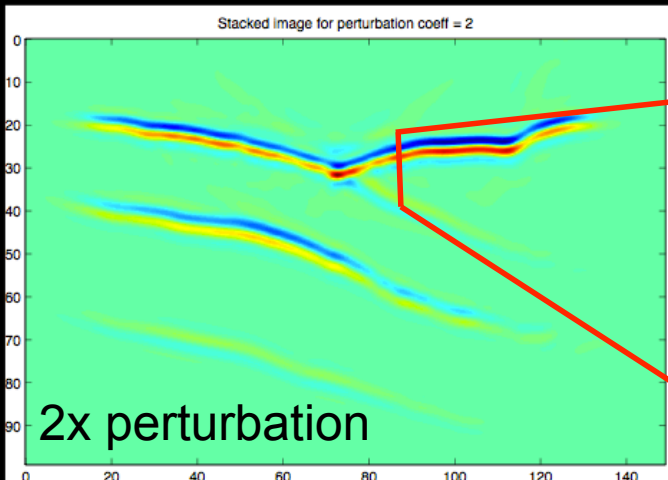


Just right

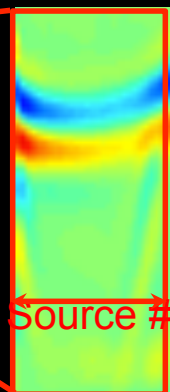


Incorrect model creates measurable moveout in single-source images

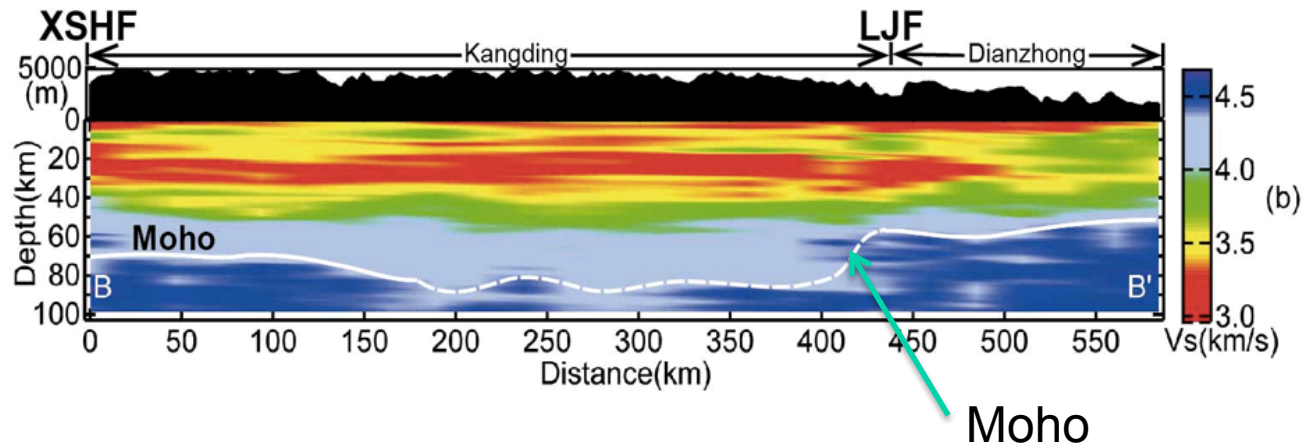
Best way to quantify error? → misfit criterion



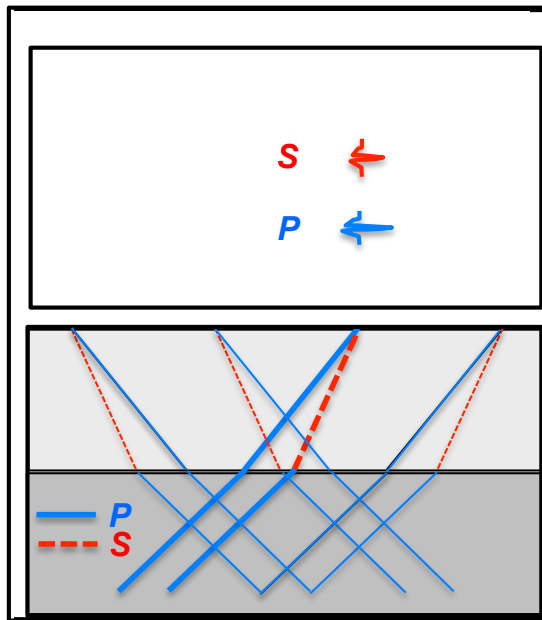
Too slow



Burdick et al. (GJI, submitted)



Moho
(crust-mantle interface; after Mohorovičić, 1857-1936)



Imaging With Converted Waves
(*P-to-S* or *S-to-P*)

Strong Moho topography

Problem: Traditional Receiver Function analysis assumes horizontal interfaces

PhD Research: Xuefeng Shang
(supported by Shell and CMG Program of NSF)
Shang et al. (GRL, 2012)